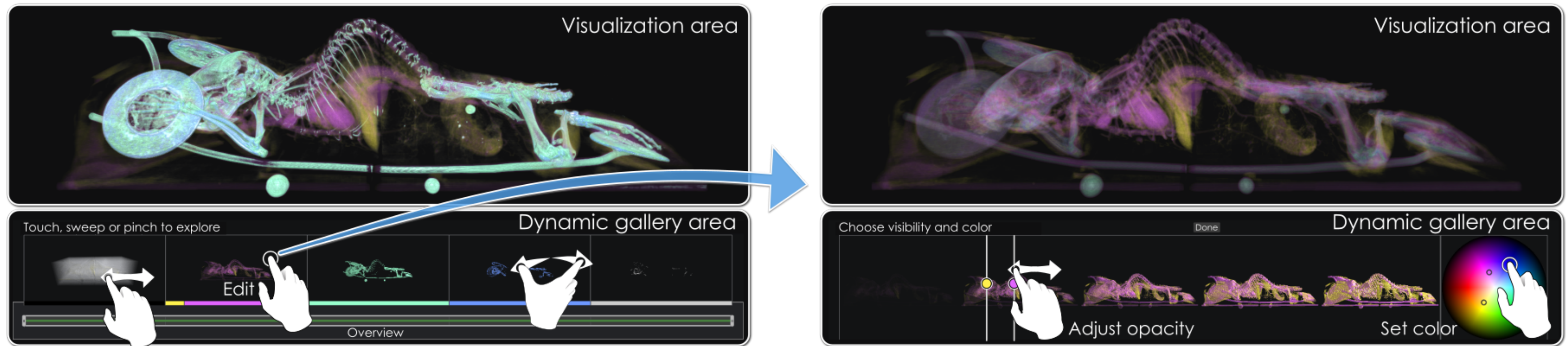


# Hybrid Tactile/Tangible Interaction for 3D Data Exploration

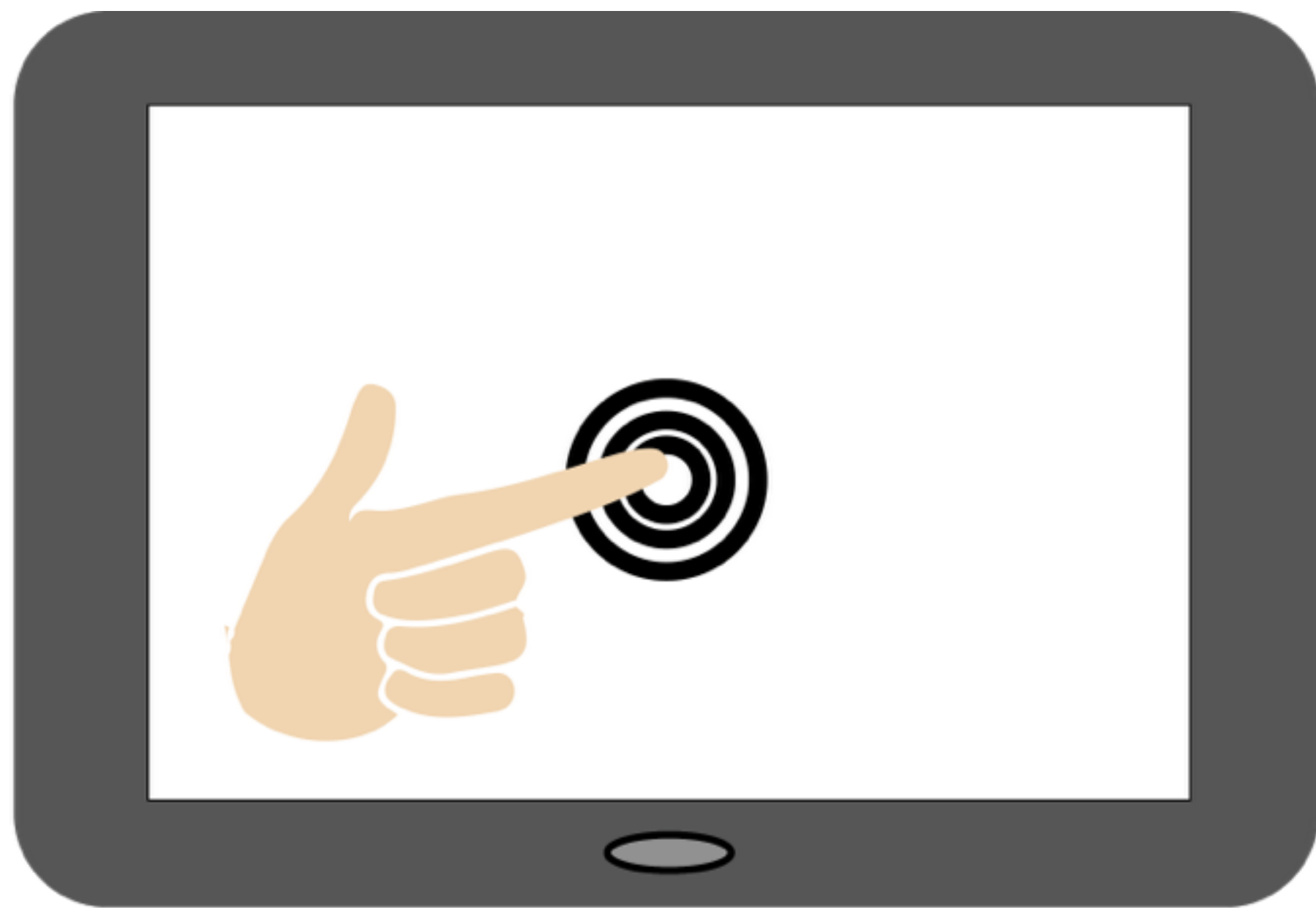
Lonni Besançon, Paul Issartel, Mehdi Ammi, Tobias Isenberg

# Problem

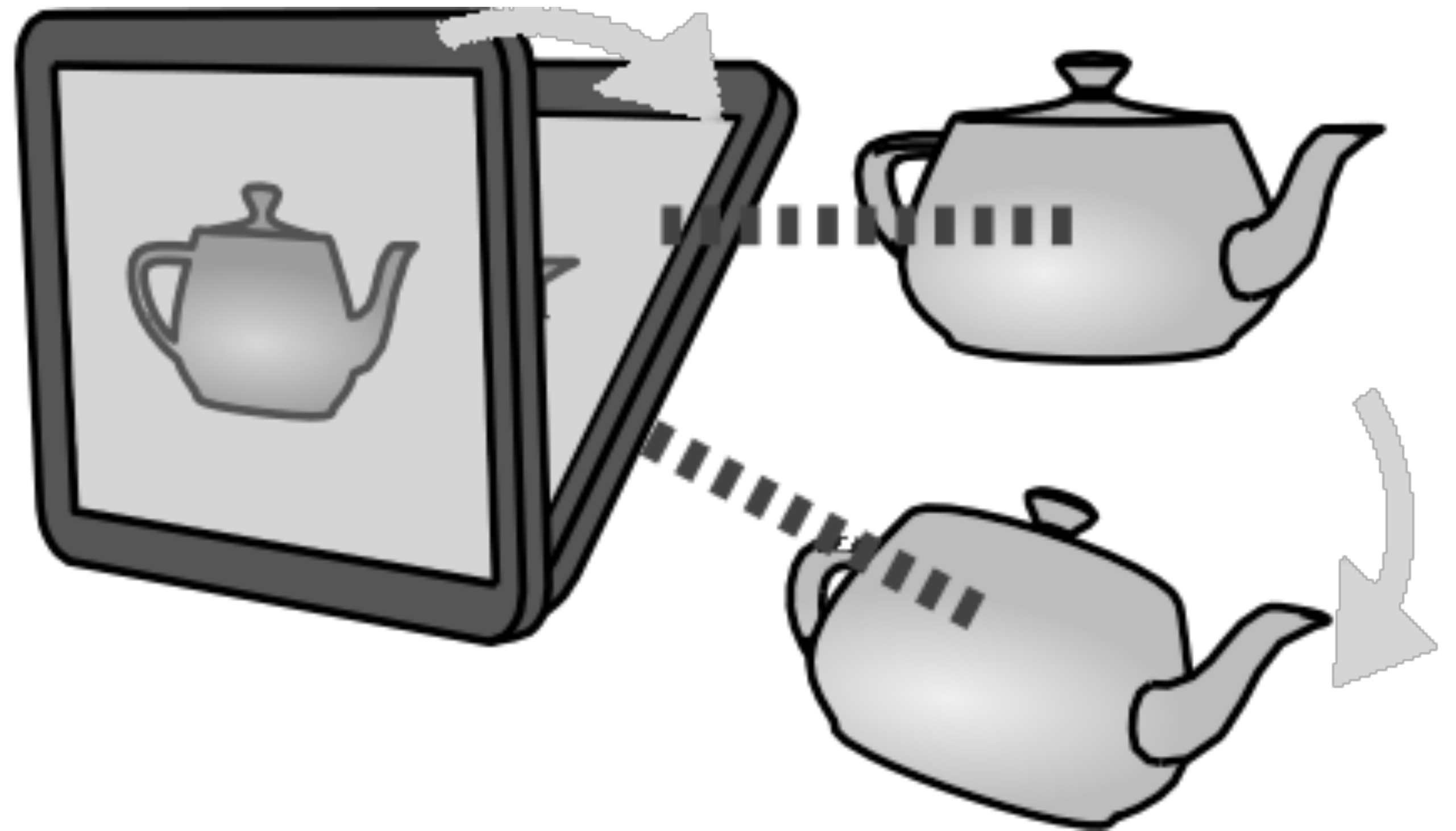
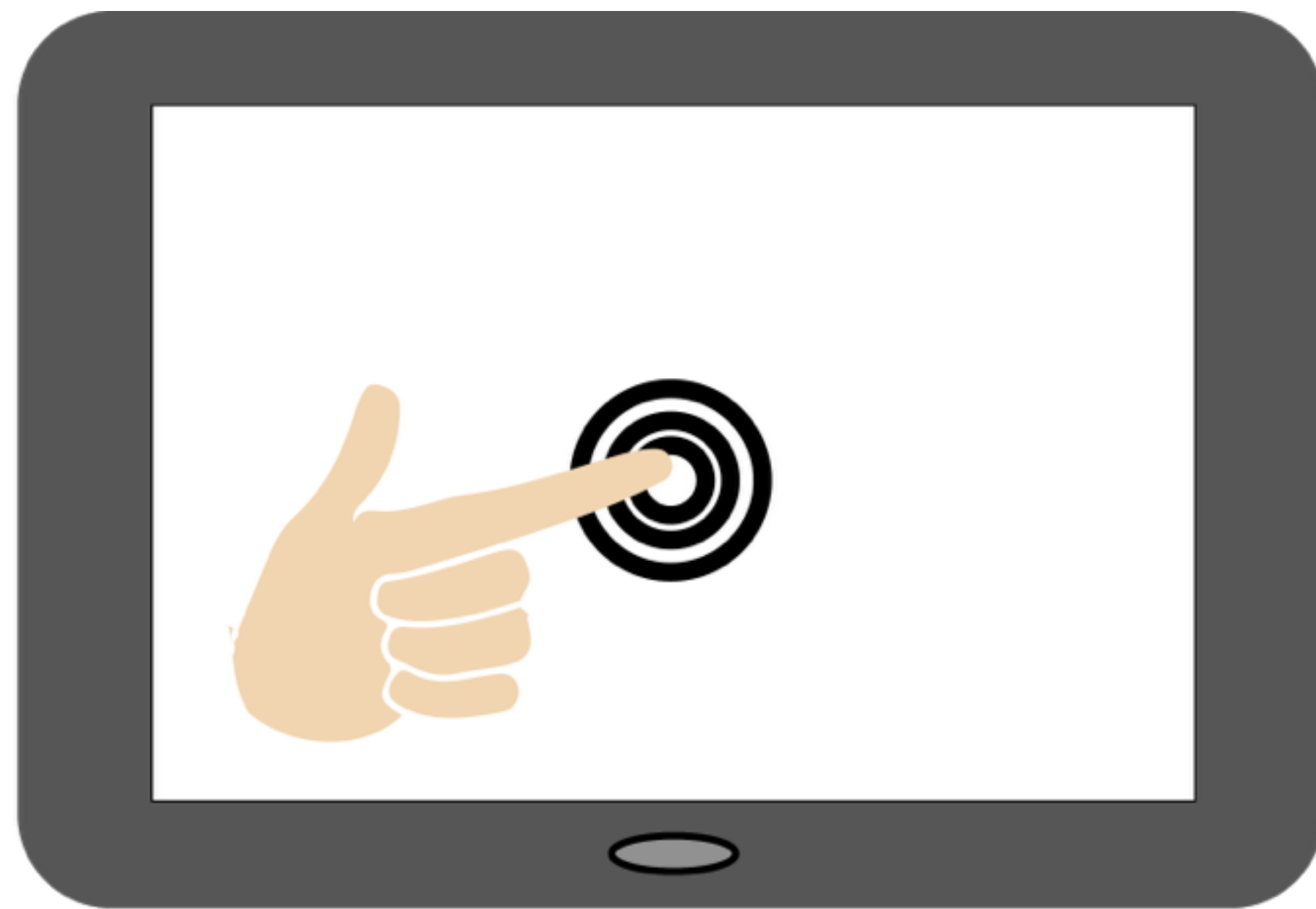


Jönsson et al. (2016)

# Problem



# Problem

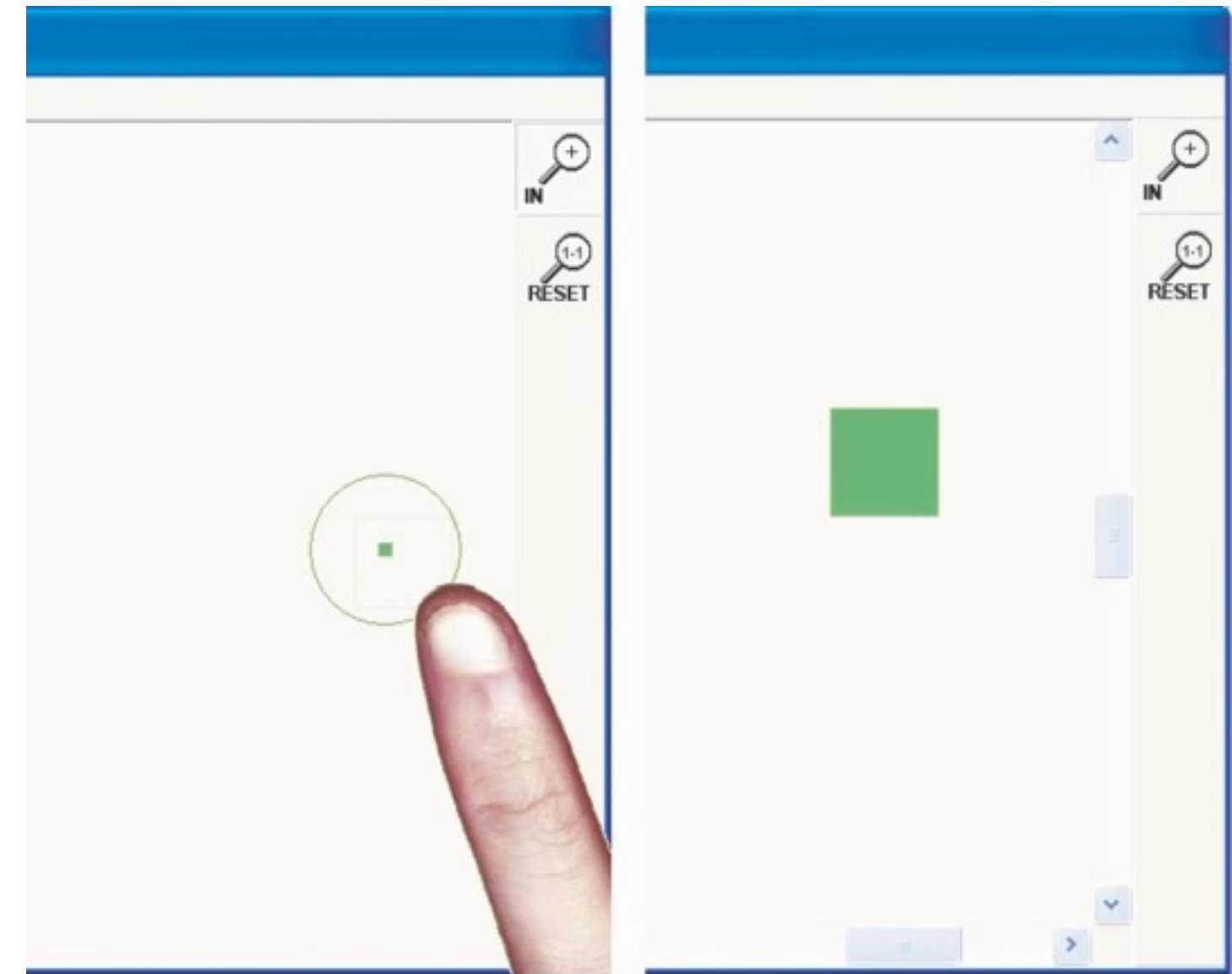




# Tactile interaction



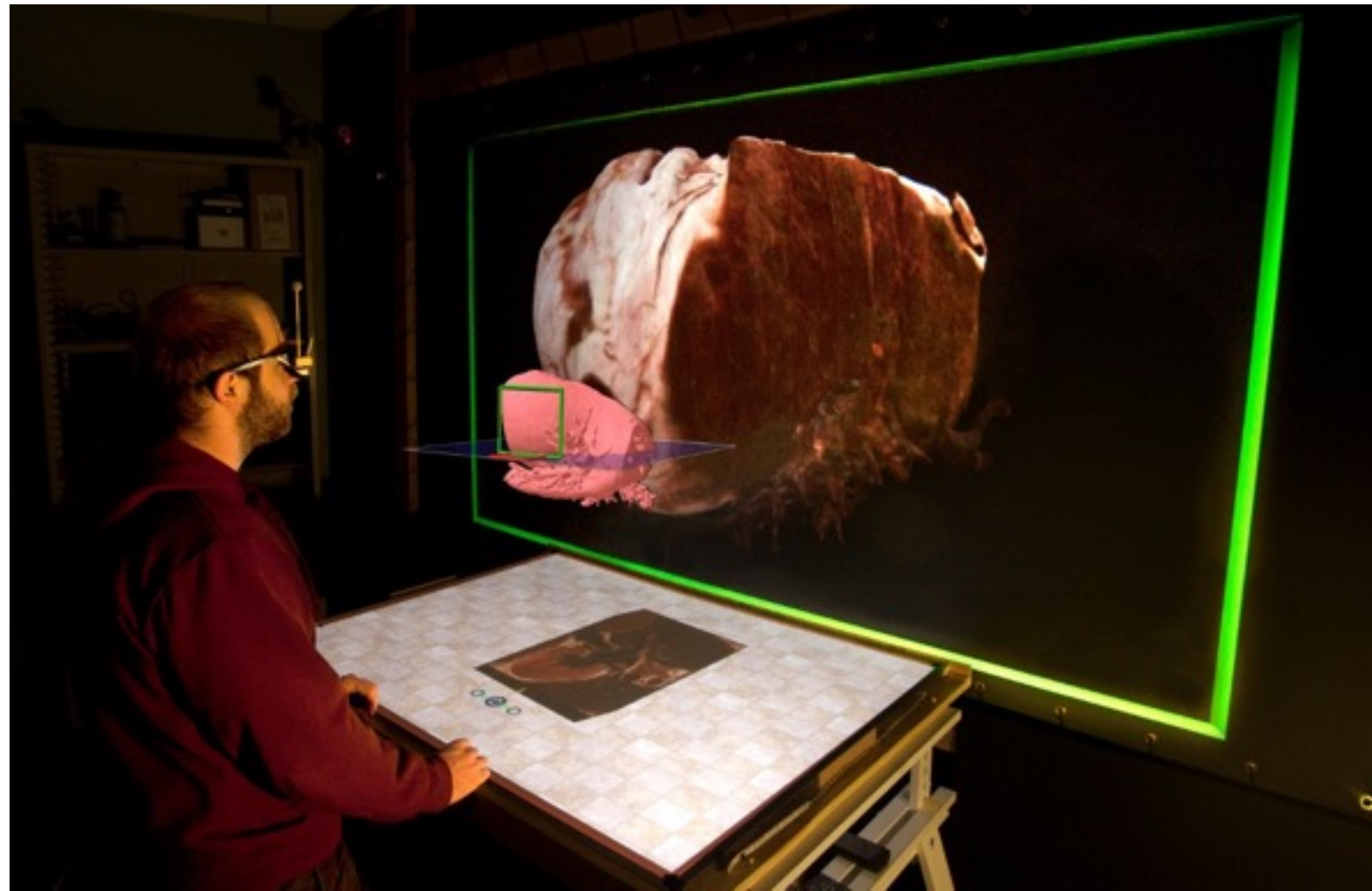
Yu et al. (2010)



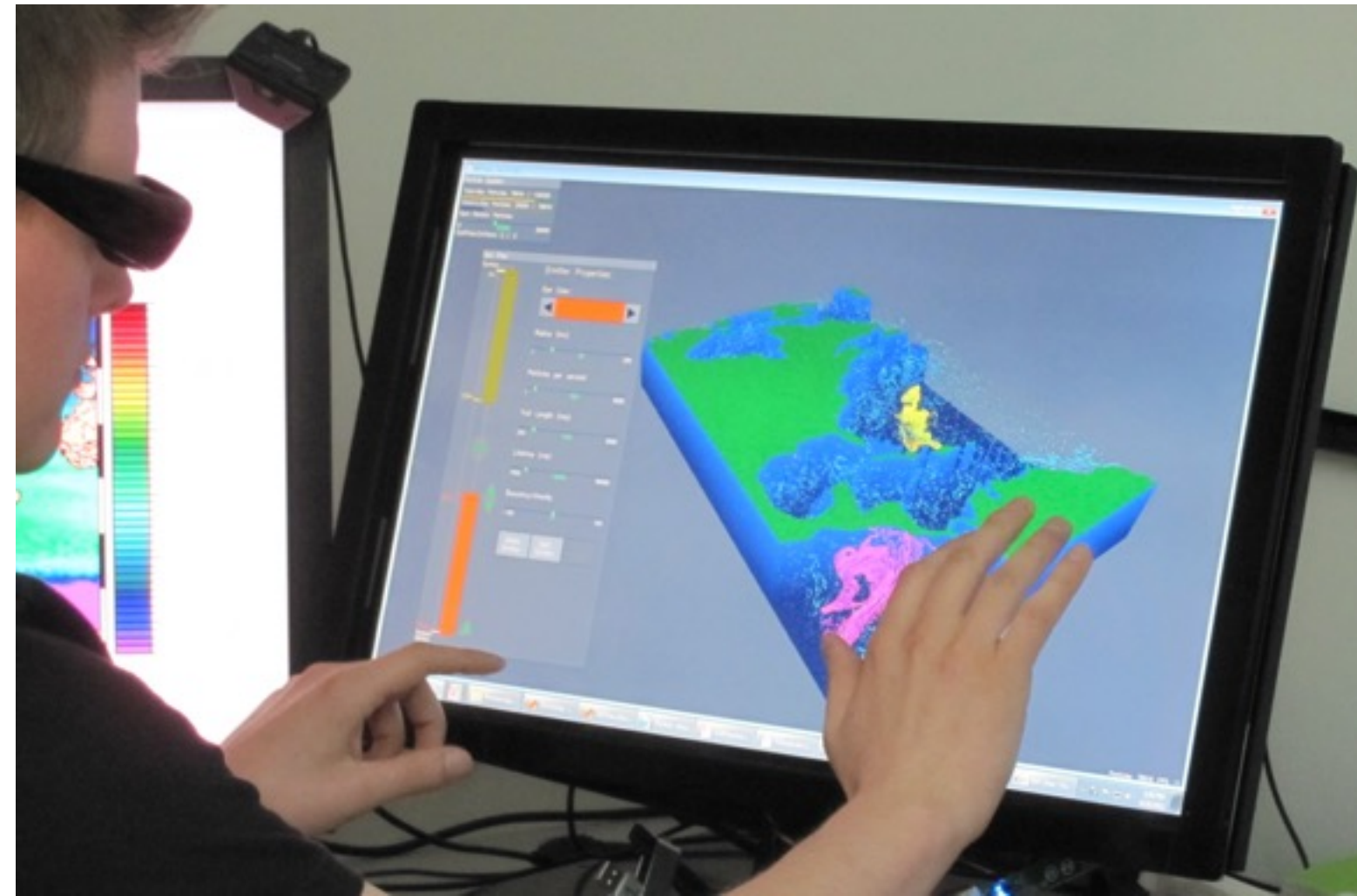
Albinson & Zhai. (2003)



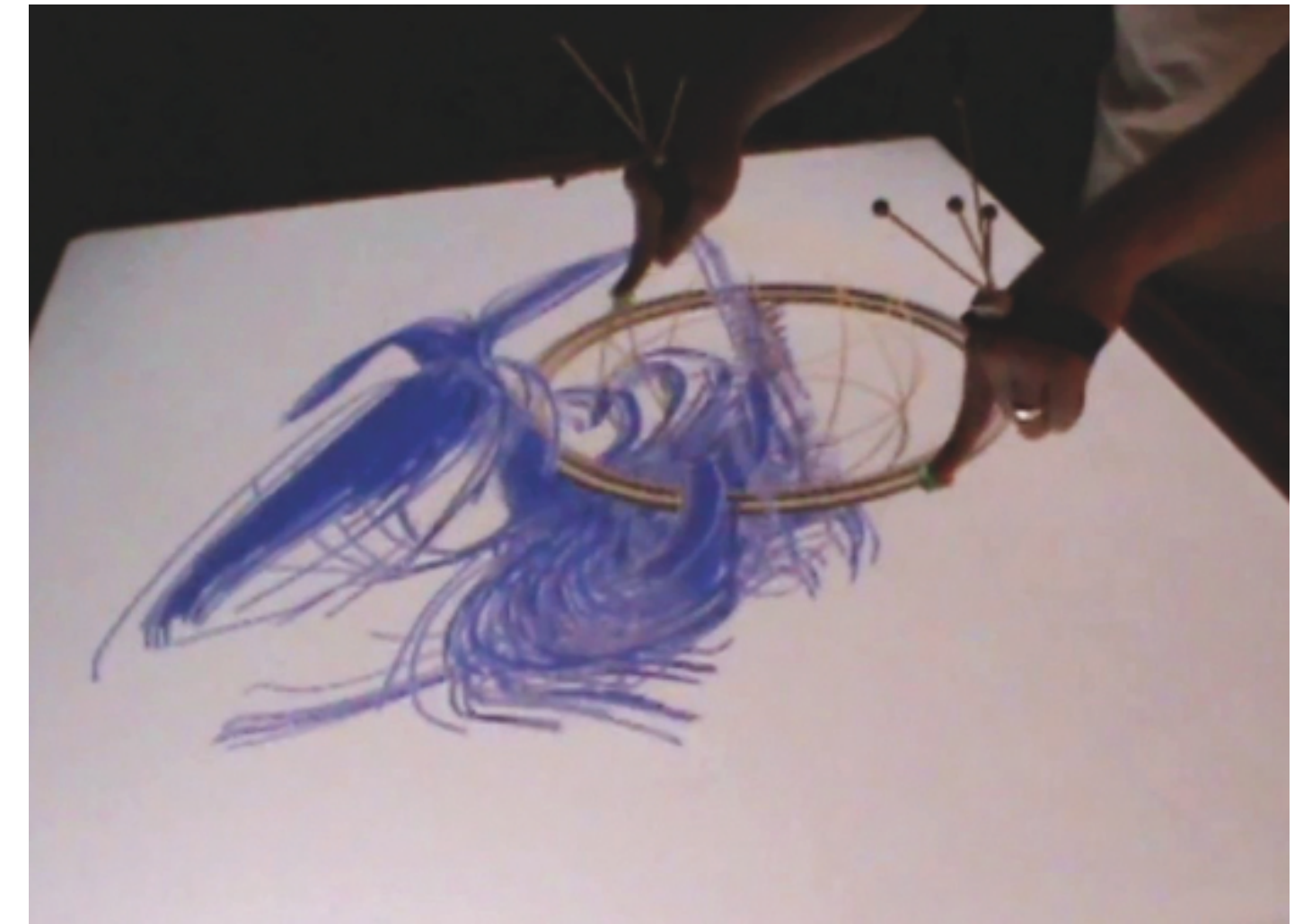
# Tactile interaction



Coffey et al. (2012)



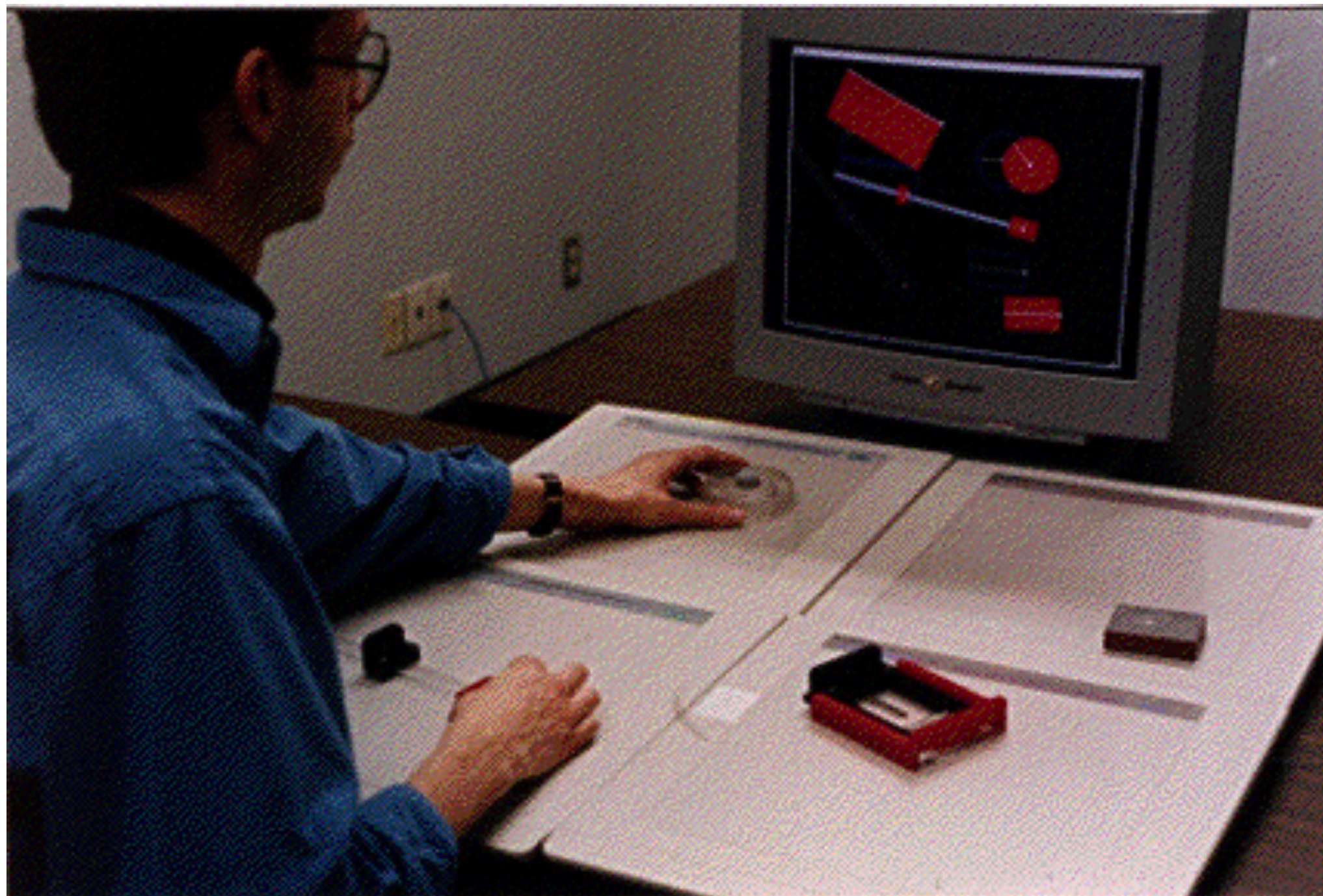
Butkiewicz & Ware (2012)



Jackson et al. (2012)



# Tangible Interaction



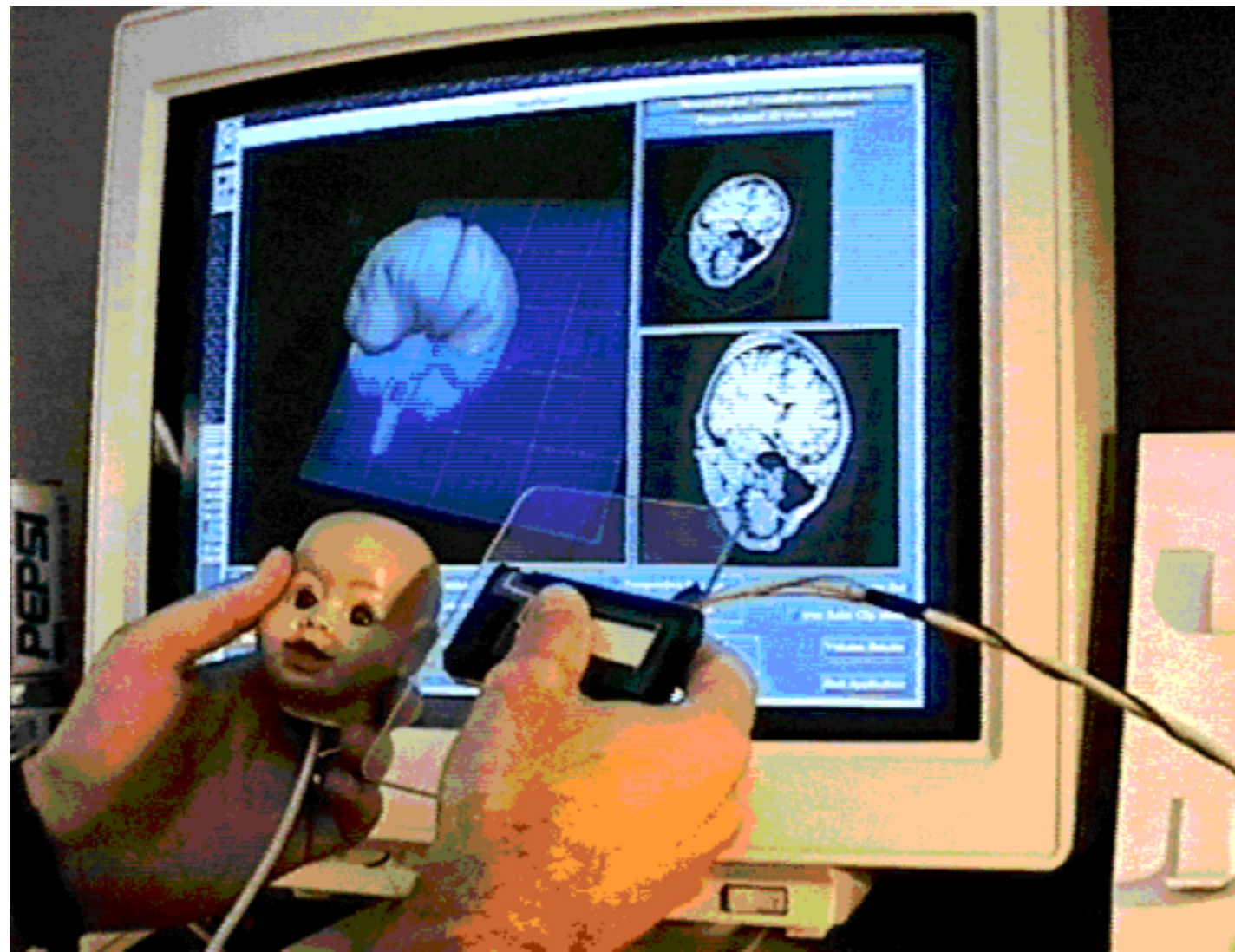
Fitzmaurice & Buxton (1997)



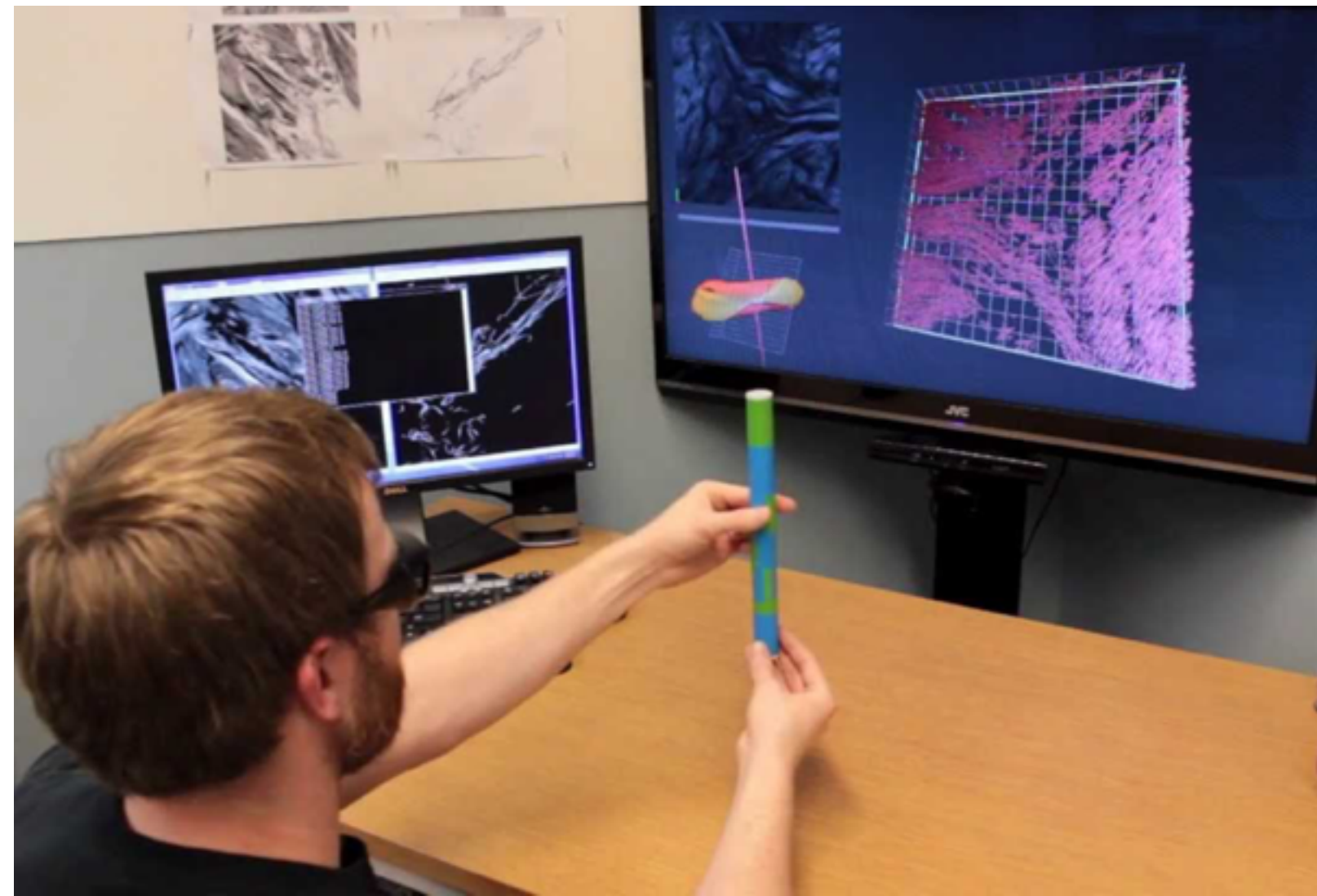
Besançon et al. (2015)



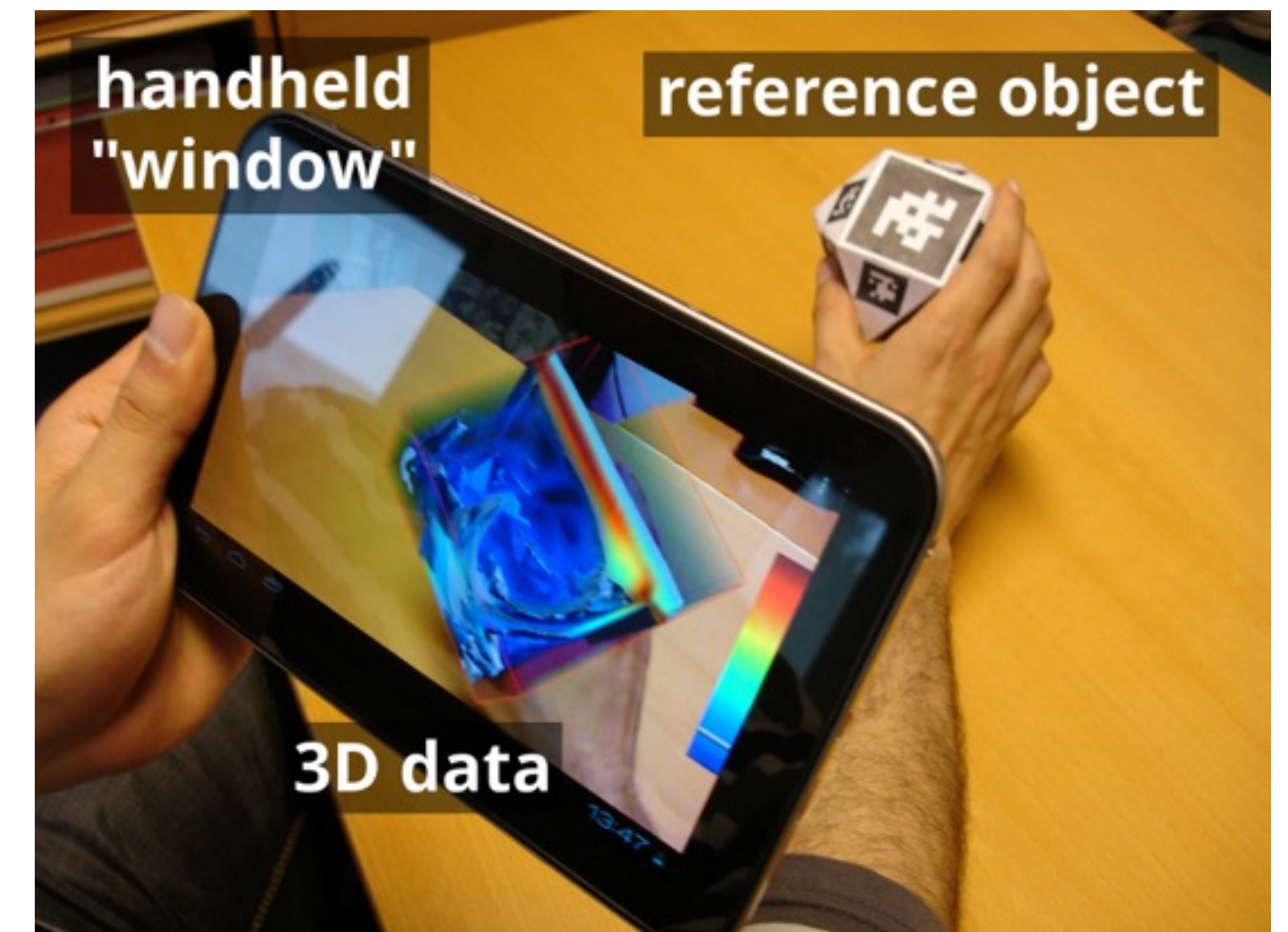
# Tangible Interaction



Hinckley et al. (1994)



Jackson et al. (2013)



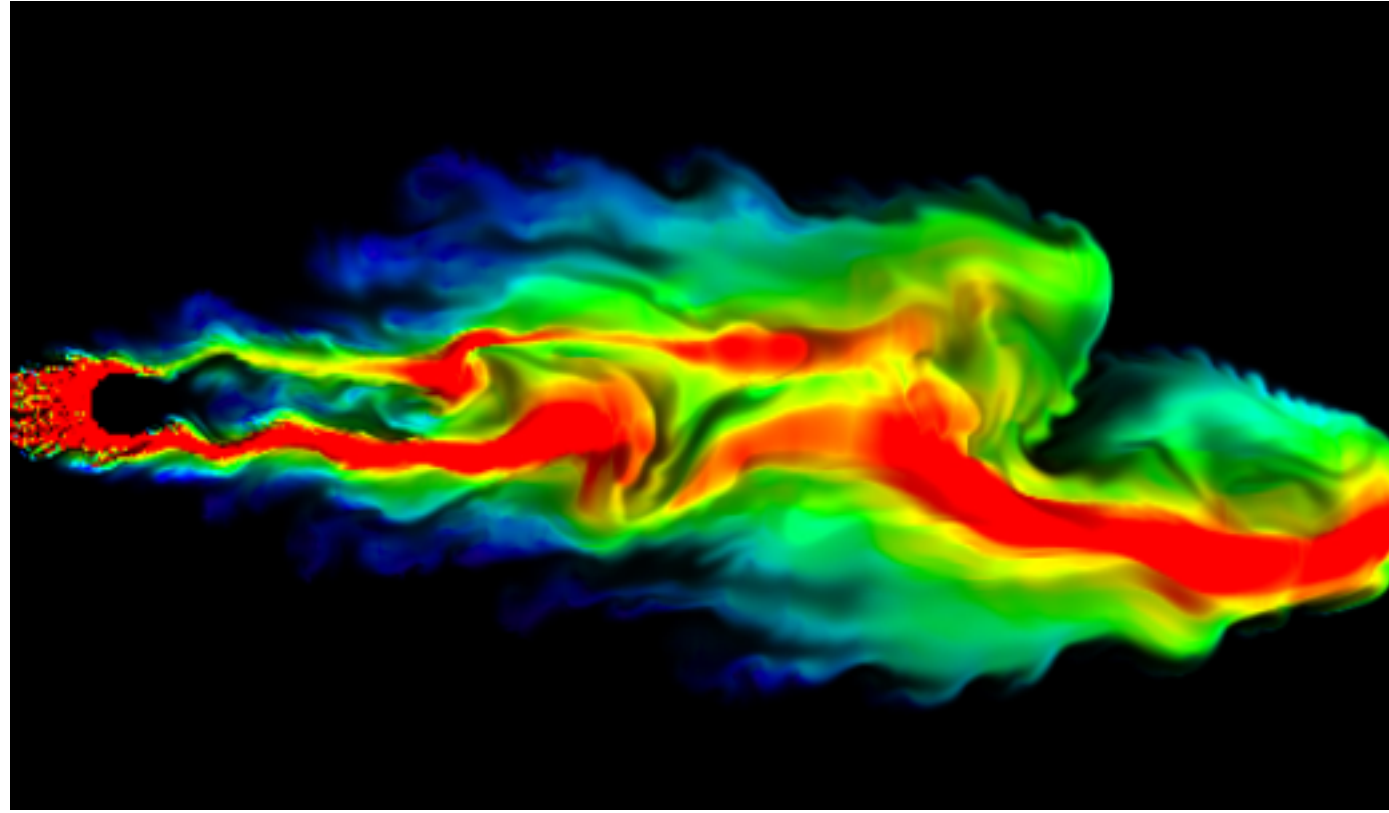
Issartel et al. (2014)



# **Problem**

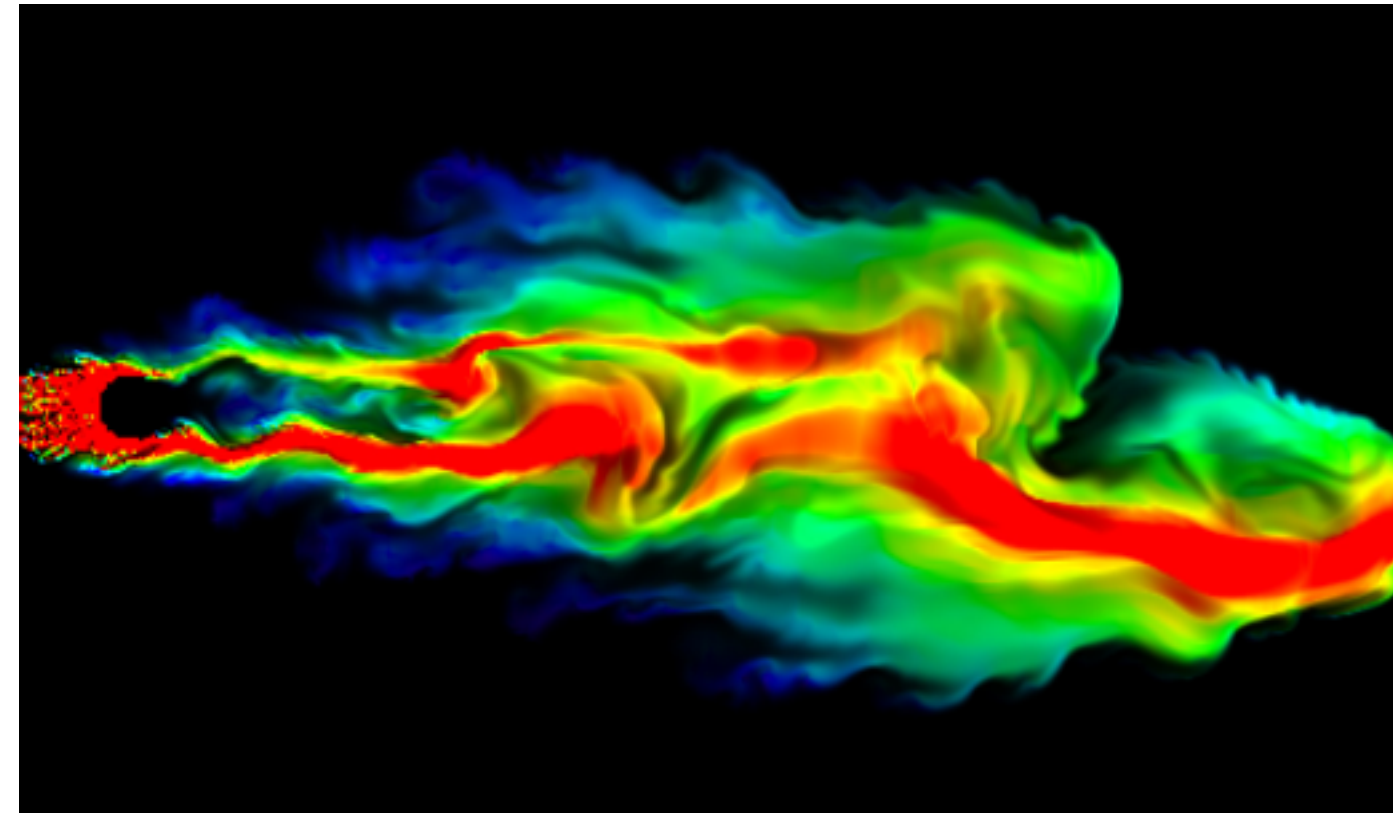
**How can tactile and tangible interaction be combined  
to support 3D data exploration?**

# Contributions

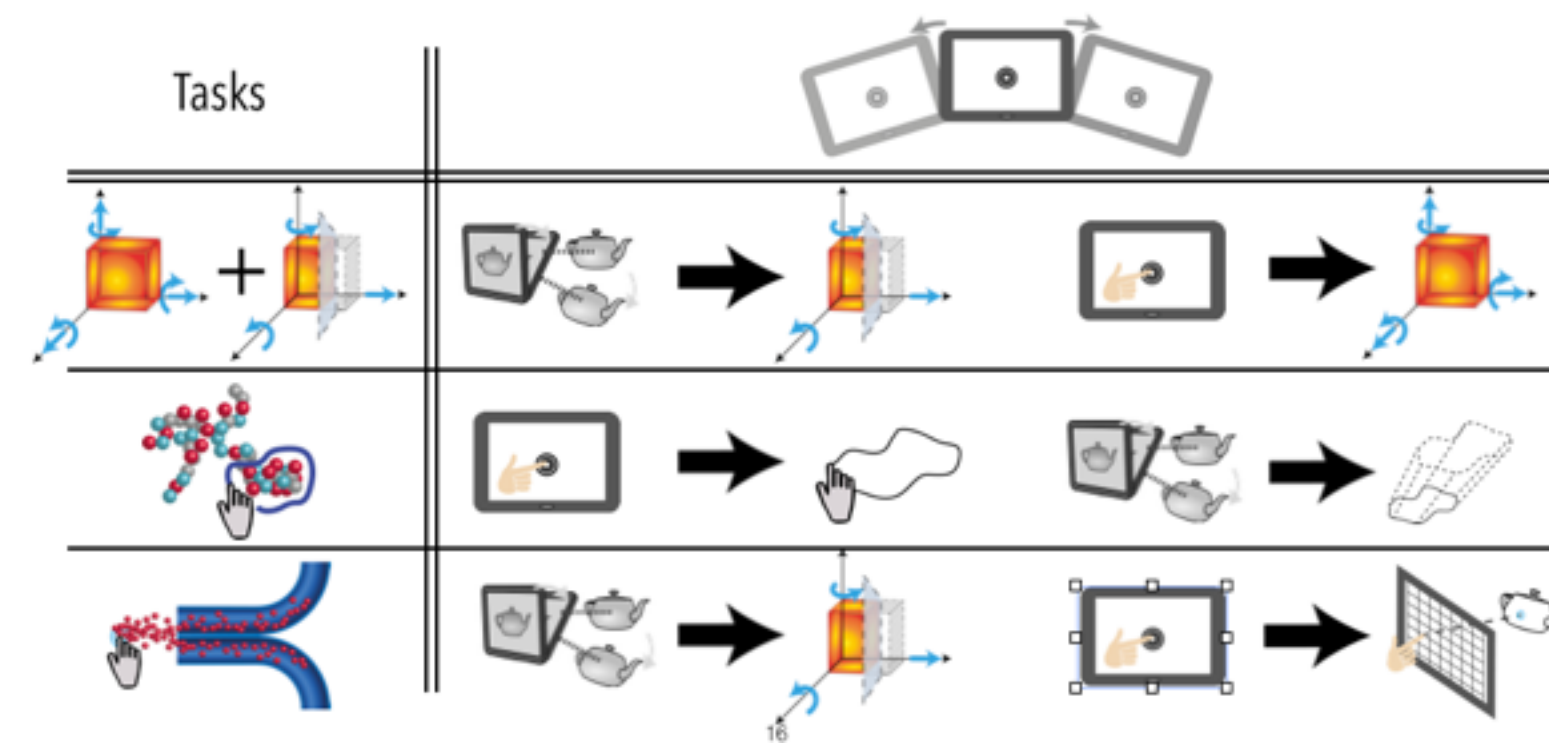
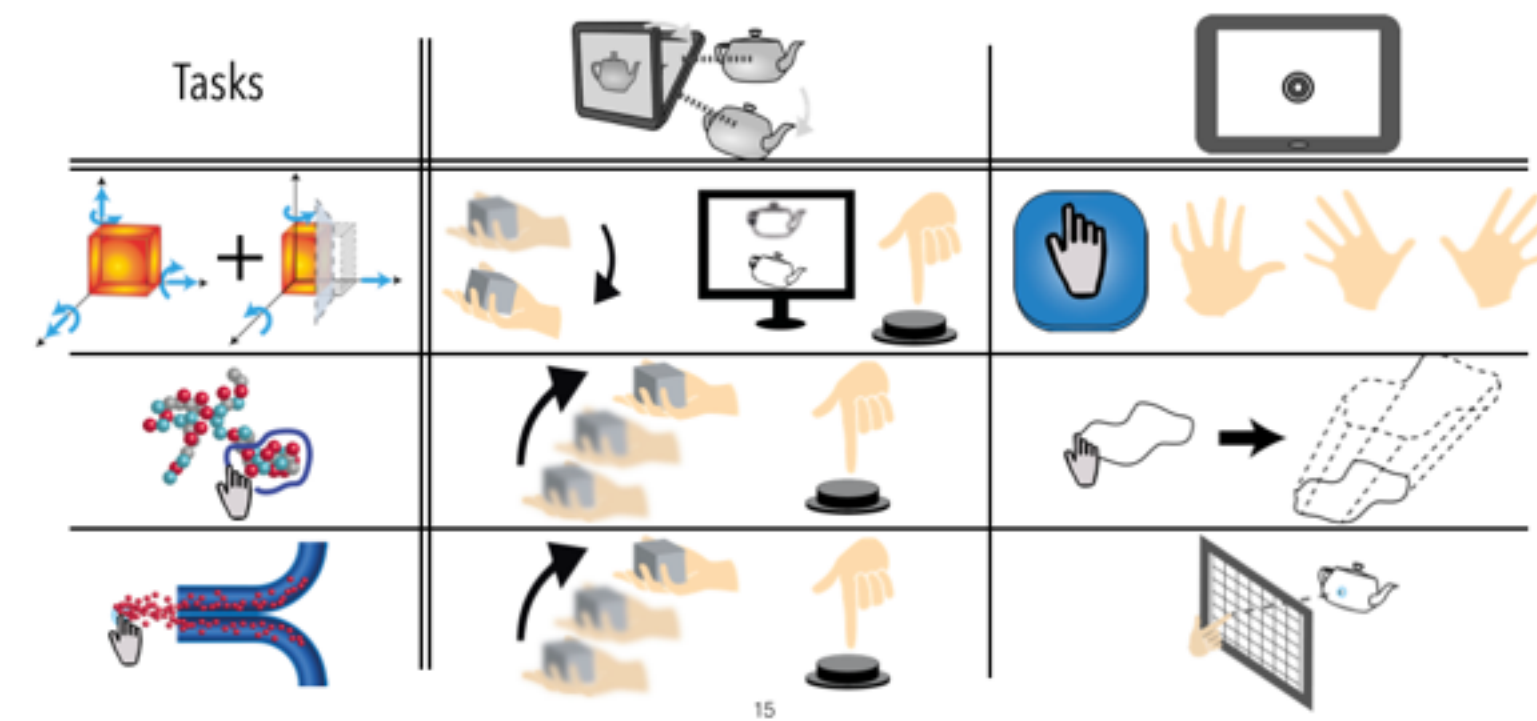


Tsigkari et al. (2012)

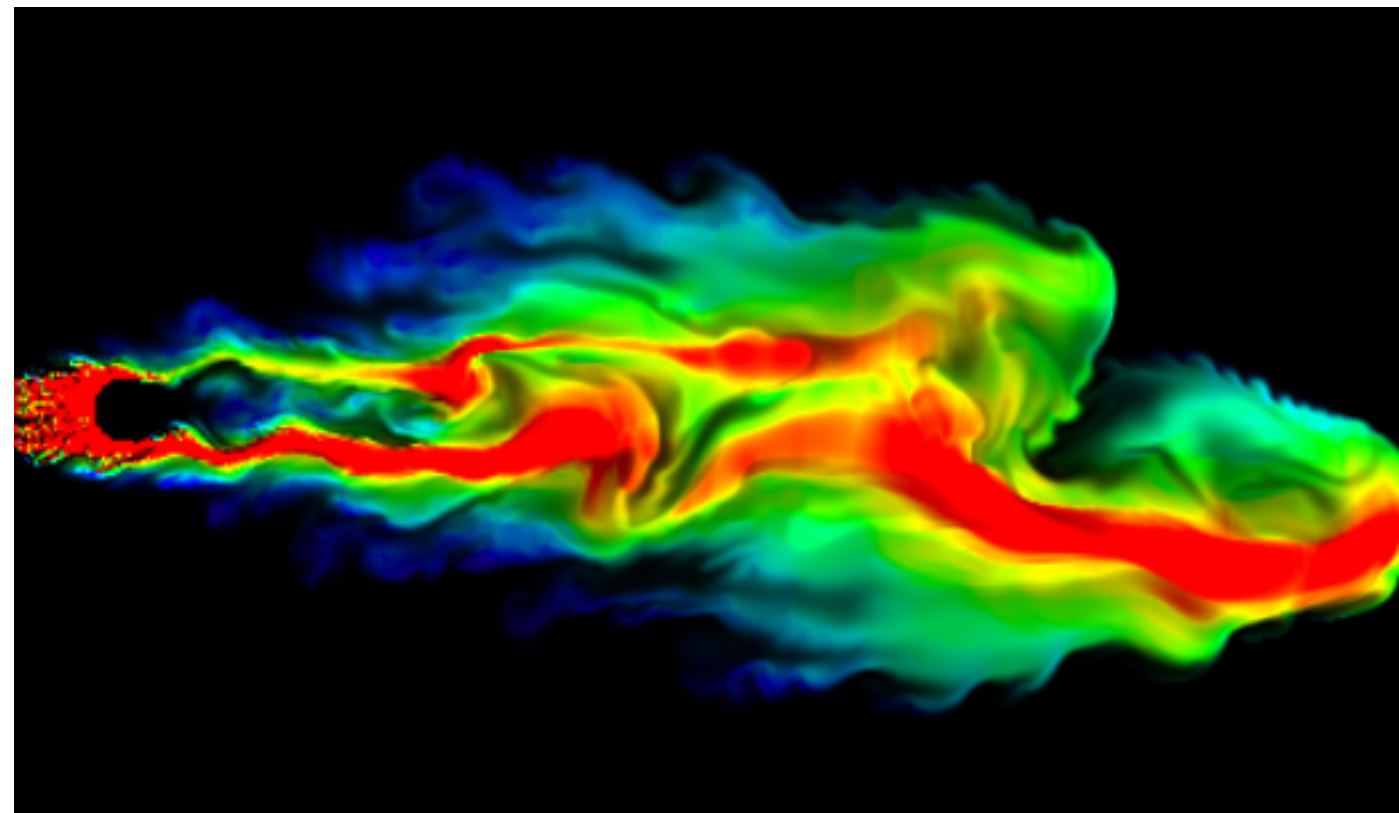
# Contributions



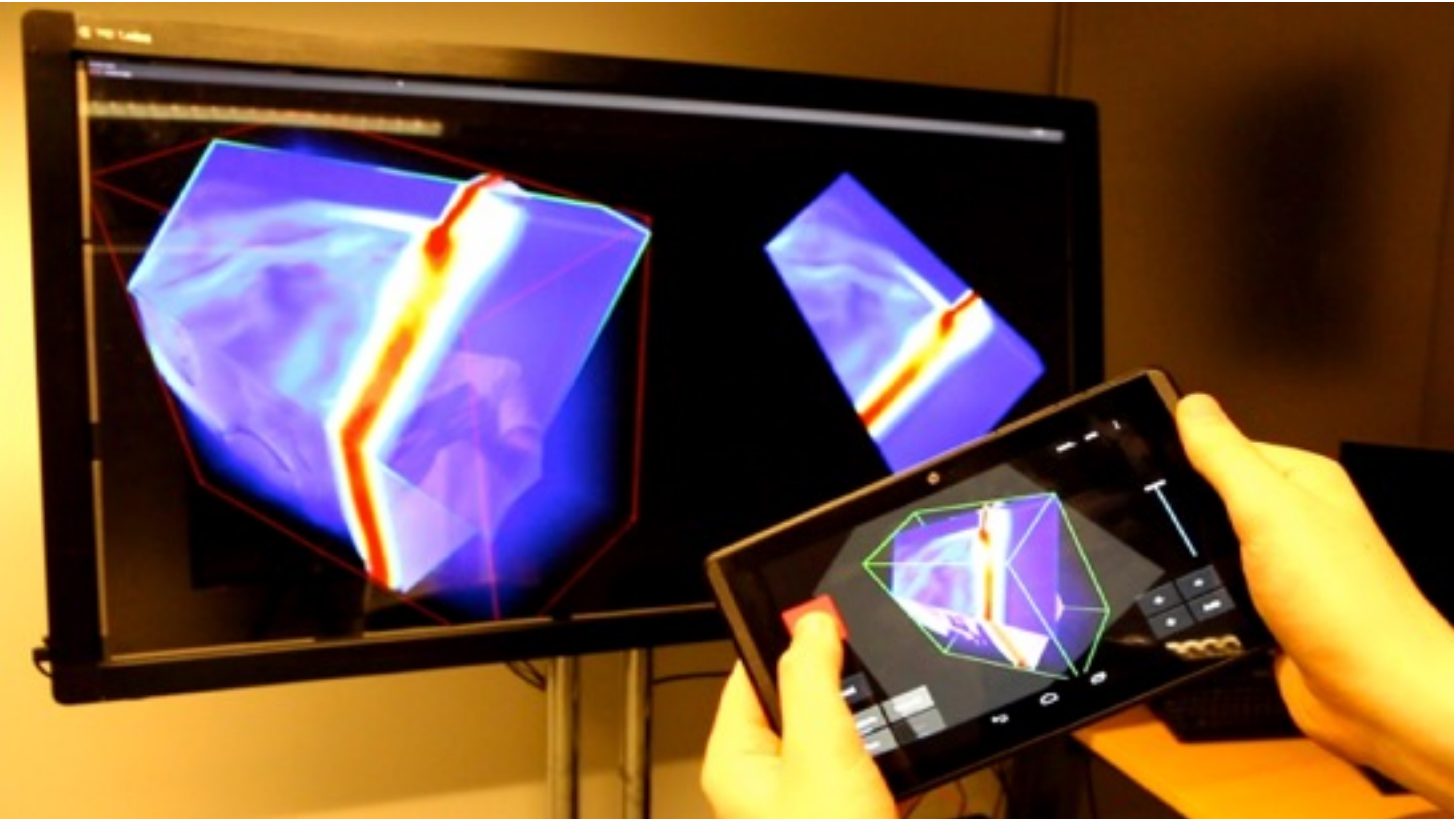
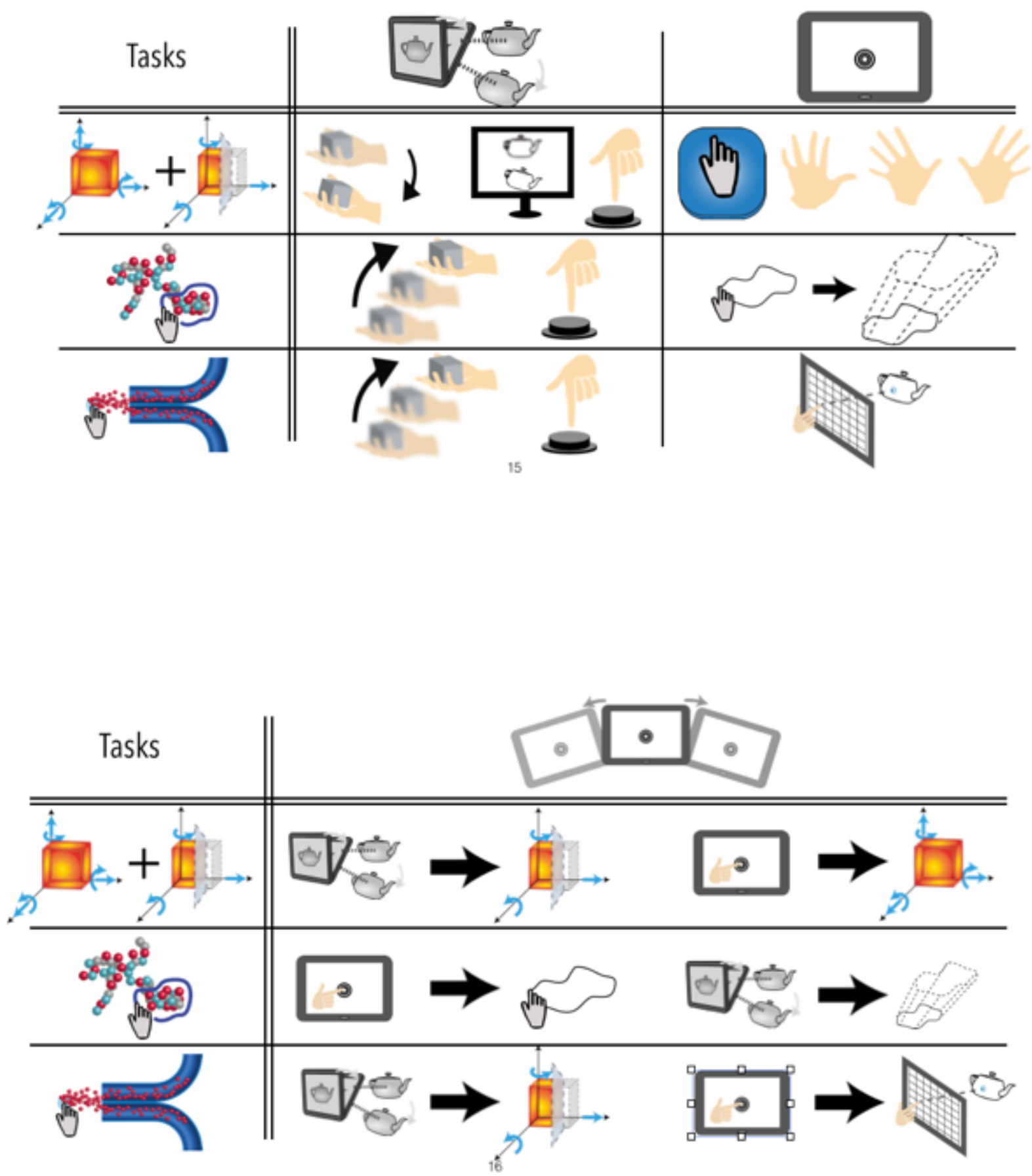
Tsigkari et al. (2012)



# Contributions



Tsigkari et al. (2012)

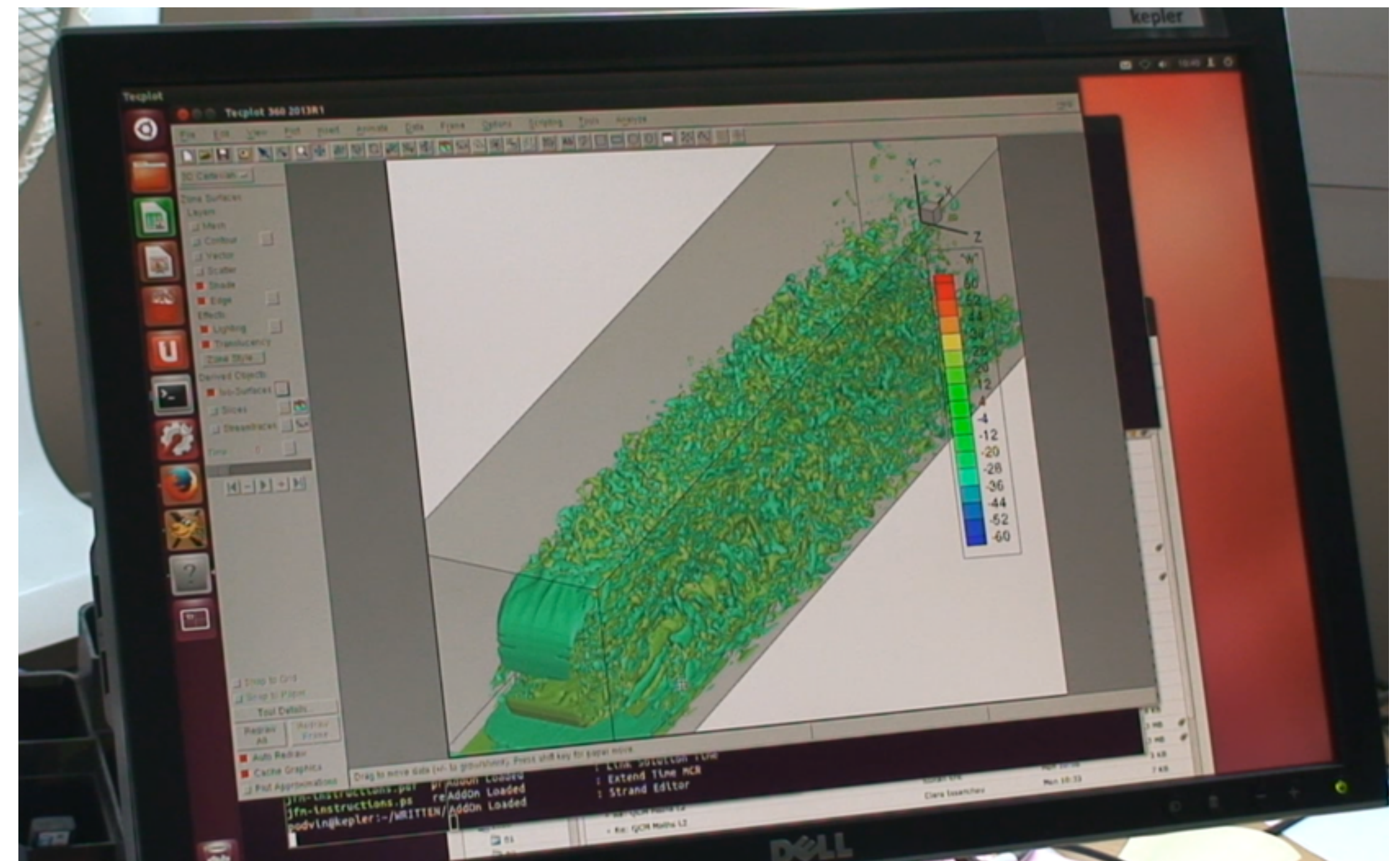




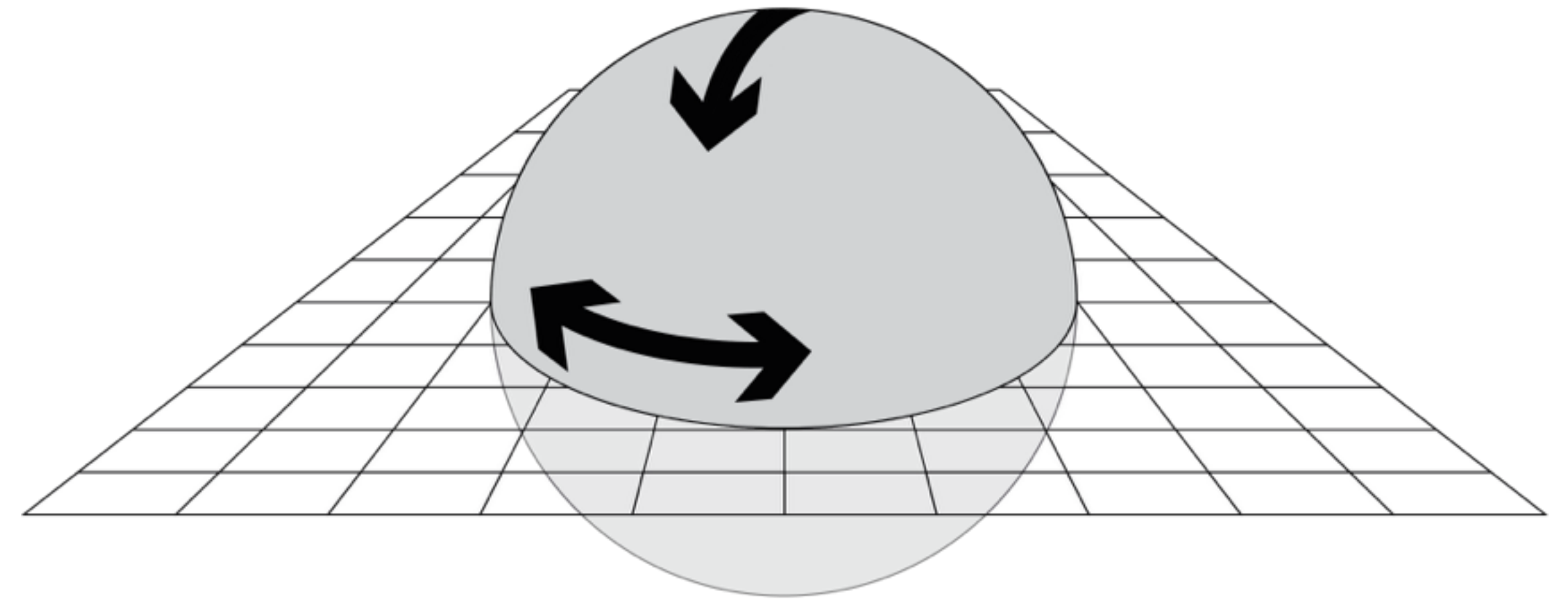
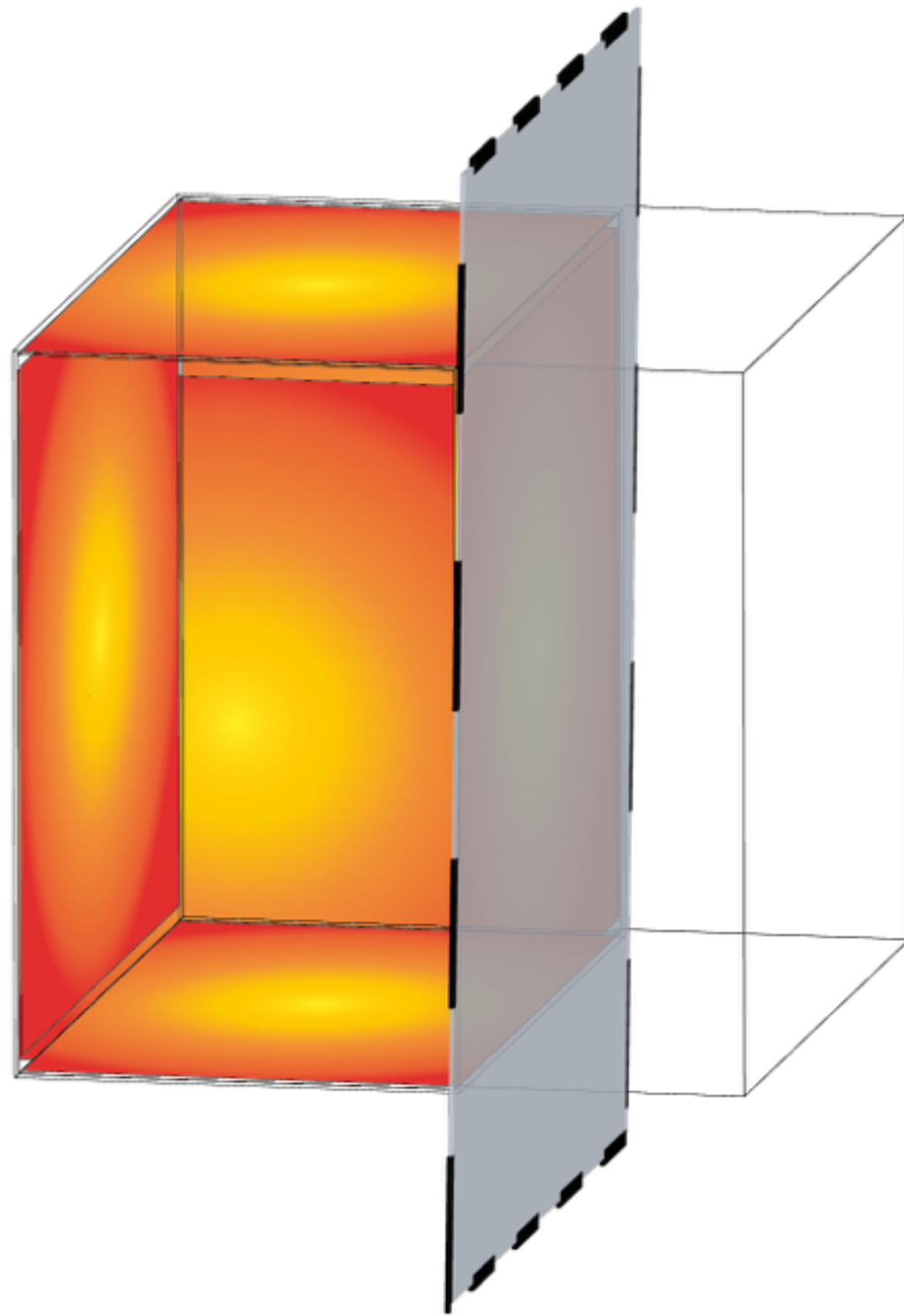
**Contribution #1:**  
**Understanding the needs of fluid dynamic experts**

# Preliminary study: understanding experts needs

- Field study with experts
- Five fluid dynamic researchers
- Observations and video-recordings
- Semi-structured interviews

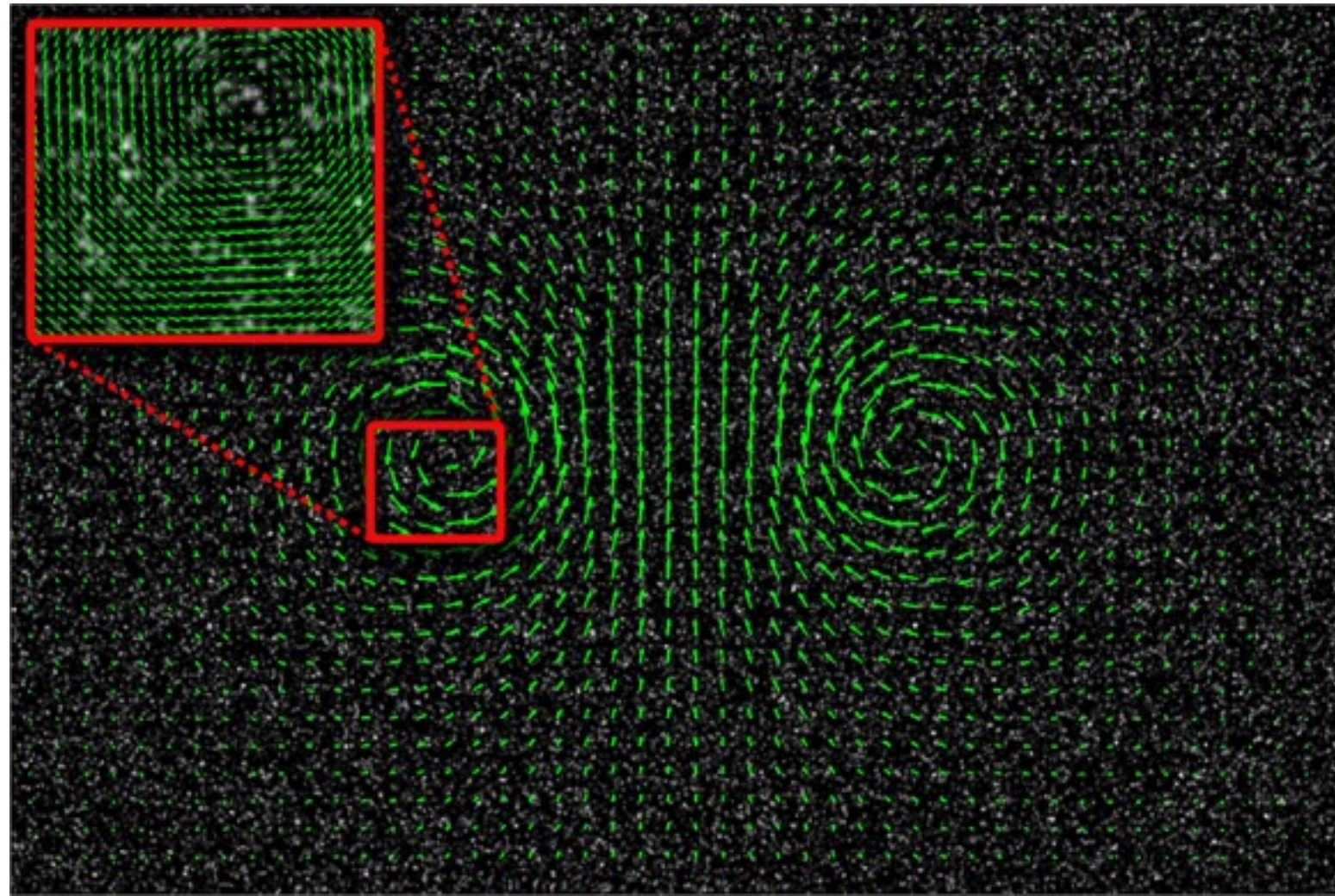


# Preliminary study results

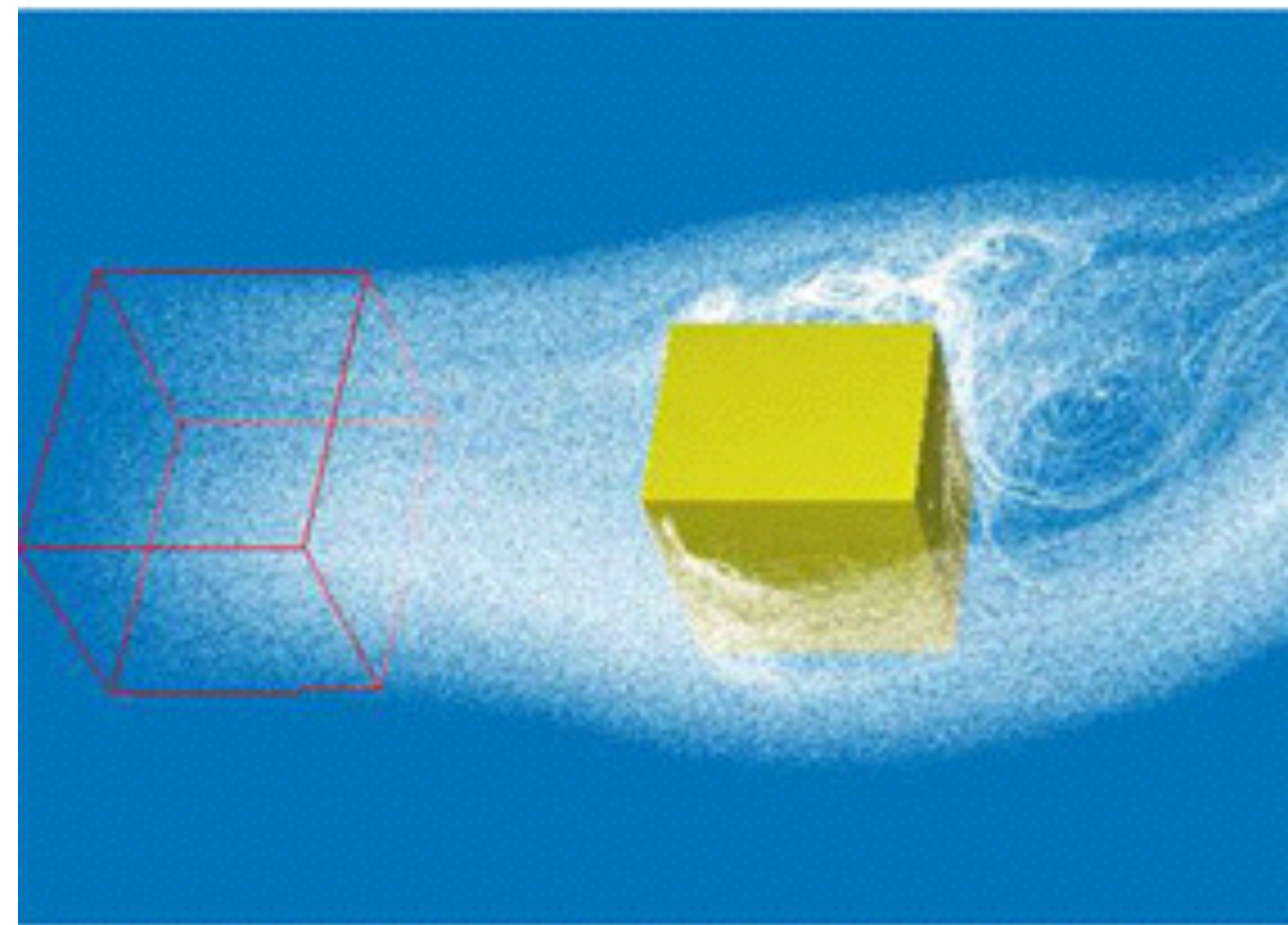




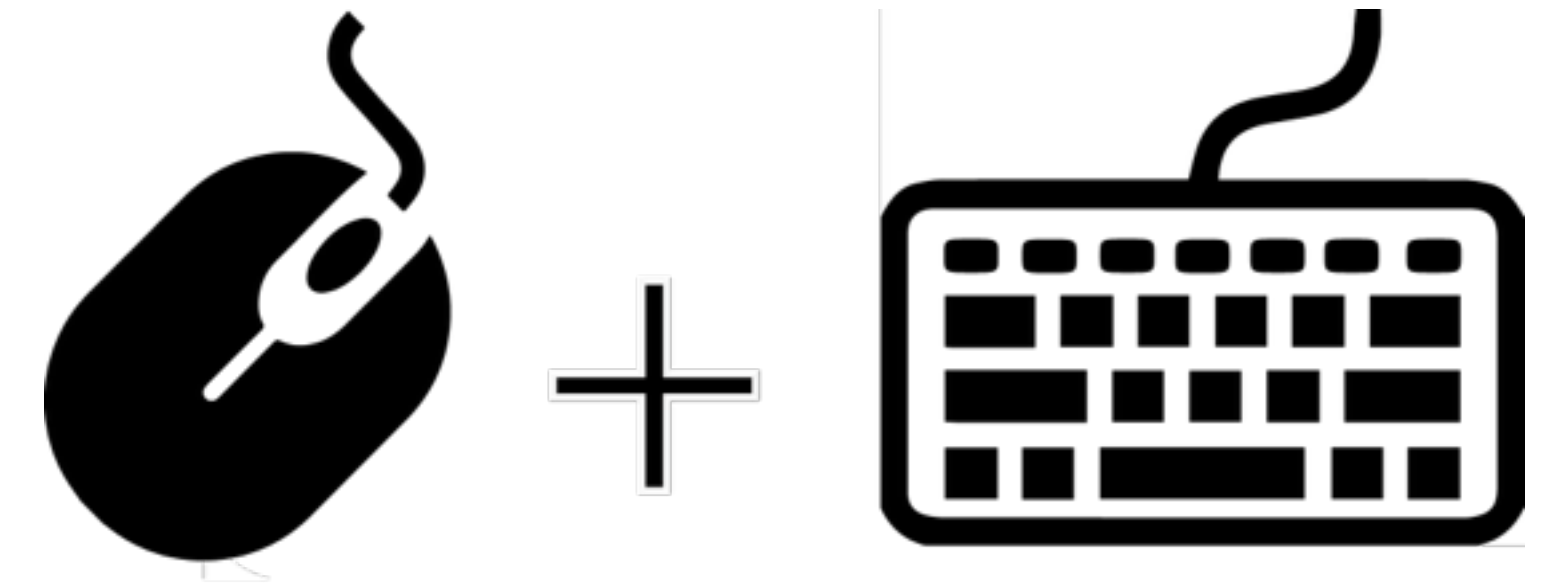
# Preliminary study results



PIVlab multipass ©Willa  
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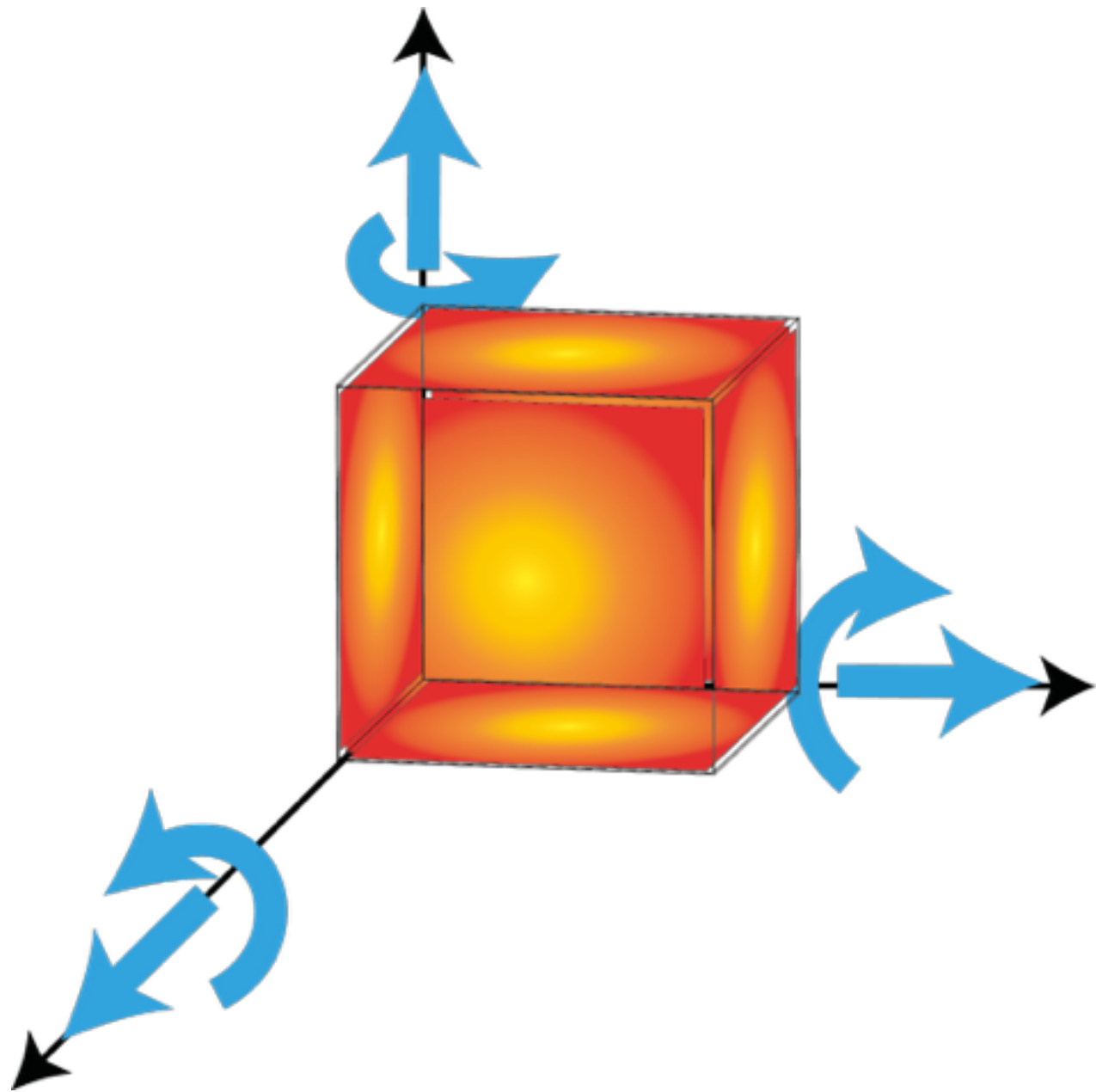


Kruger et al. (2005)

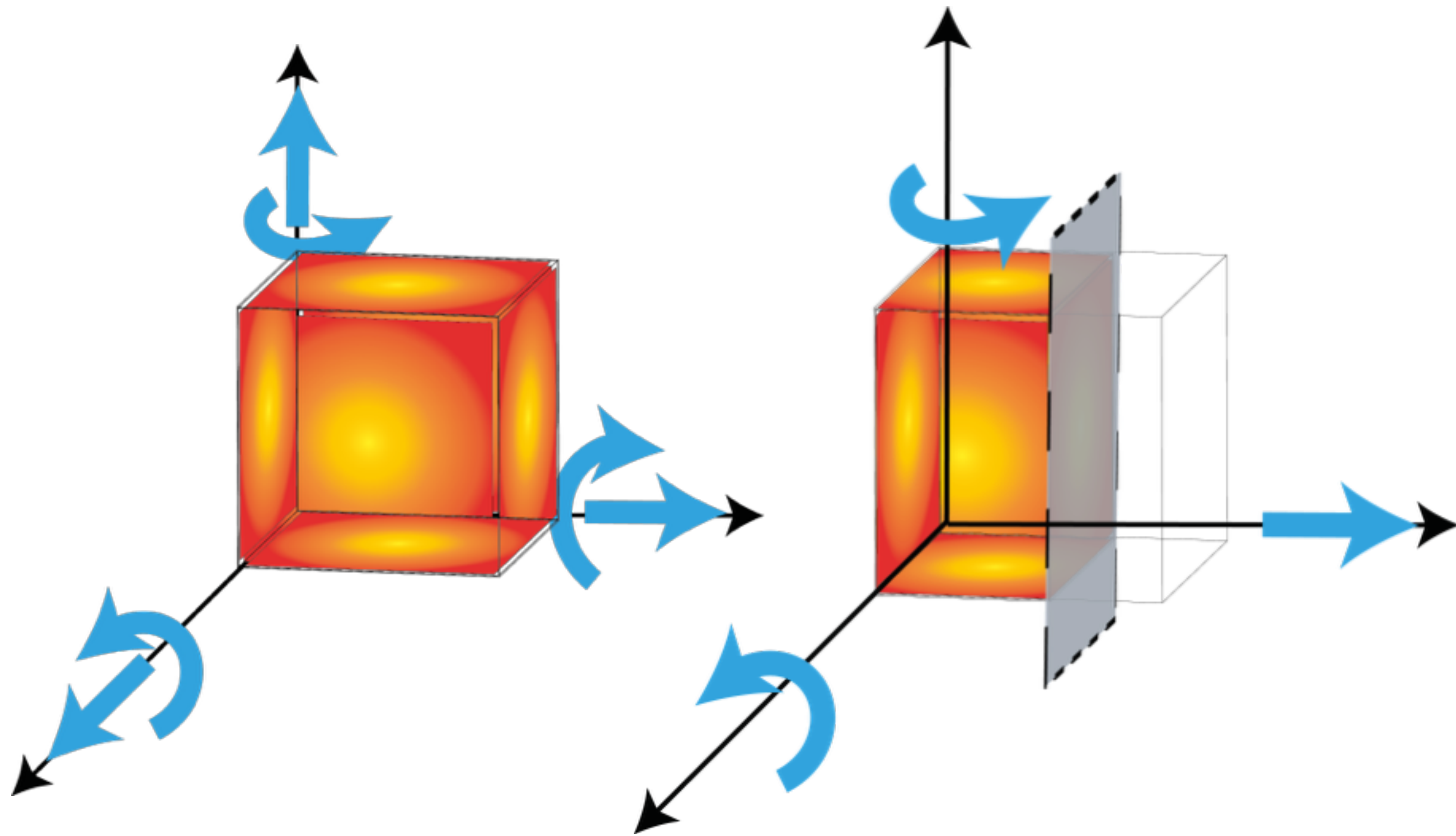




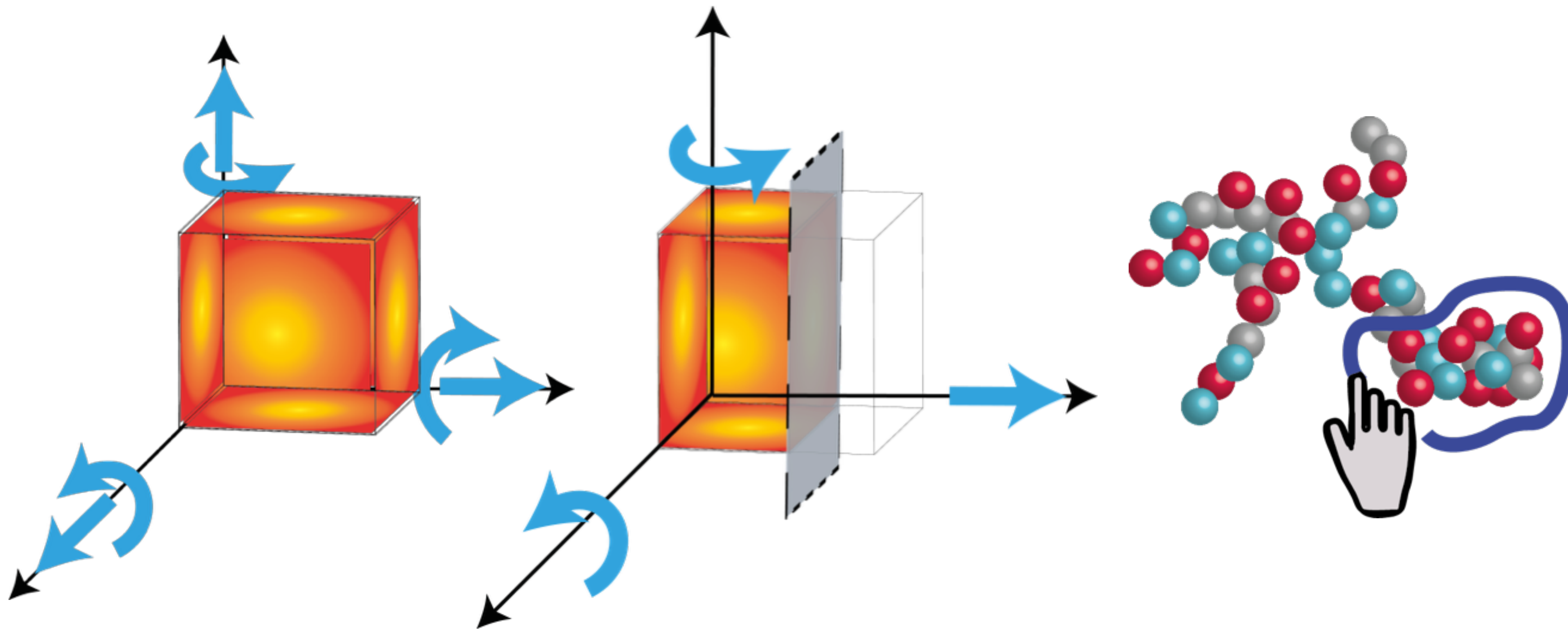
# Interaction Tasks in Spatial 3D data



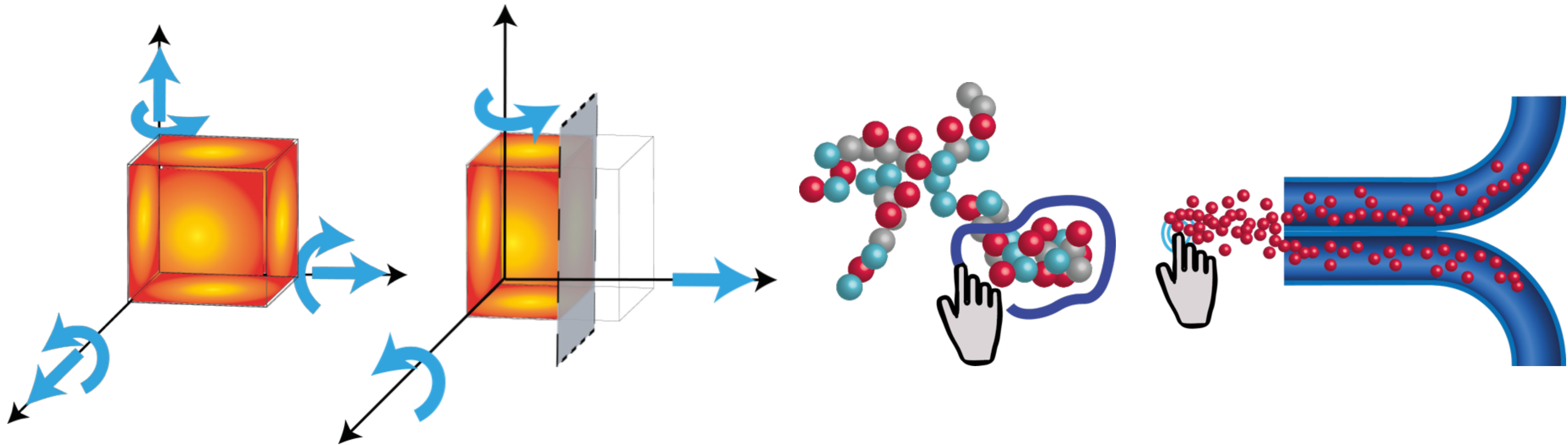
# Interaction Tasks in Spatial 3D data



# Interaction Tasks in Spatial 3D data



# Interaction Tasks in Spatial 3D data



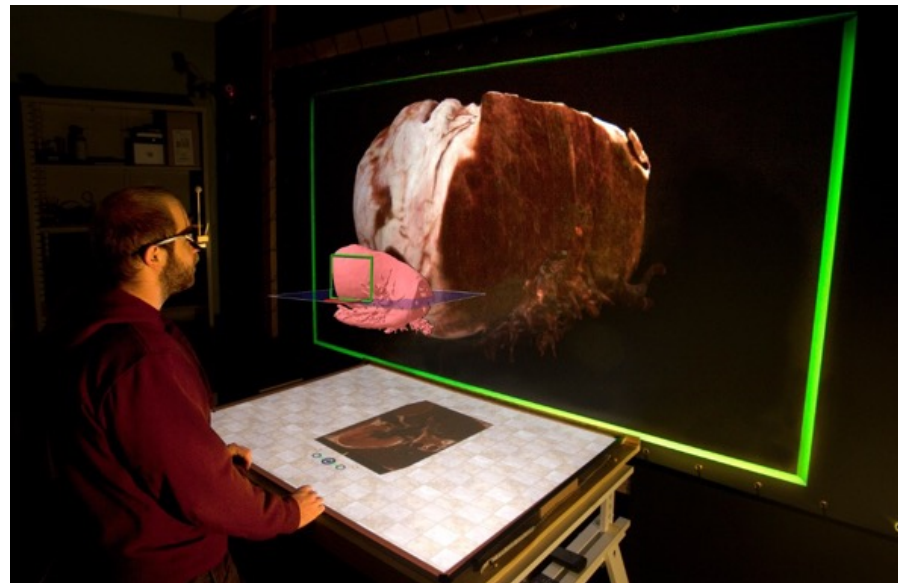


# **Contribution #2:**

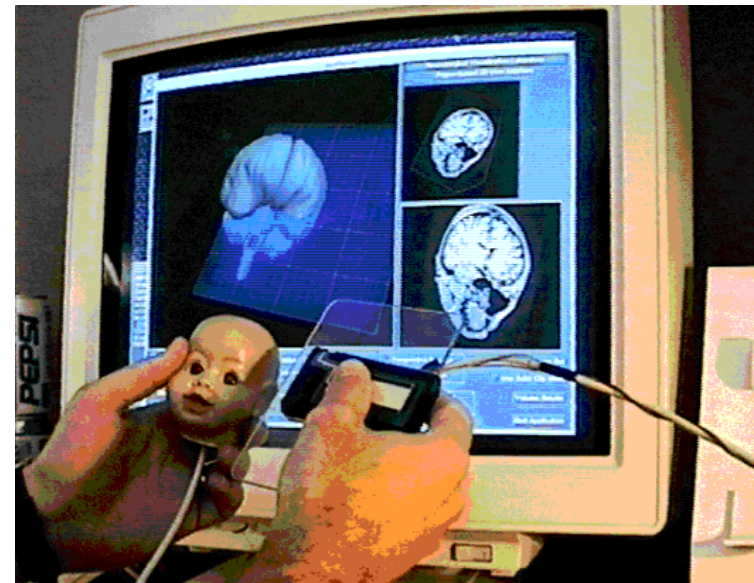
## **Design space exploration**



# Examples



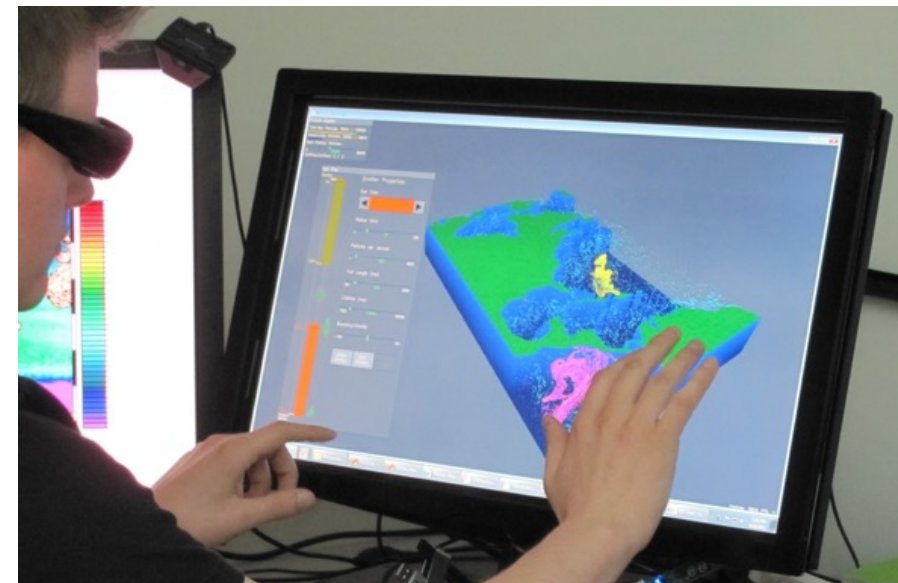
Coffey et al. (2012)



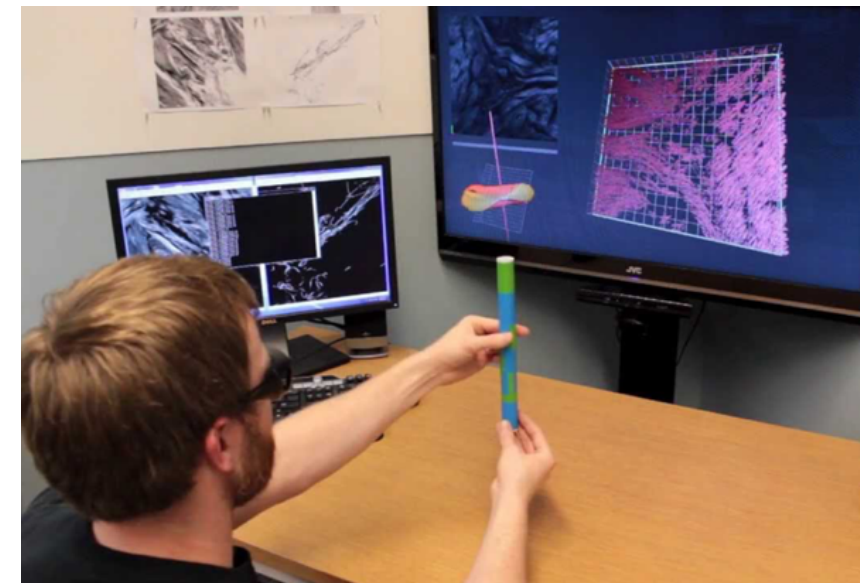
Hinckley et al. (1994)



Keefe (2010)



Butkiewicz & Ware (2012)



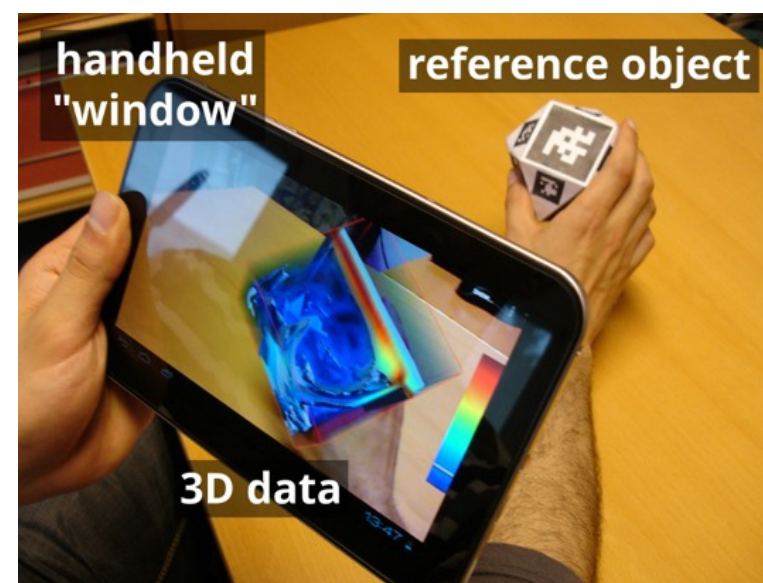
Jackson et al. (2013)



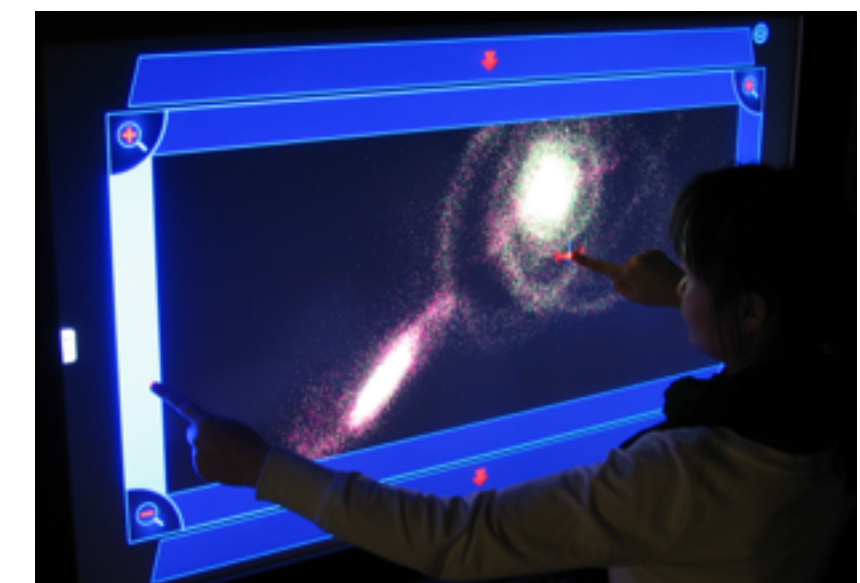
Schkolne et al. (2012)



Jackson et al. (2012)



Issartel et al. (2014)



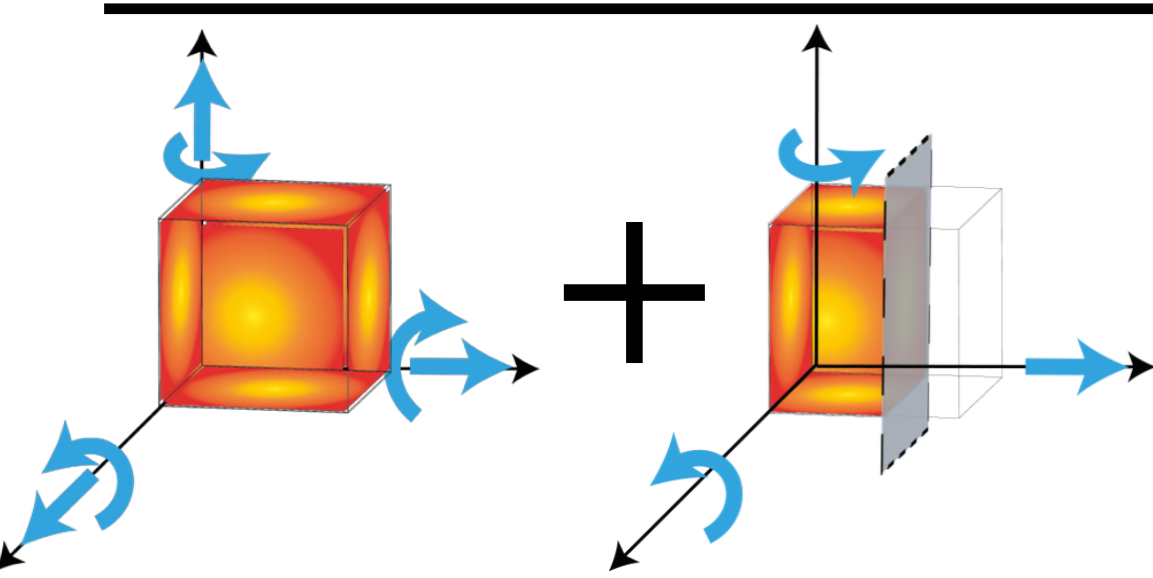
Yu et al. (2014)



# Design Space Exploration: tactile-only and tangible-only settings

Tasks		

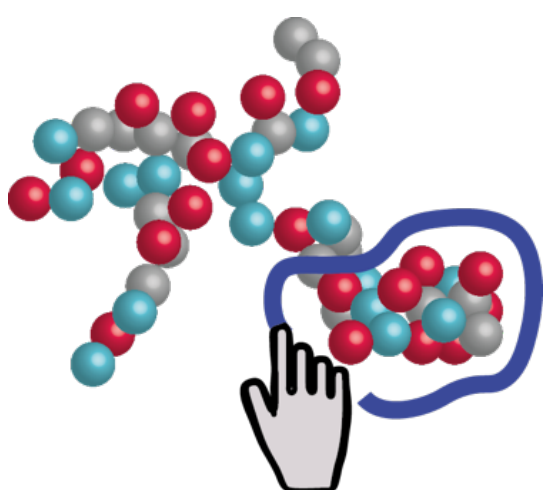
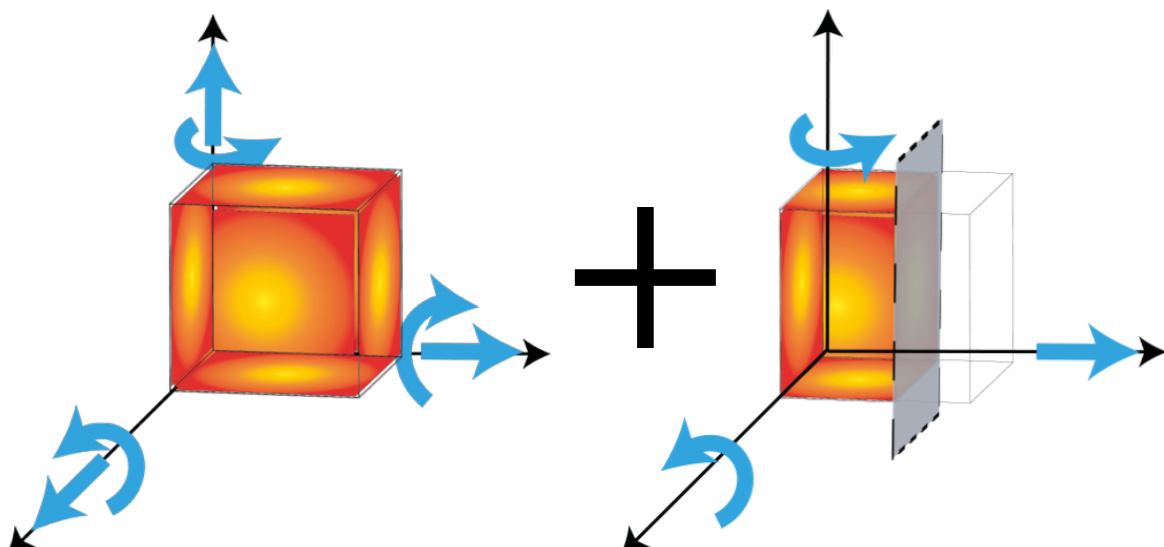
# Design Space Exploration: tactile-only and tangible-only settings

Tasks		
		

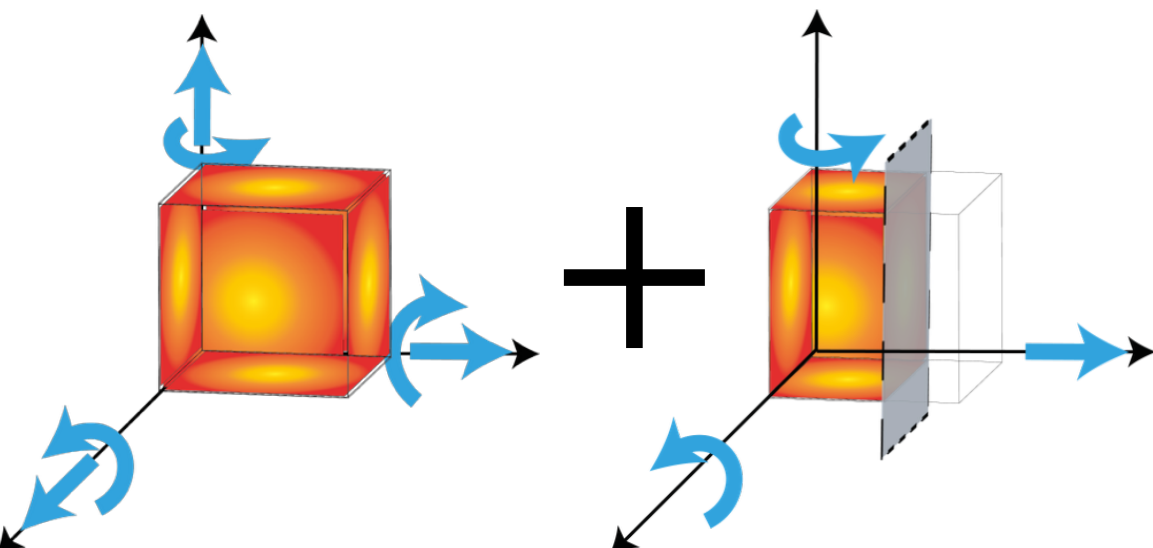
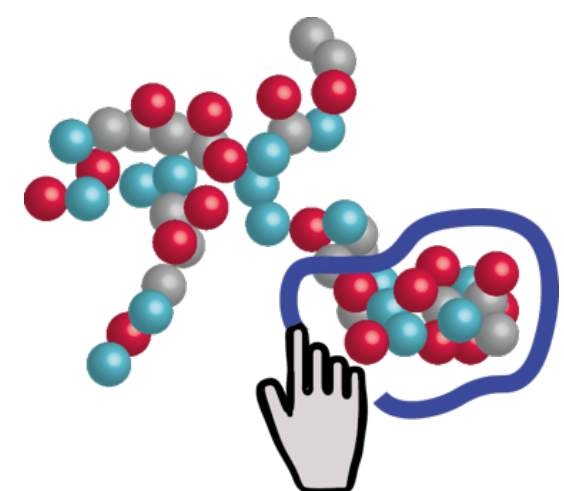
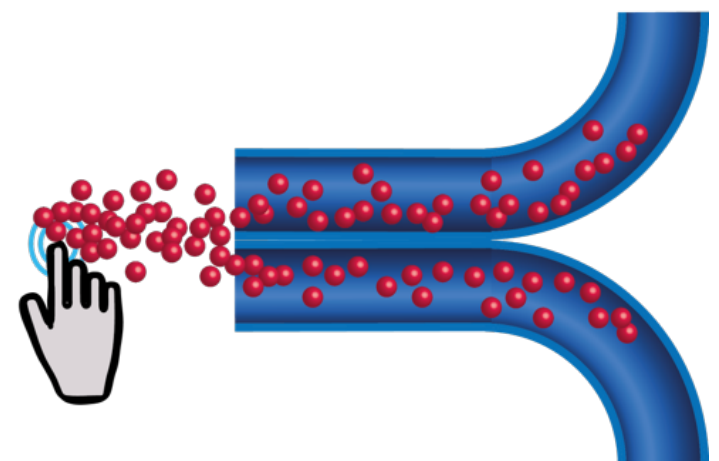


# Design Space Exploration: tactile-only and tangible-only settings

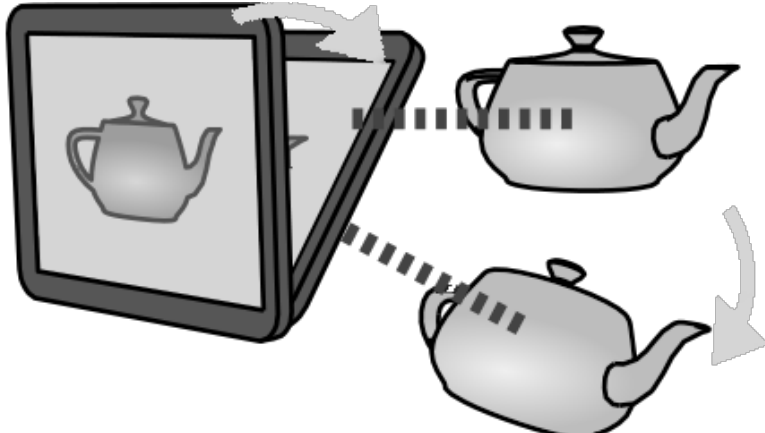
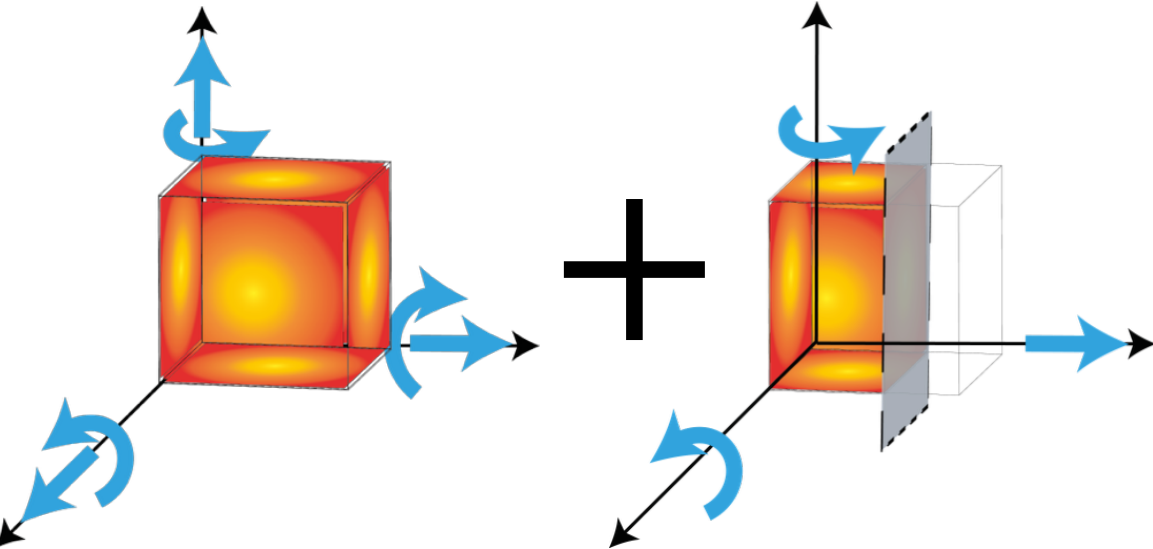
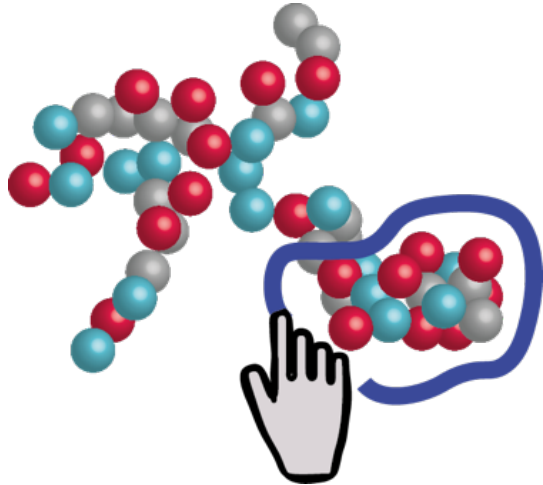
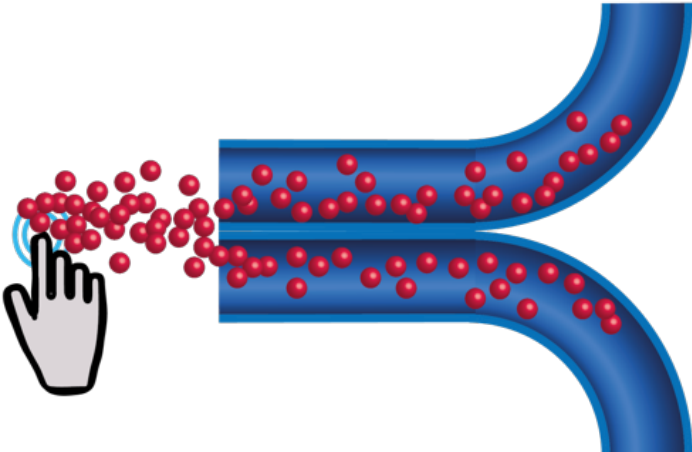
Tasks



# Design Space Exploration: tactile-only and tangible-only settings

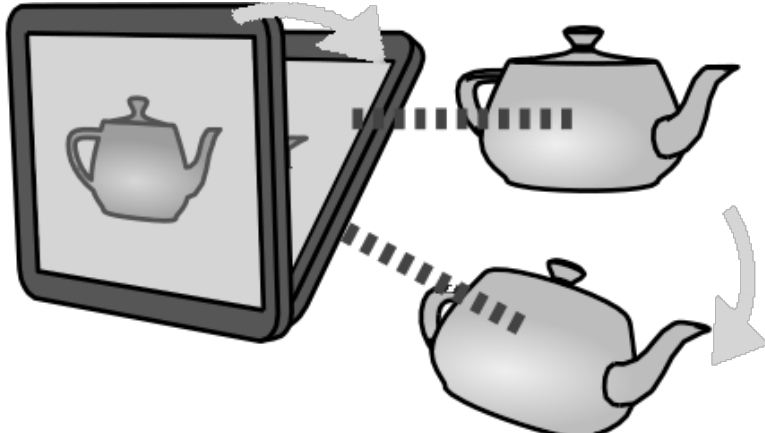
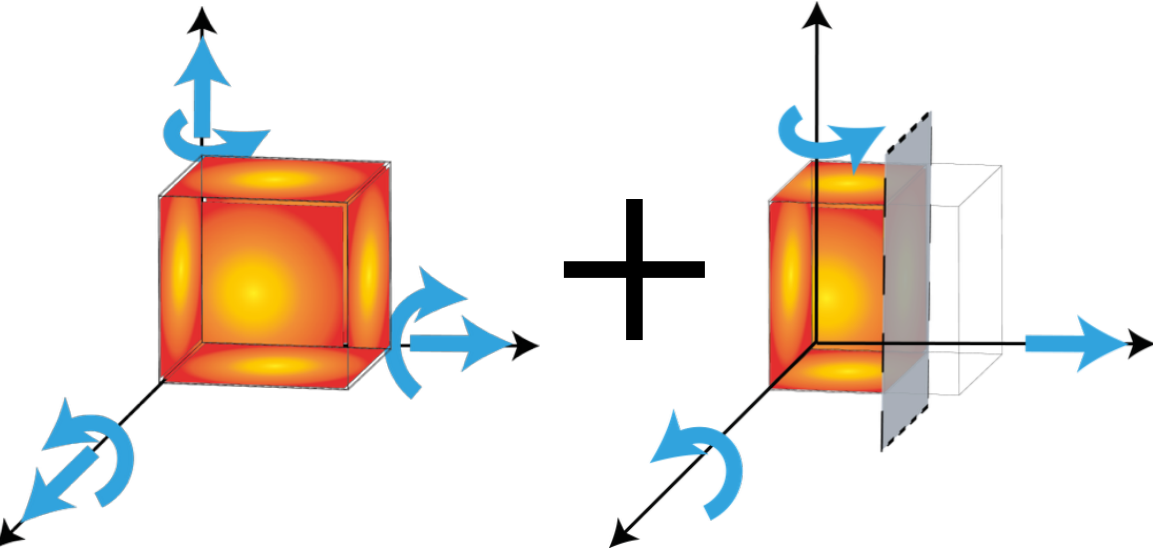

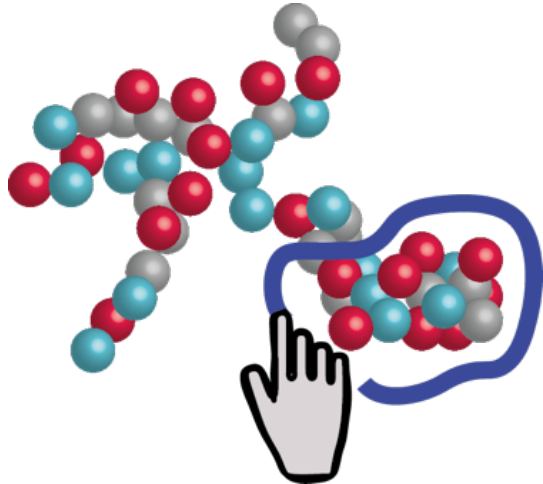
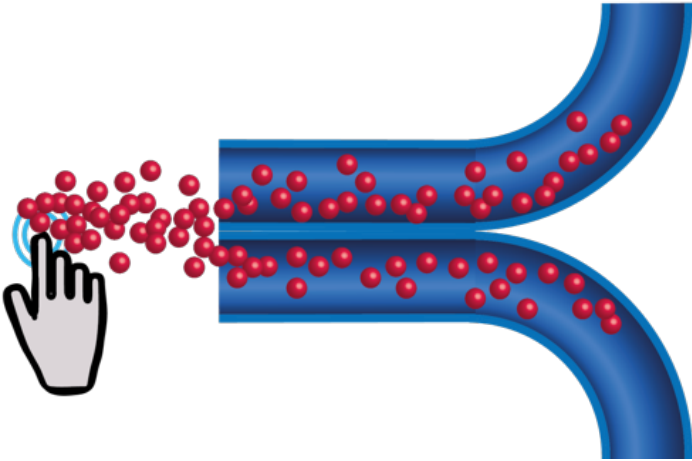
Tasks		
		
		
		

# Design Space Exploration: tactile-only and tangible-only settings

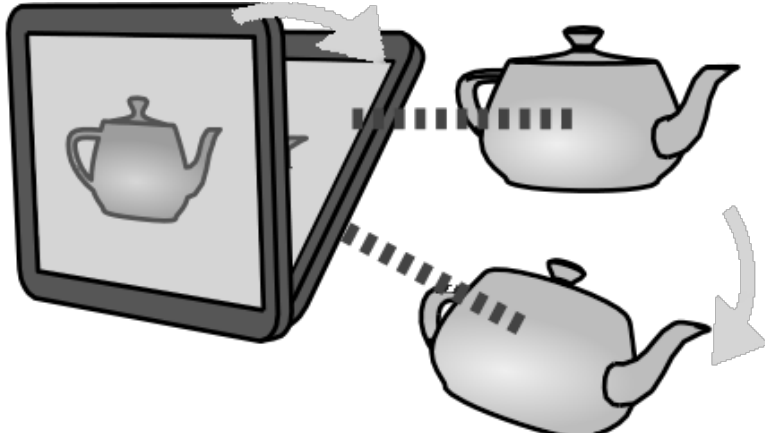
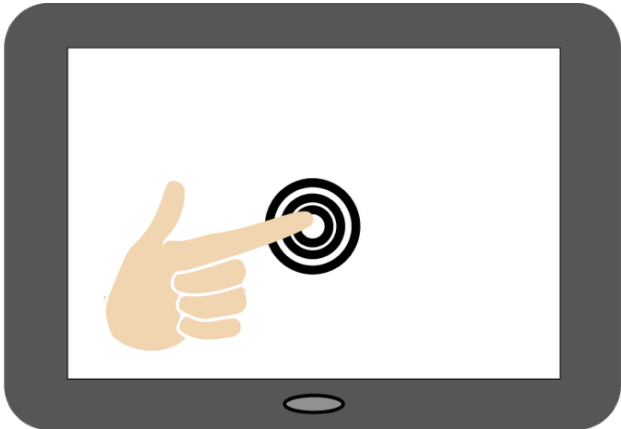
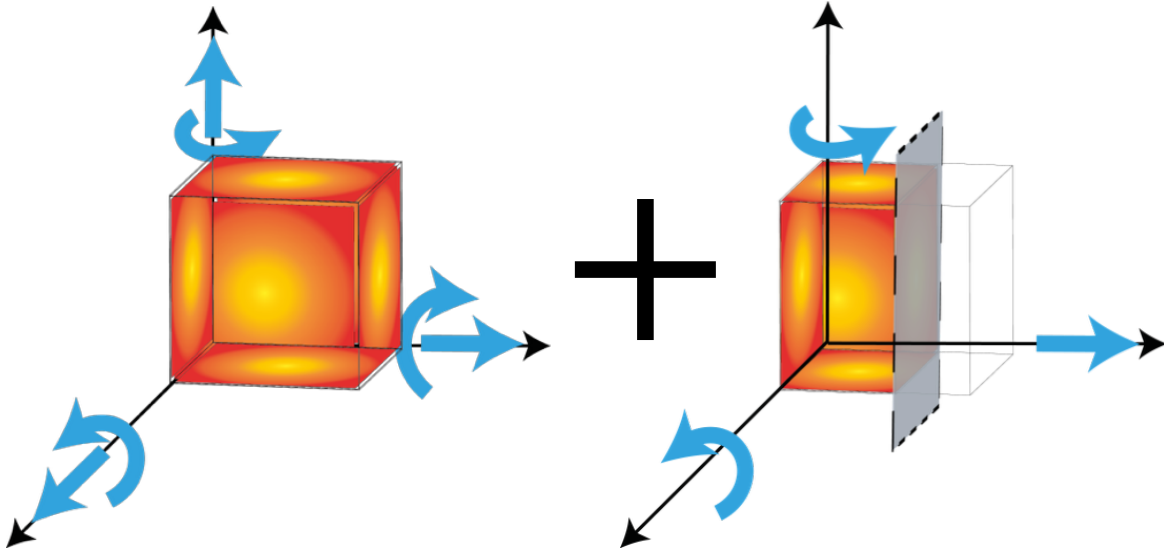

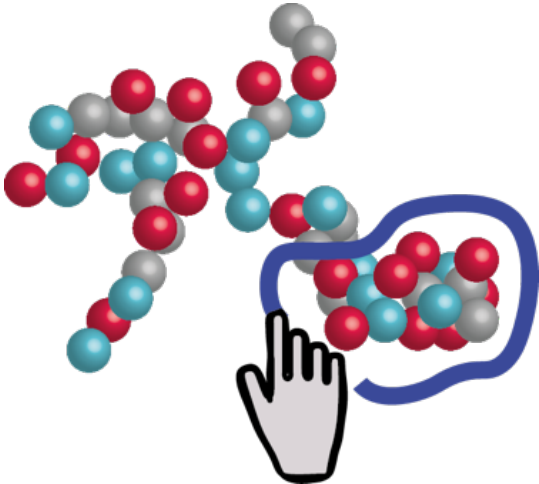
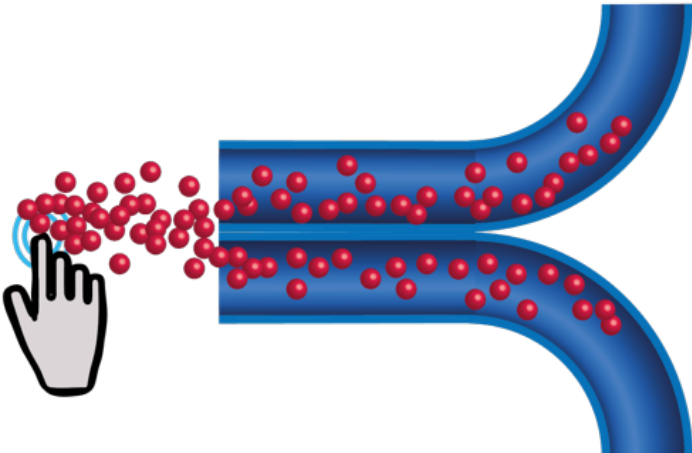
Tasks		
		
		
		



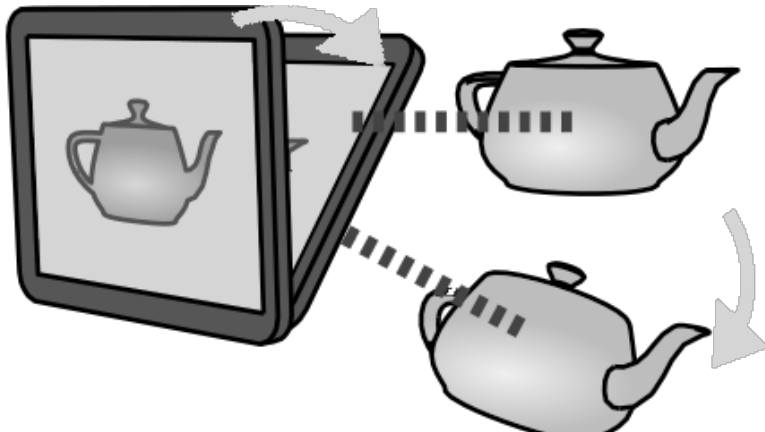
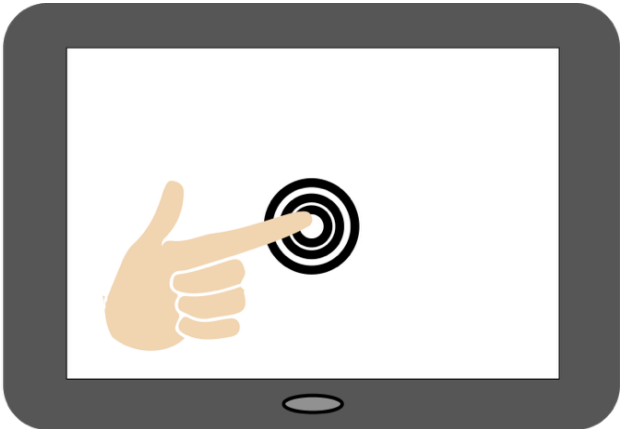
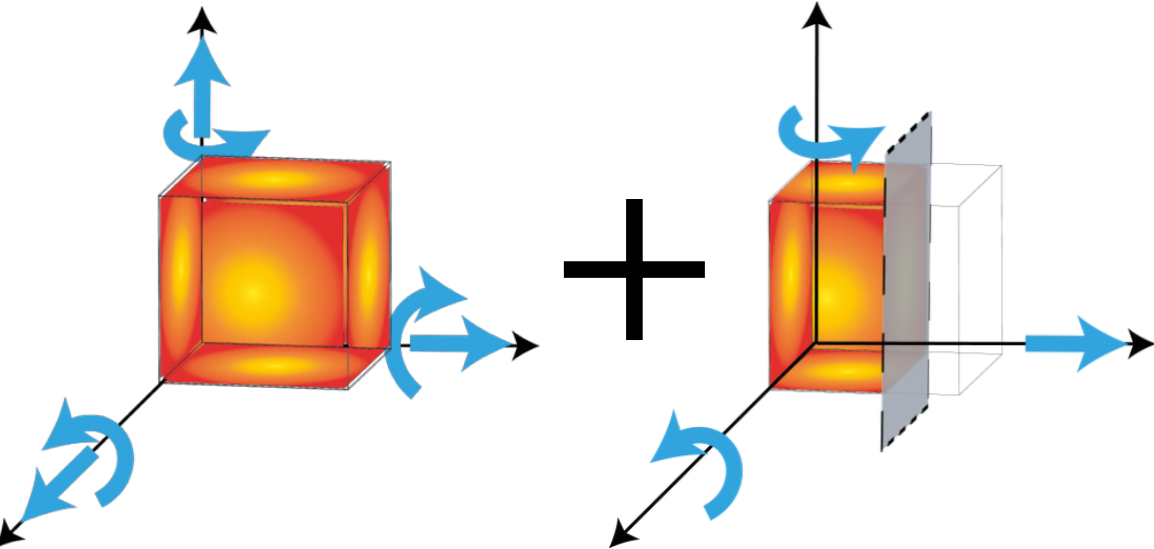

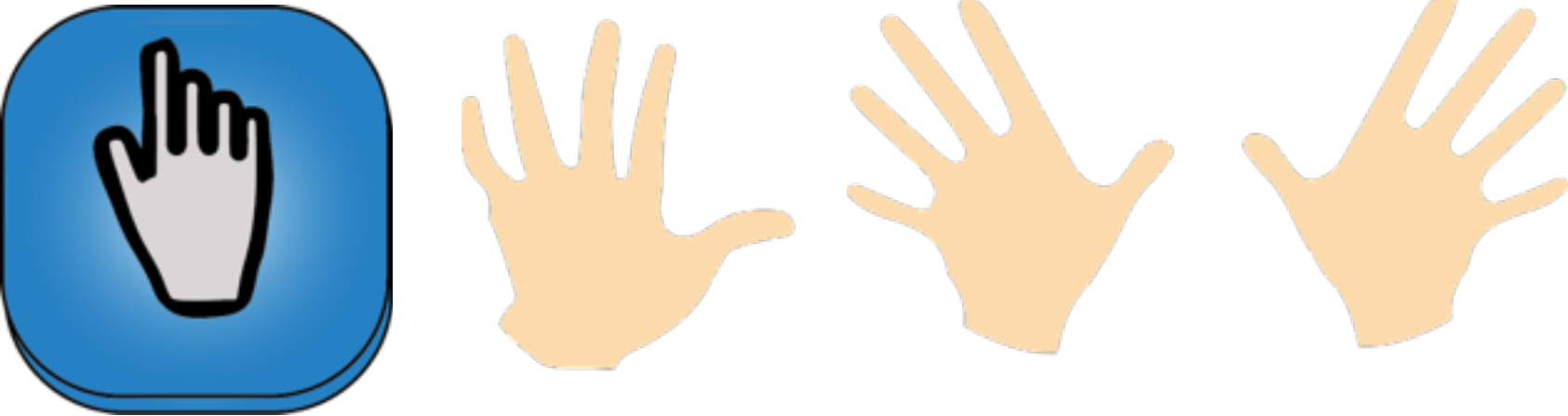
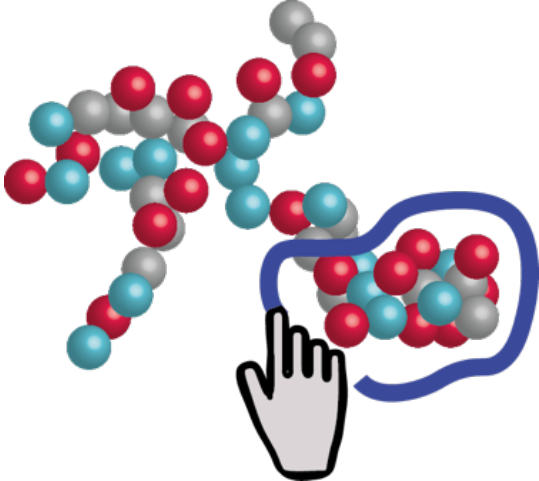
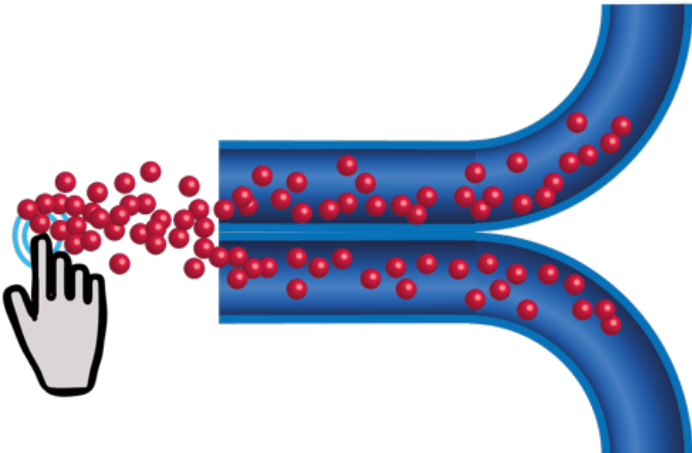
# Design Space Exploration: tactile-only and tangible-only settings

Tasks		
		
		
		

# Design Space Exploration: tactile-only and tangible-only settings

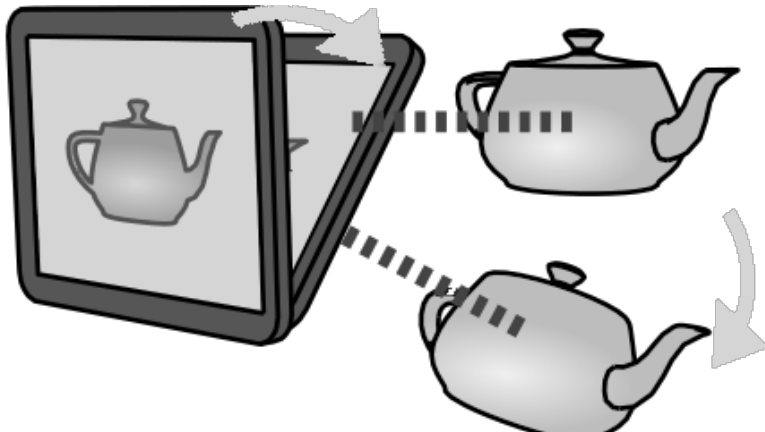
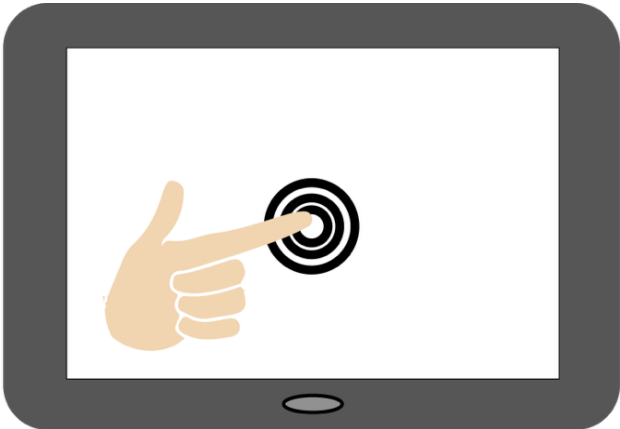
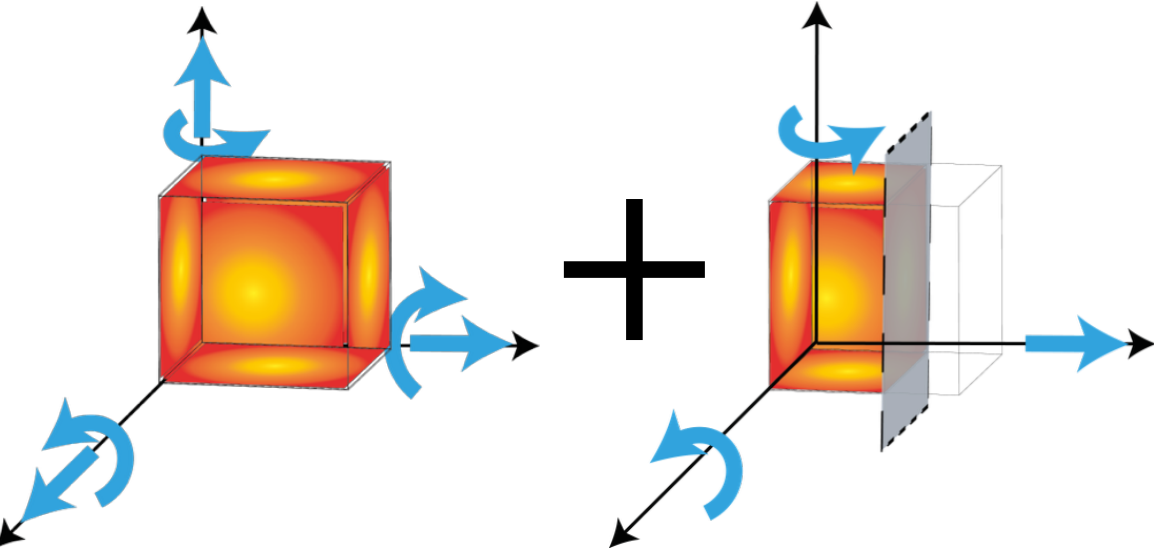

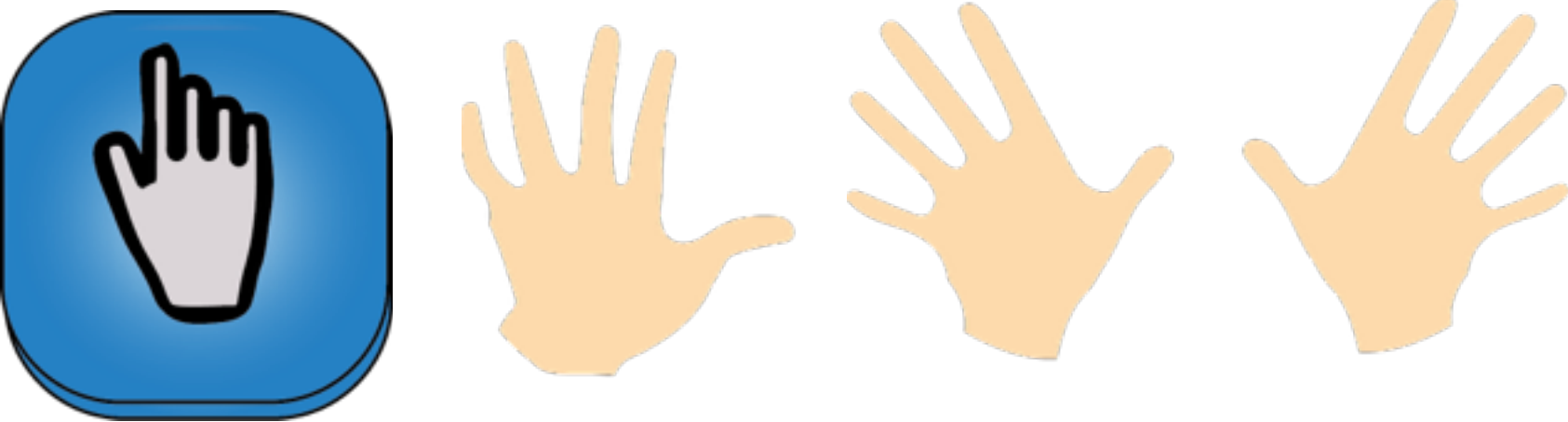
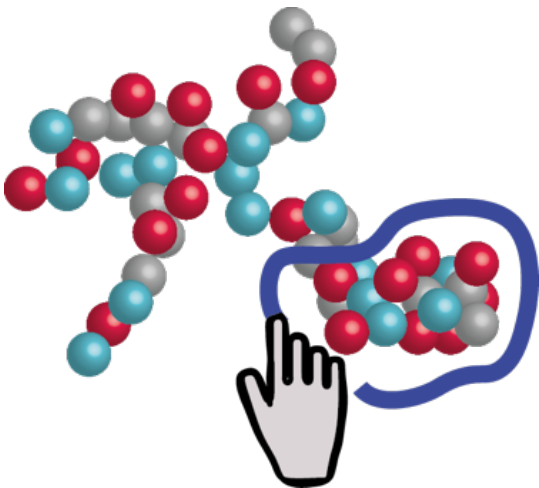
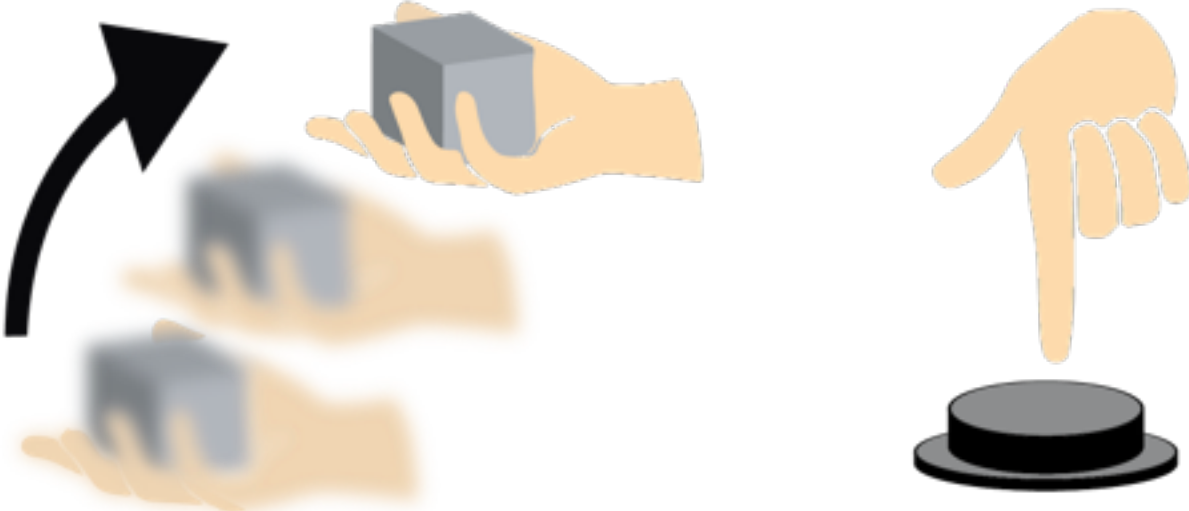
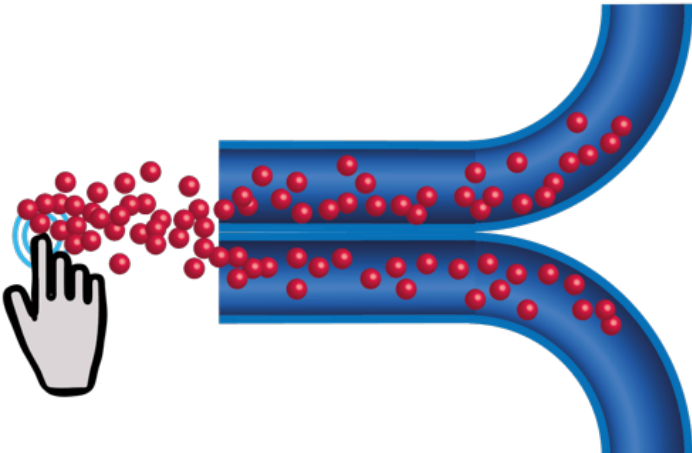
Tasks		
		
		
		

# Design Space Exploration: tactile-only and tangible-only settings

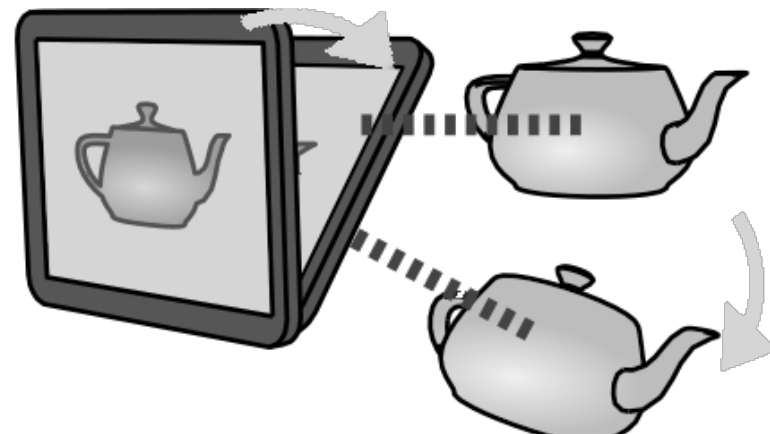
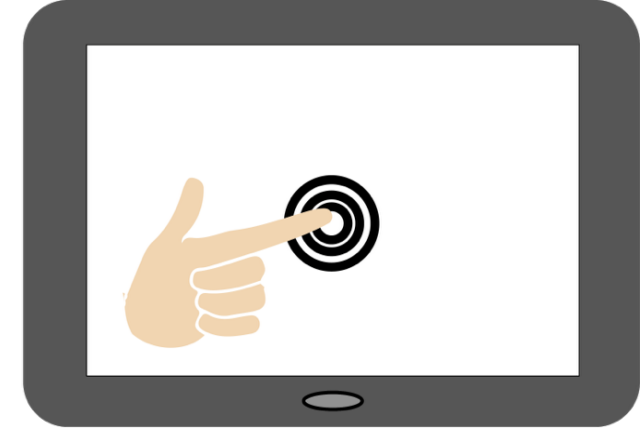
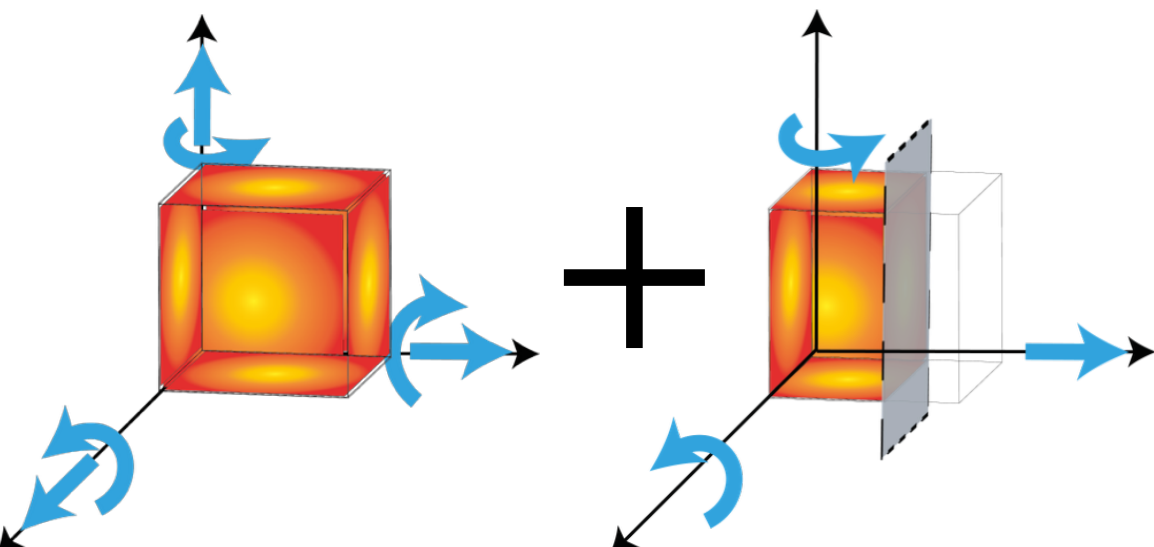

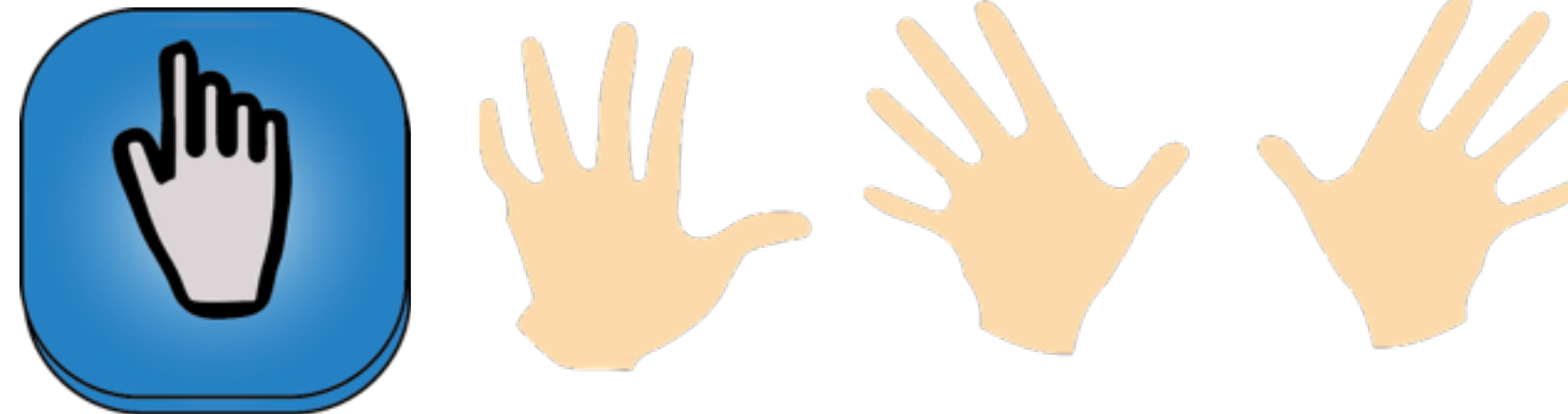
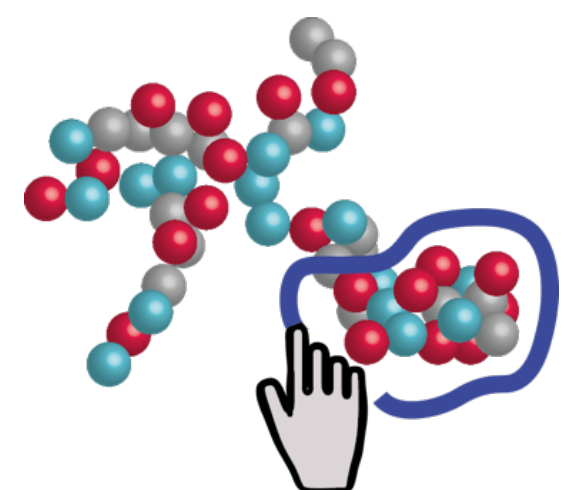
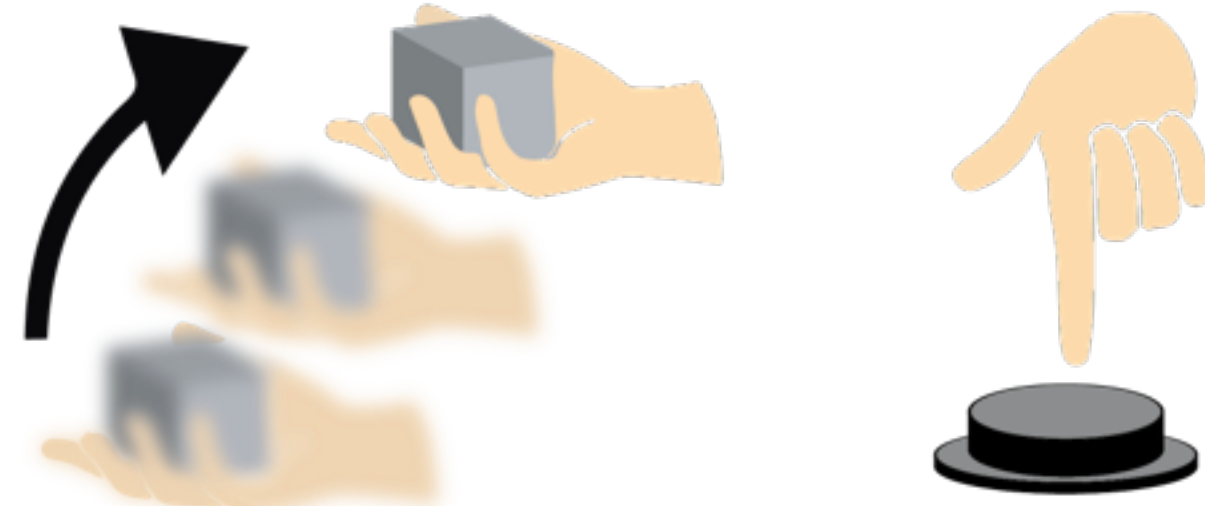
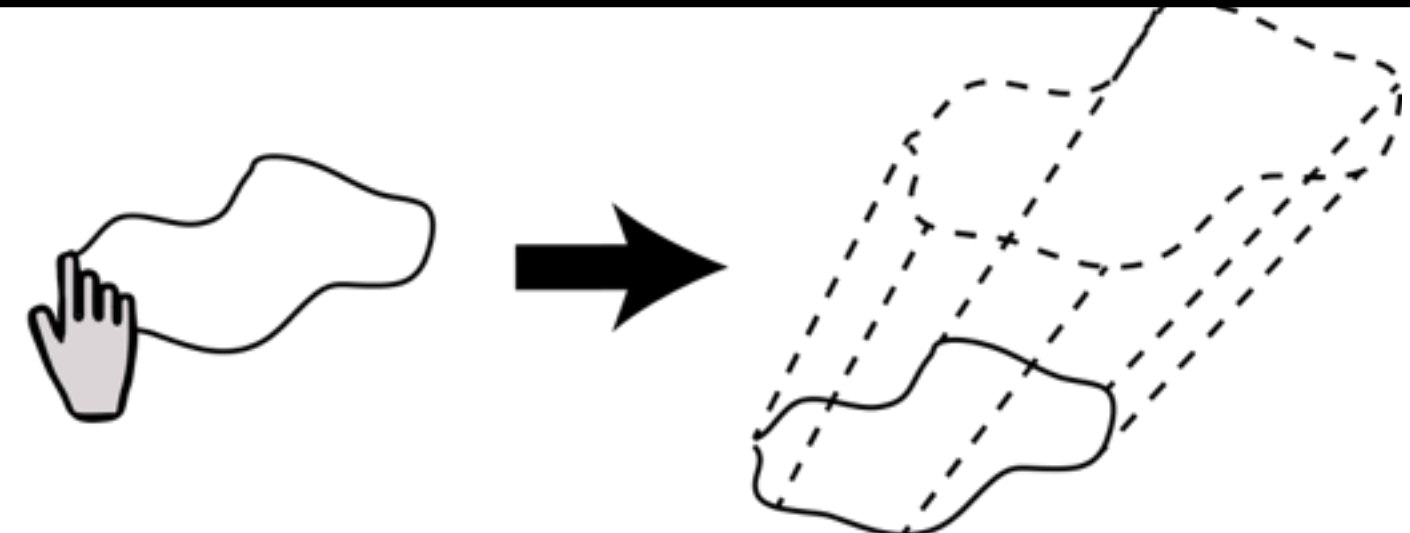
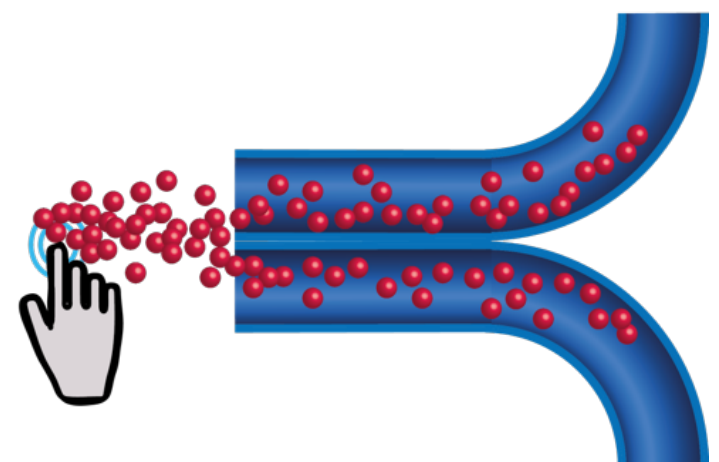
Tasks		
		
		
		



# Design Space Exploration: tactile-only and tangible-only settings

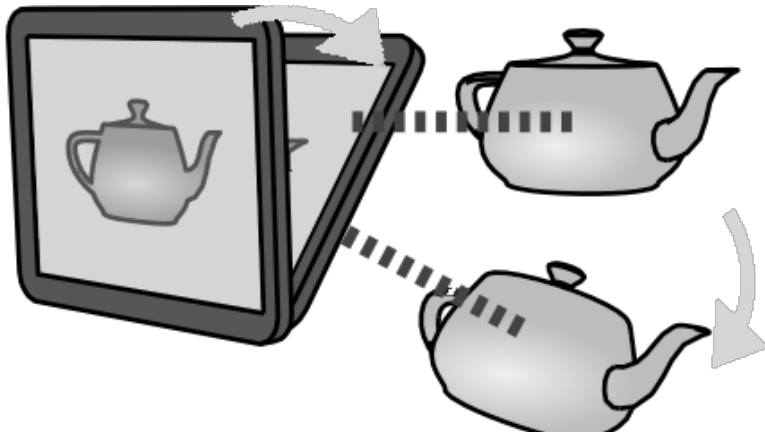
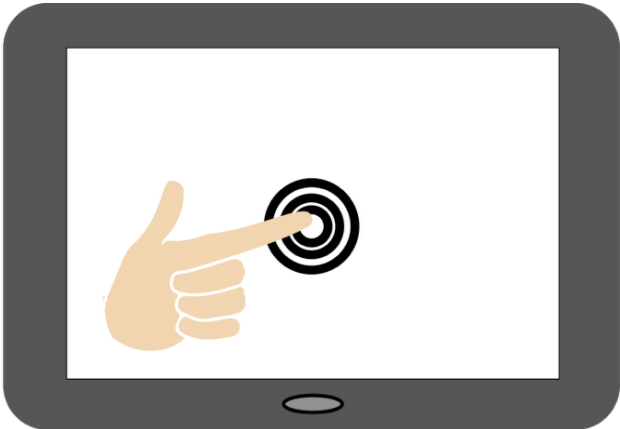
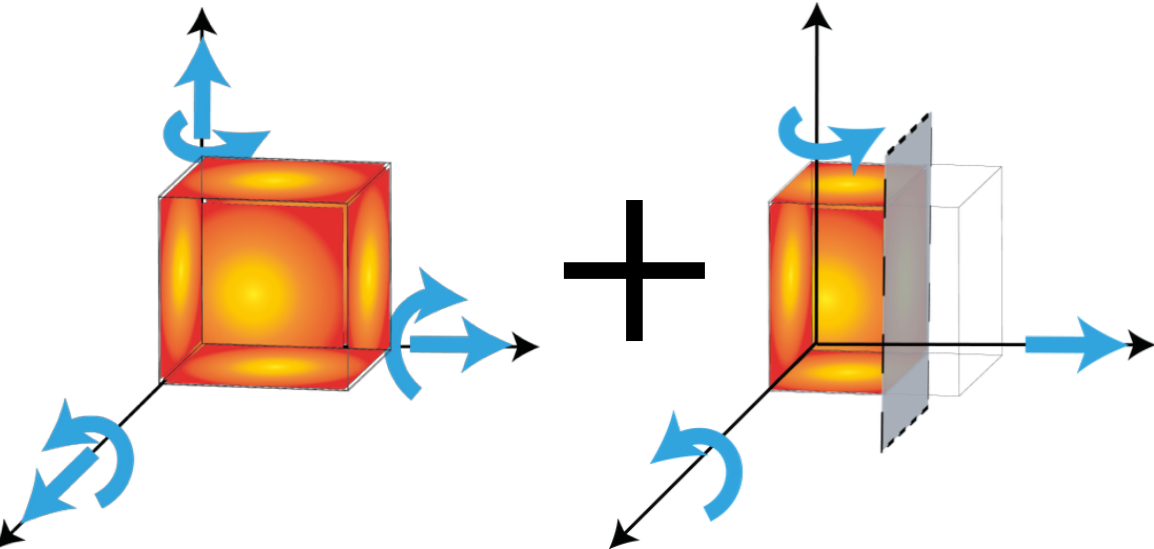

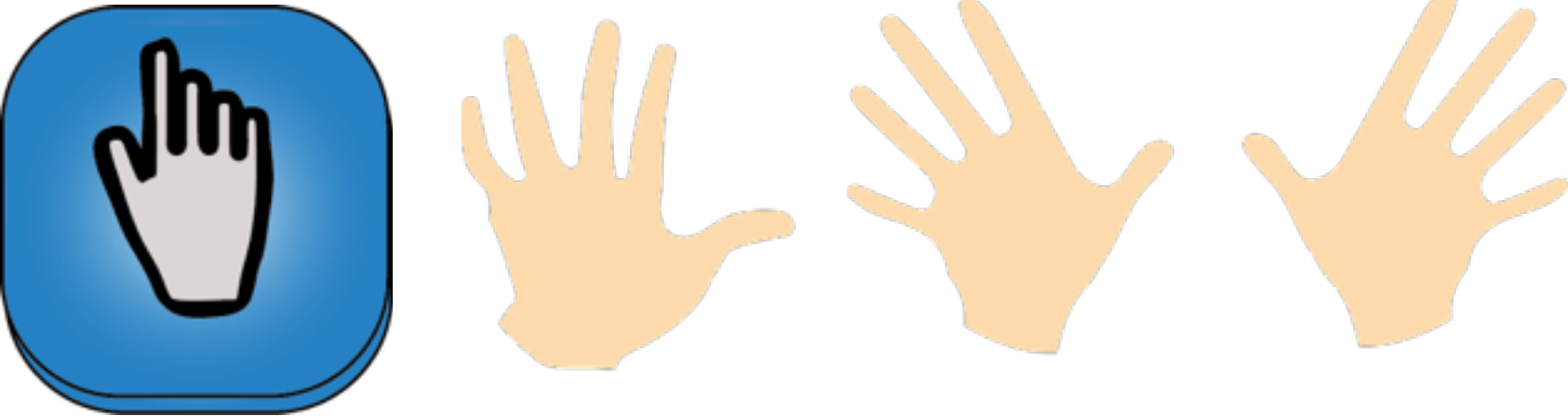
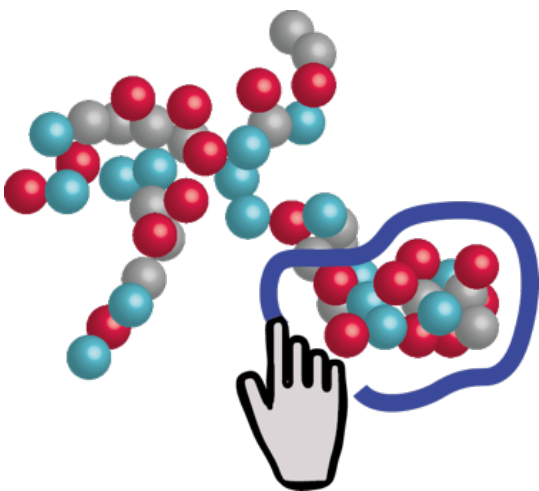
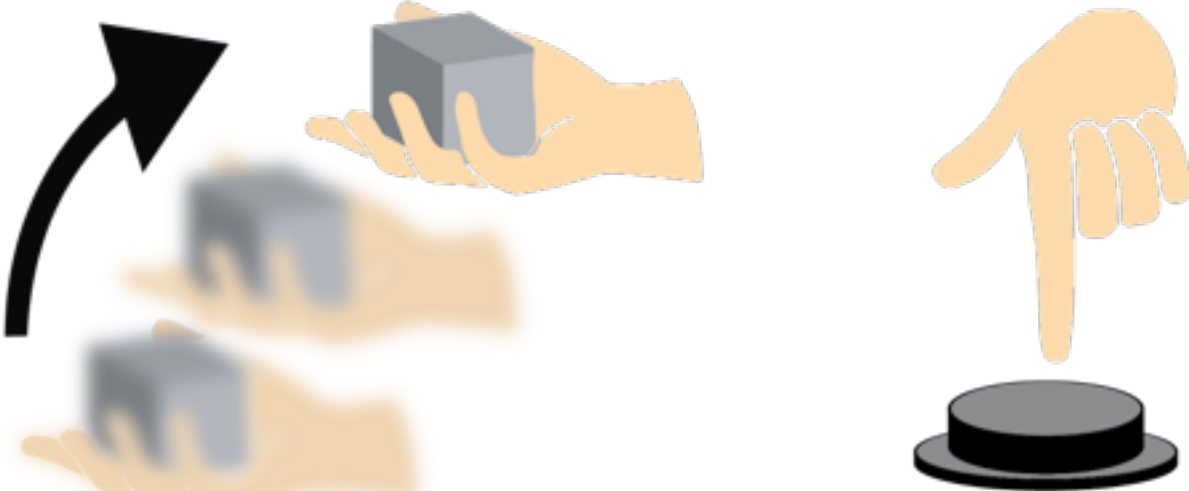
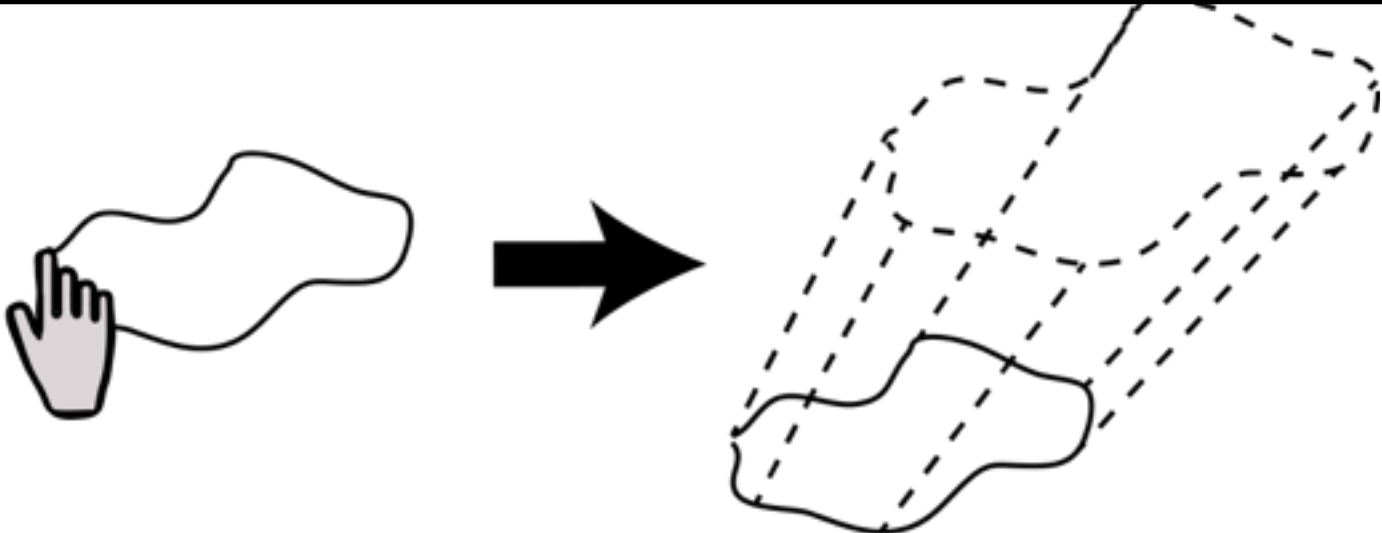
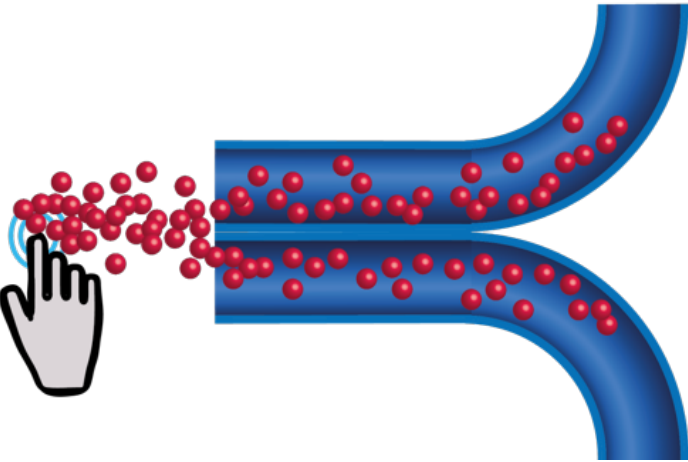
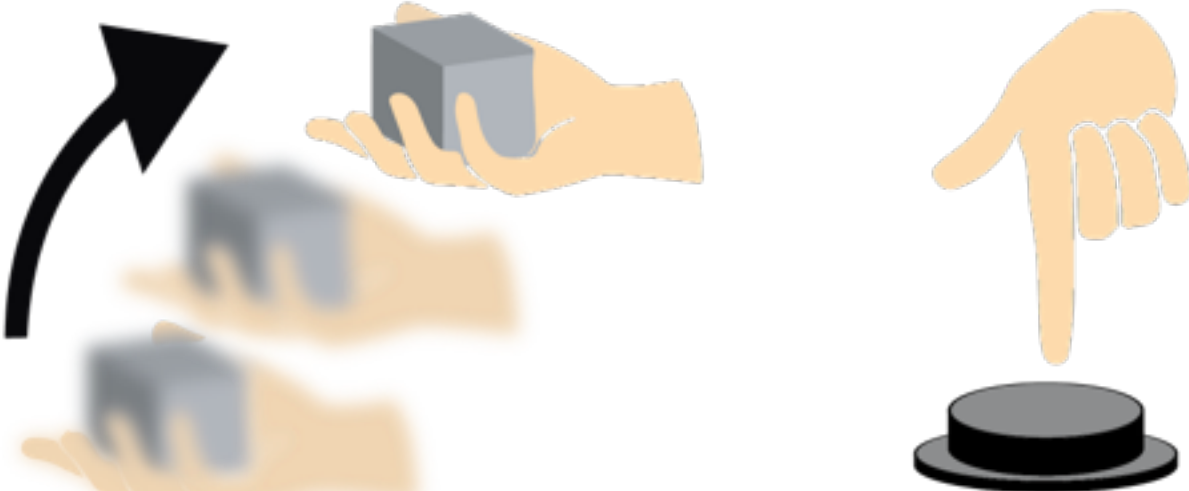
Tasks		
		
		
		

# Design Space Exploration: tactile-only and tangible-only settings

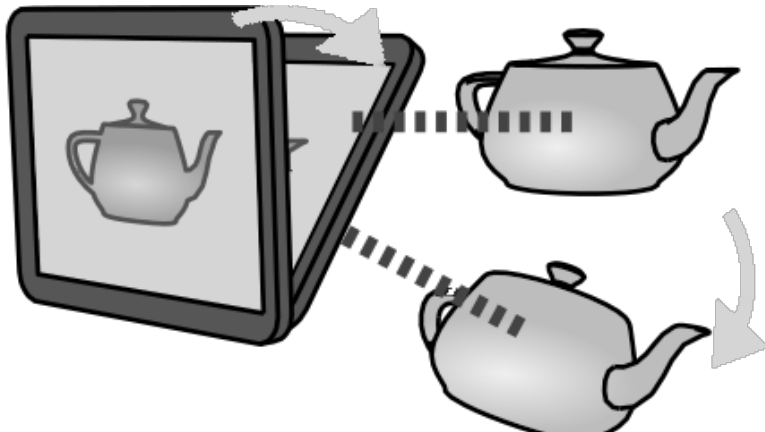
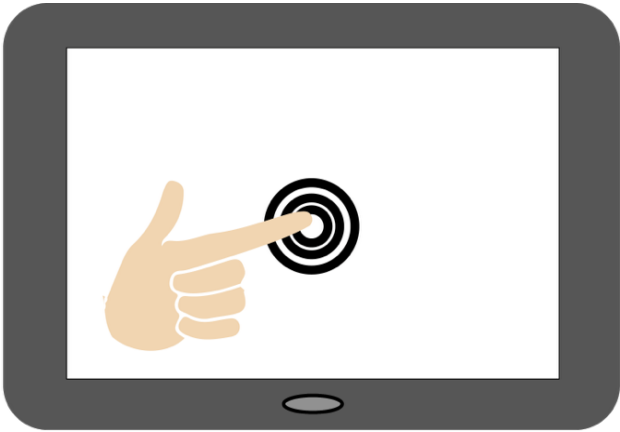
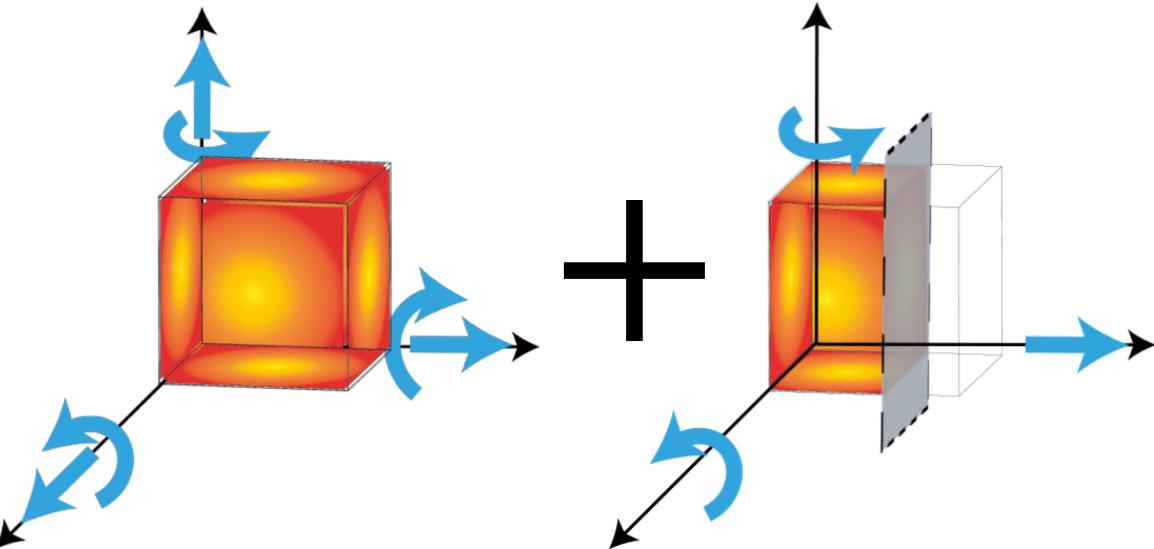

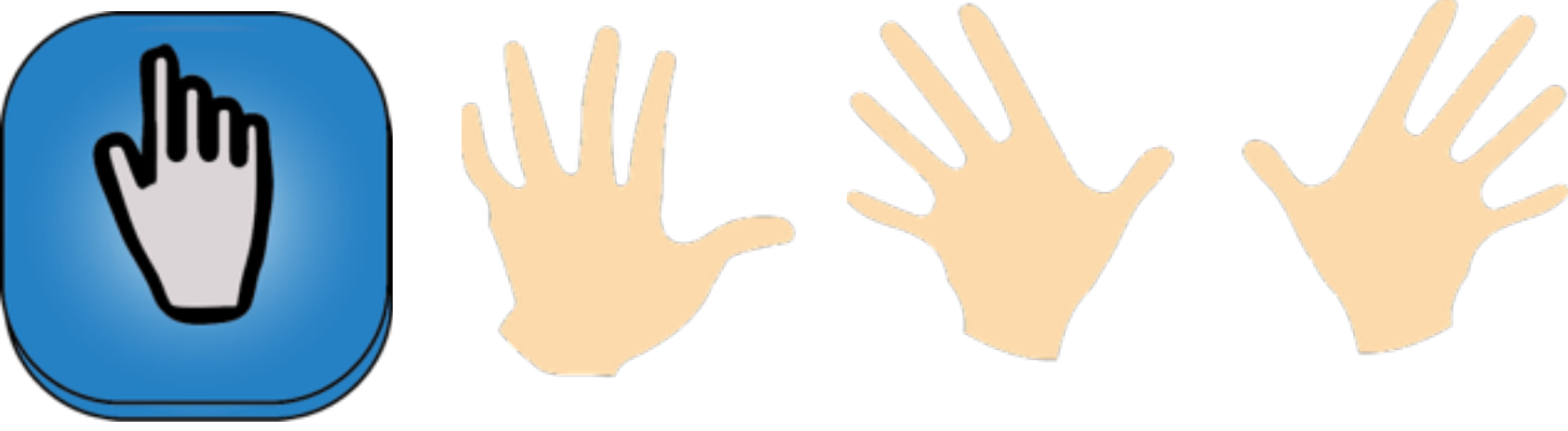
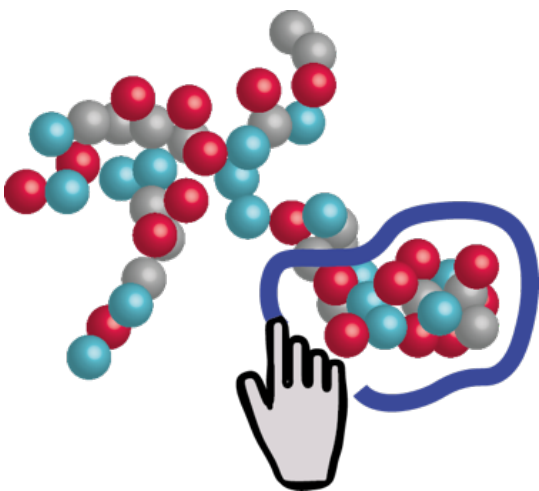
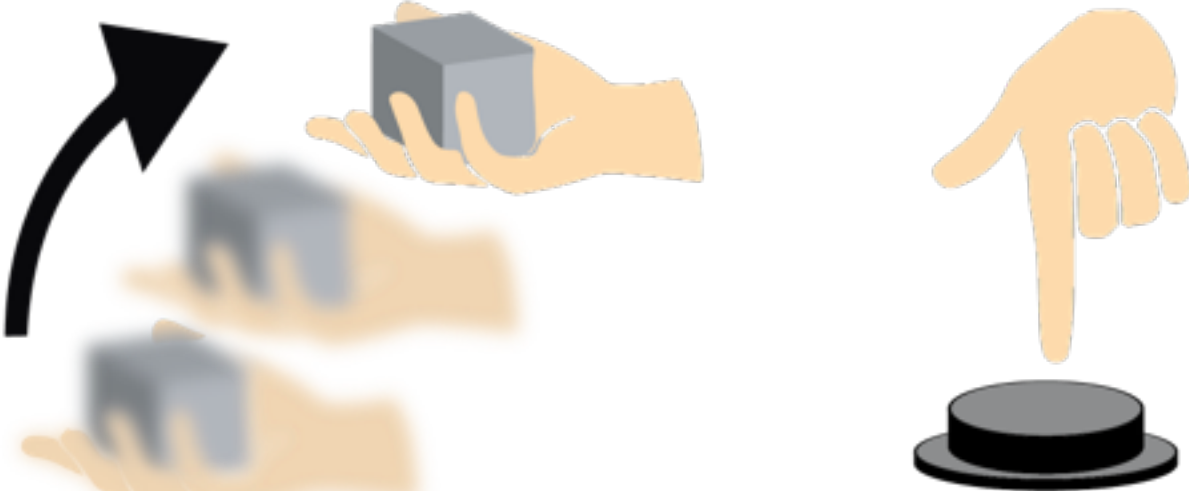
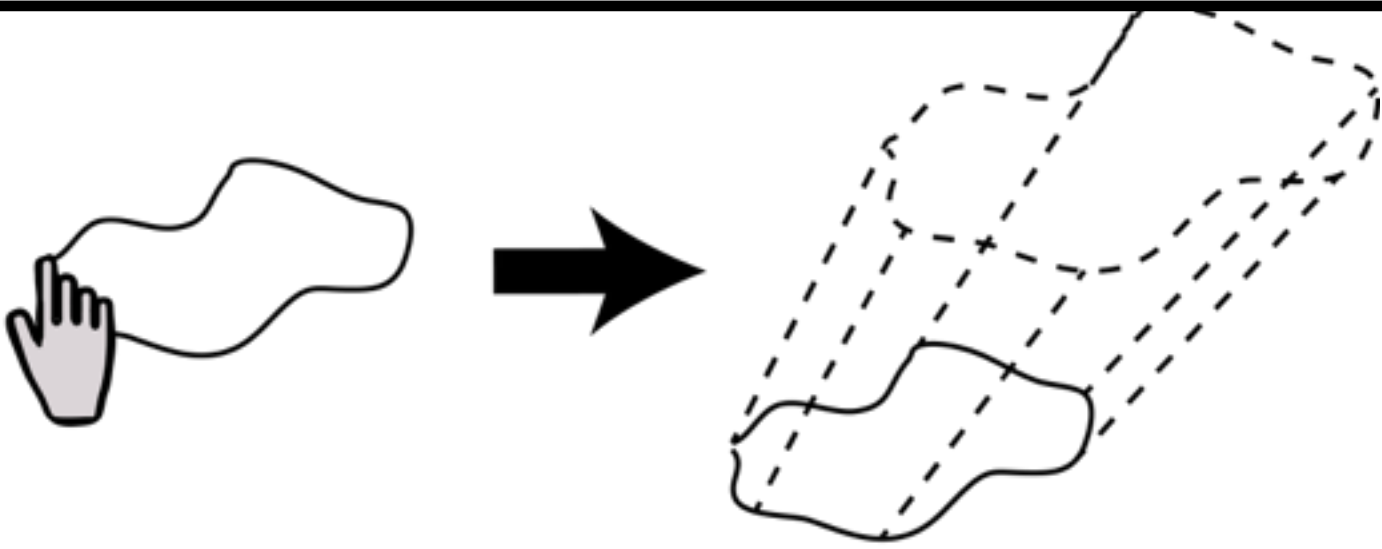
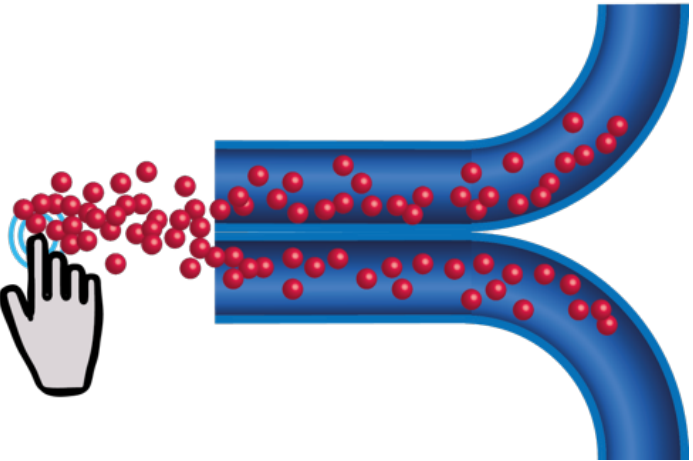
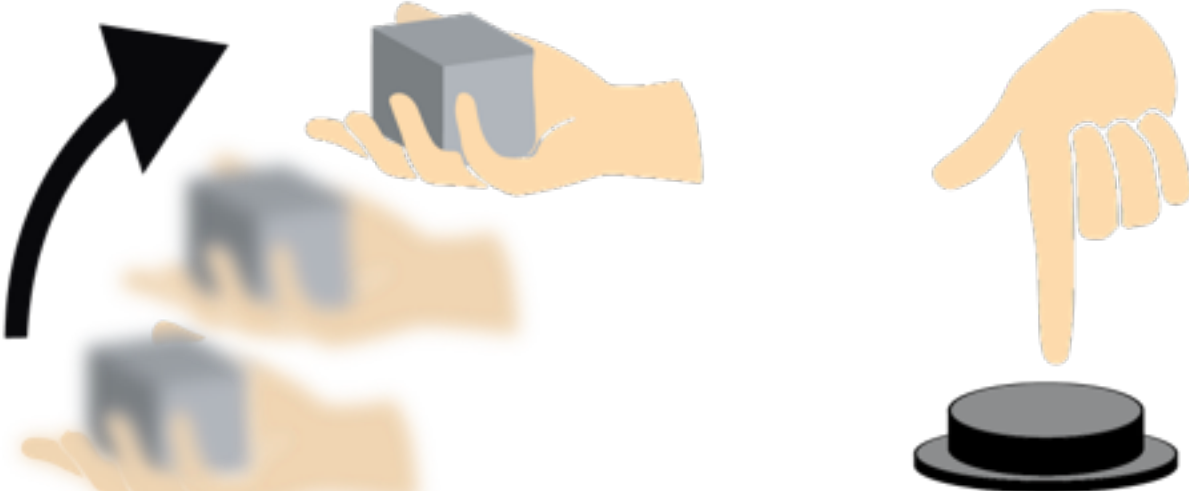
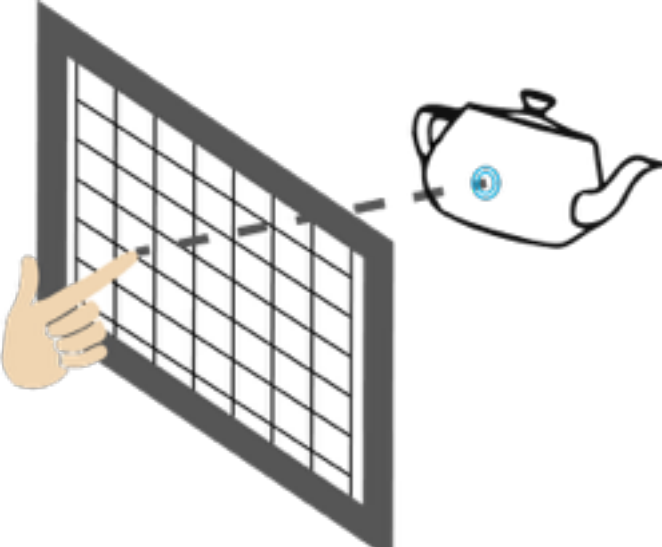
Tasks		
		
		
		



# Design Space Exploration: tactile-only and tangible-only settings

Tasks		
		
		
		

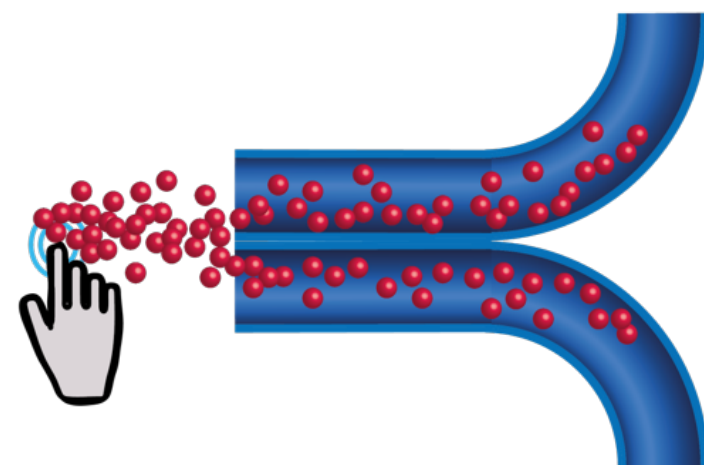
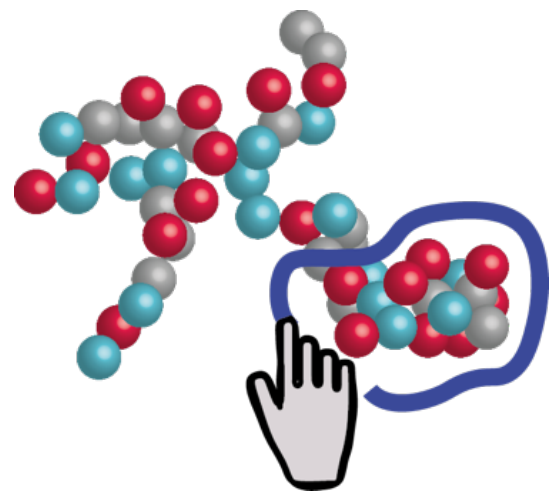
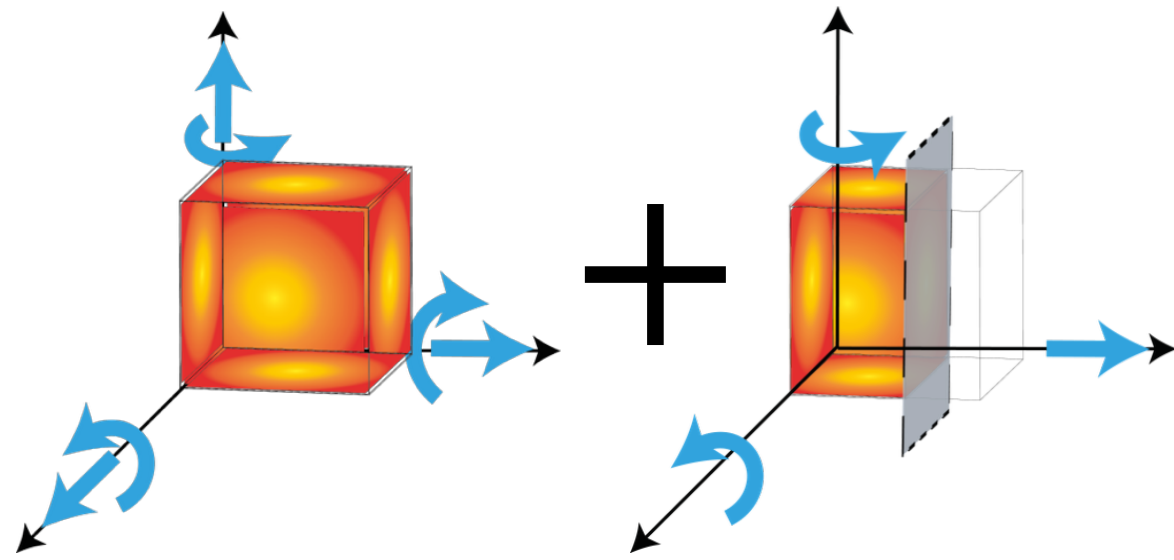
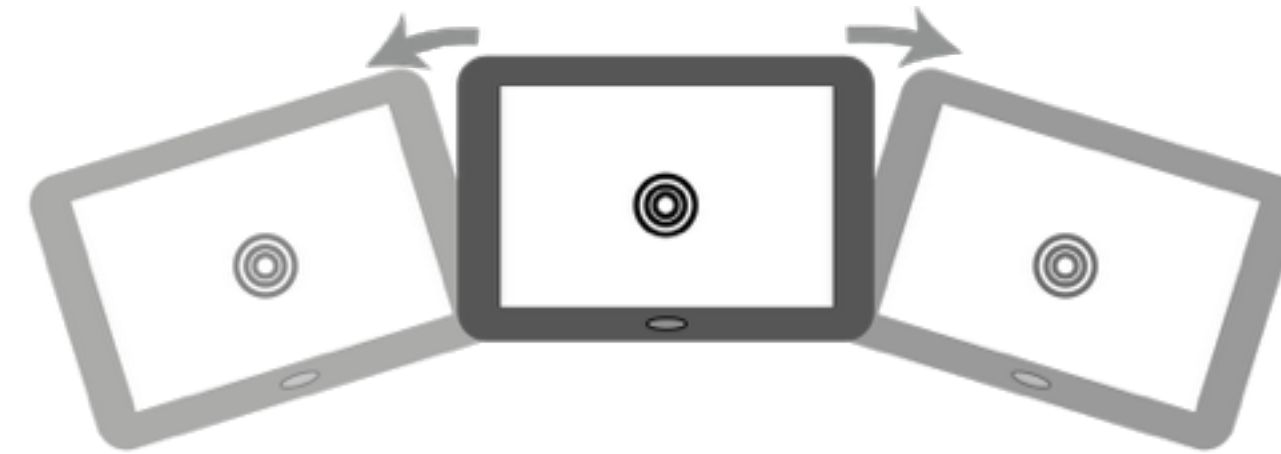
# Design Space Exploration: tactile-only and tangible-only settings

Tasks		
		
		
		



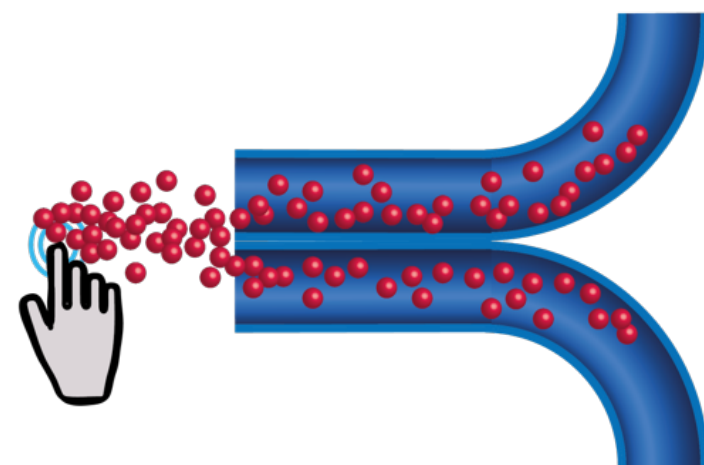
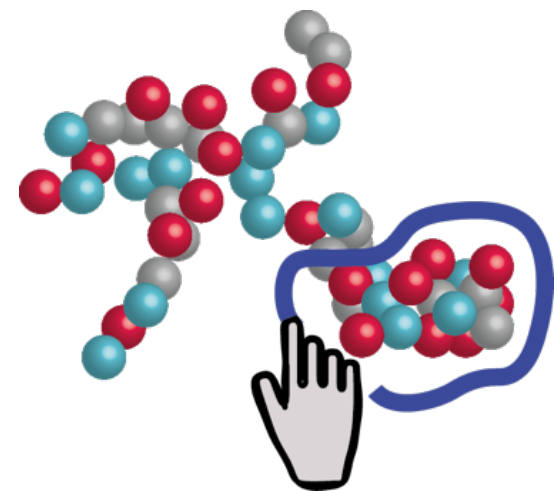
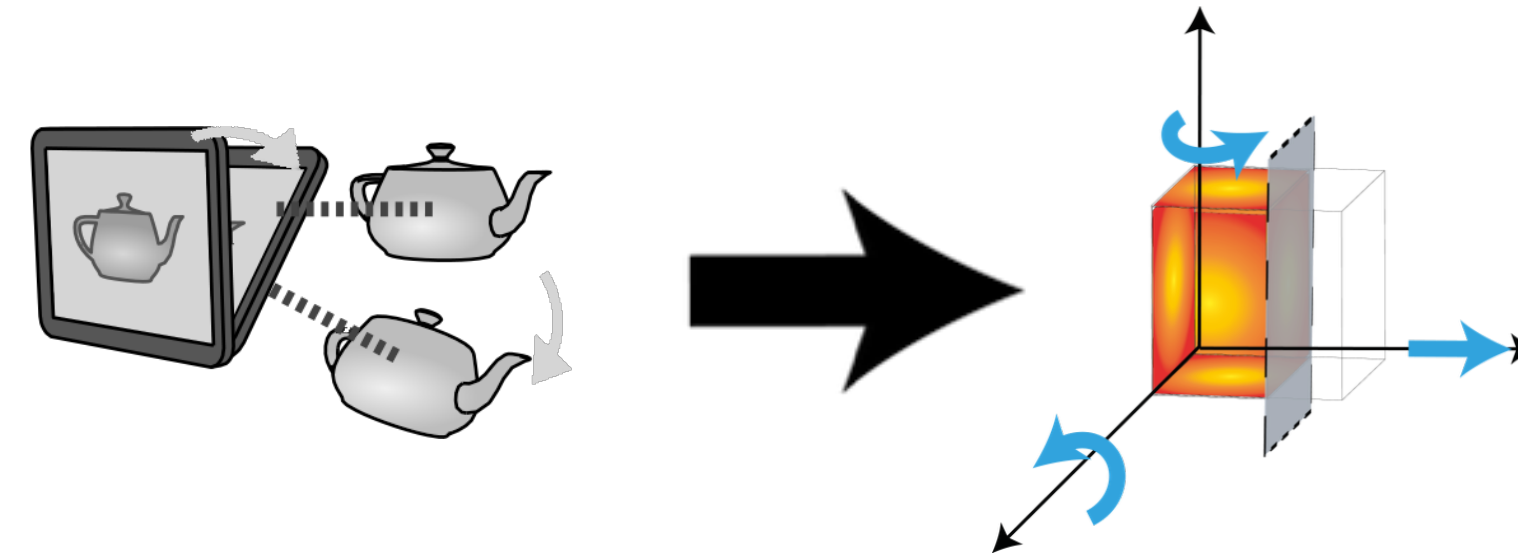
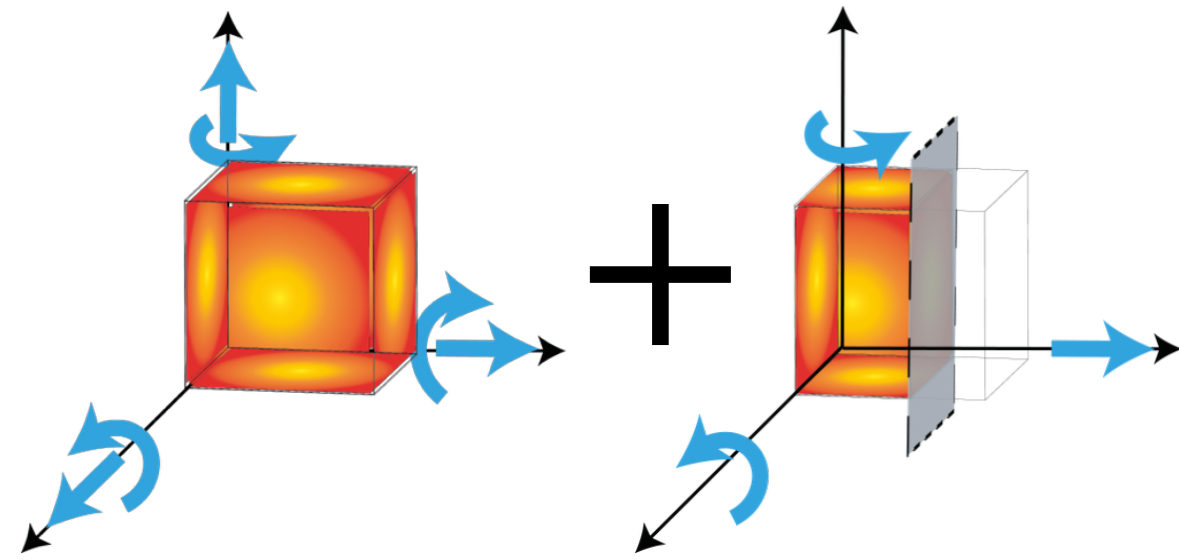
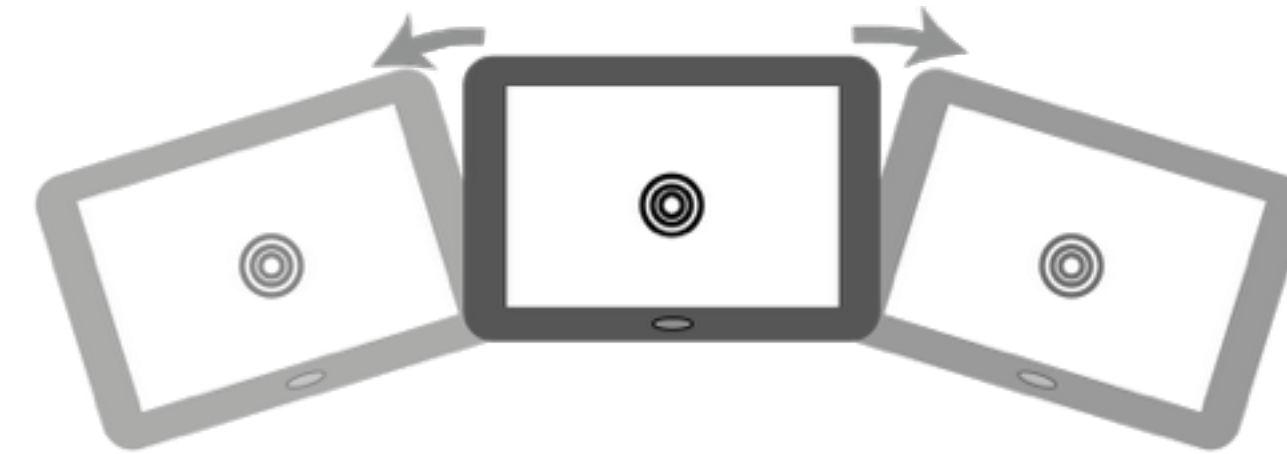
# Design Space Exploration: Hybrid interaction

Tasks

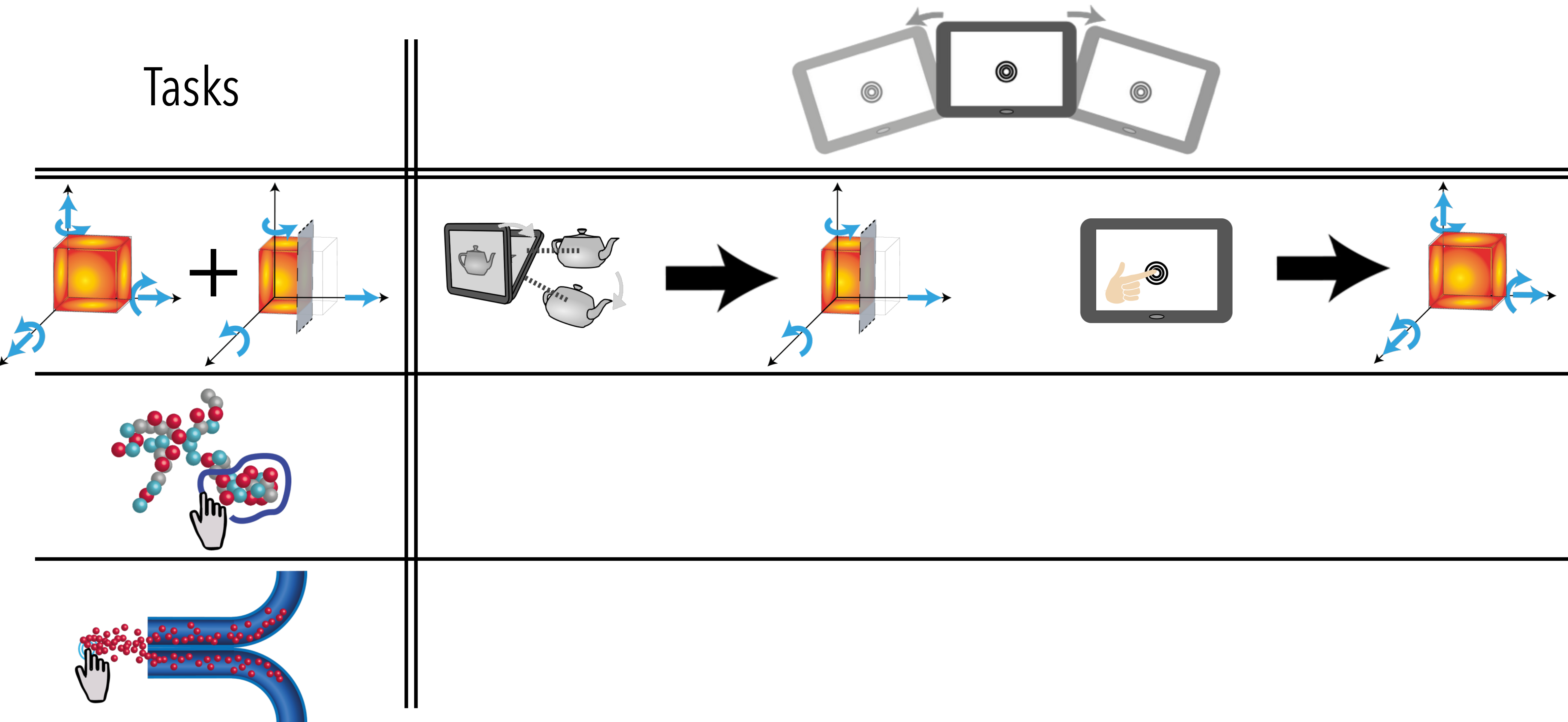


# Design Space Exploration: Hybrid interaction

Tasks

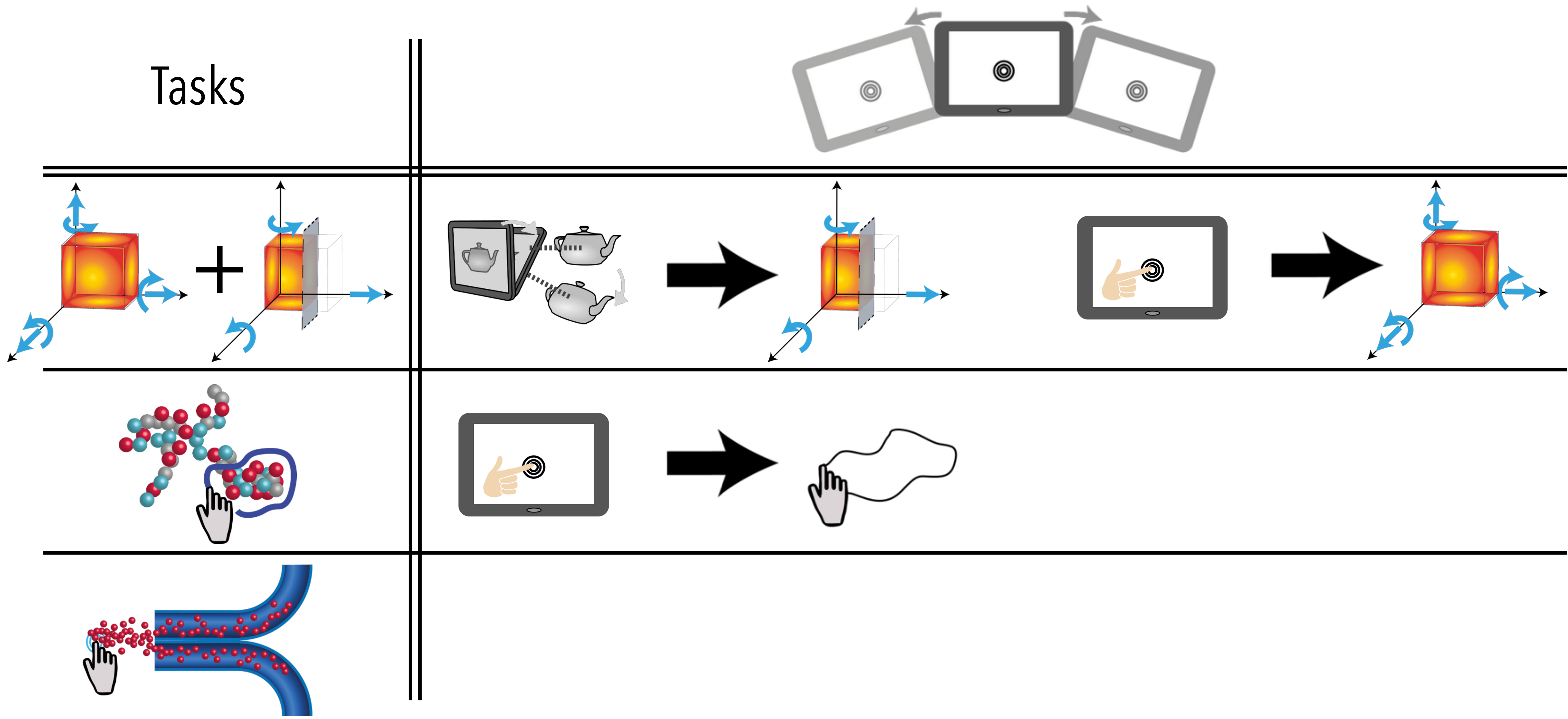


# Design Space Exploration: Hybrid interaction

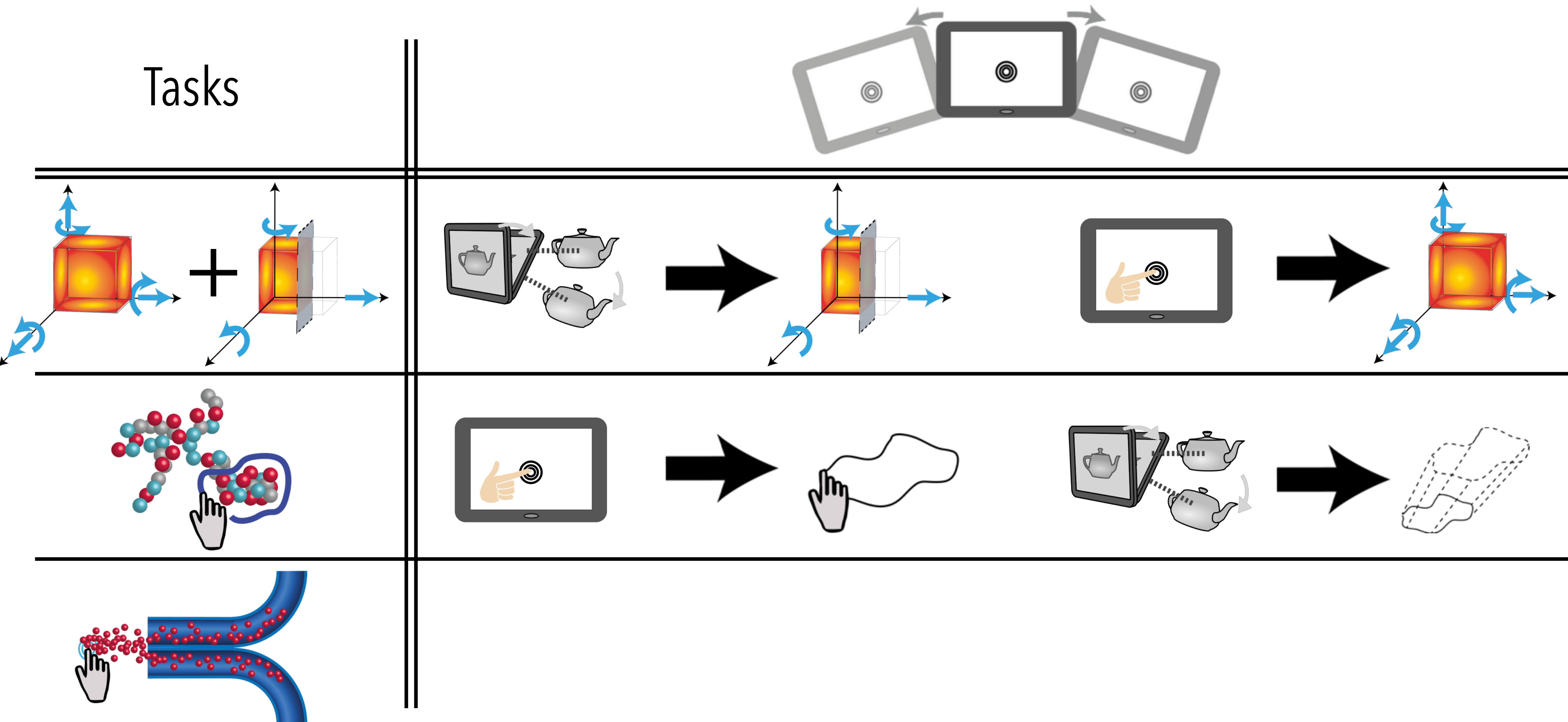




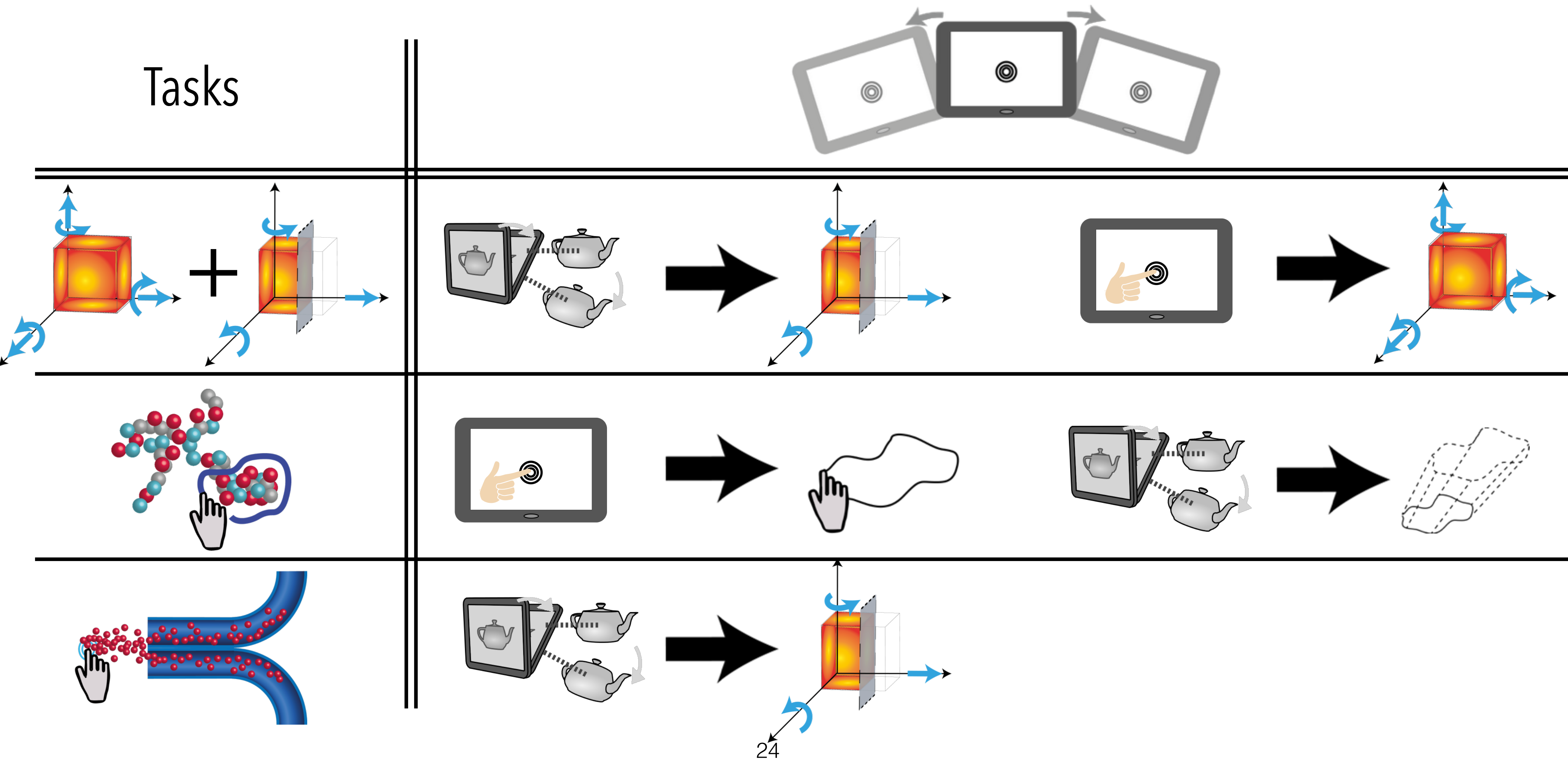
# Design Space Exploration: Hybrid interaction



# Design Space Exploration: Hybrid interaction

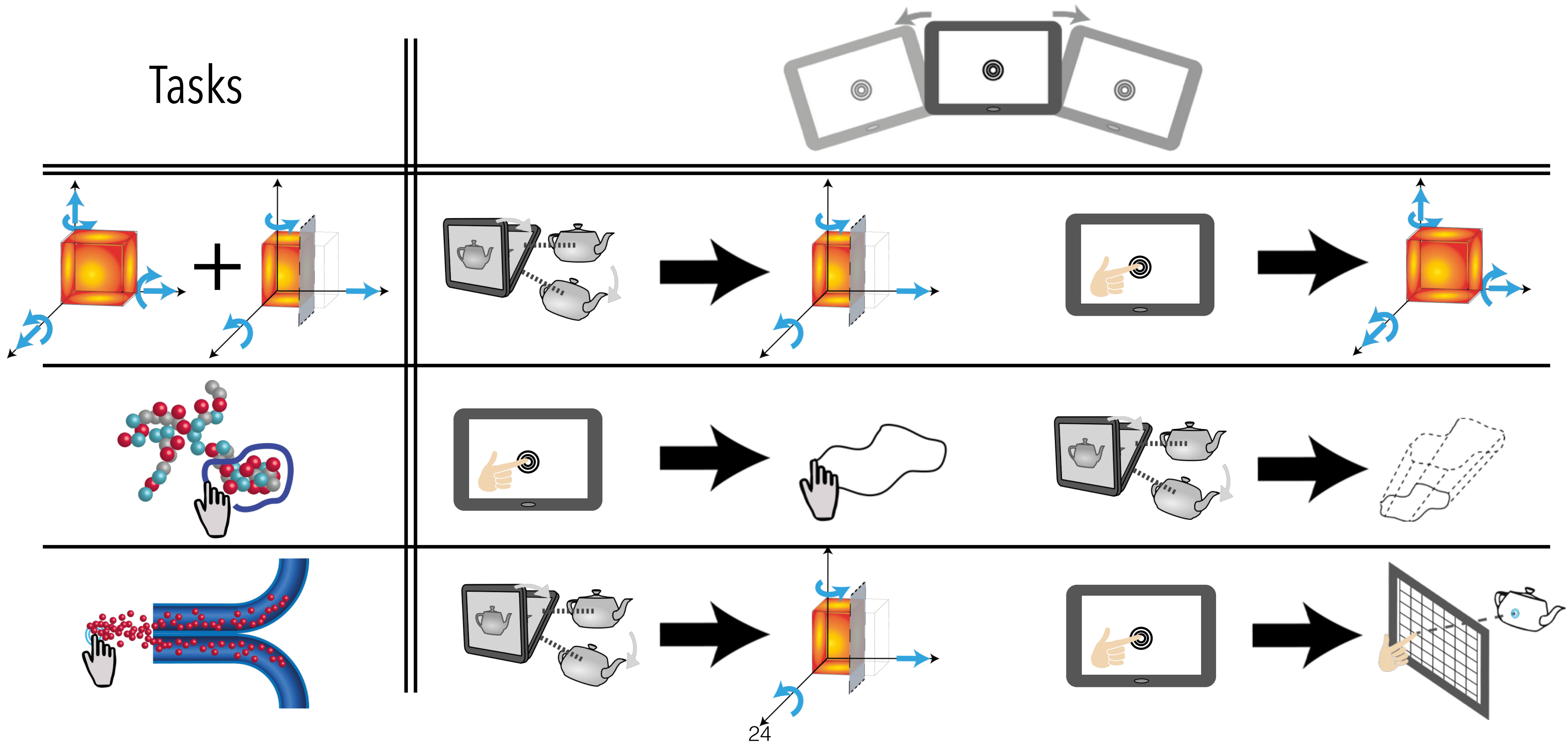


# Design Space Exploration: Hybrid interaction



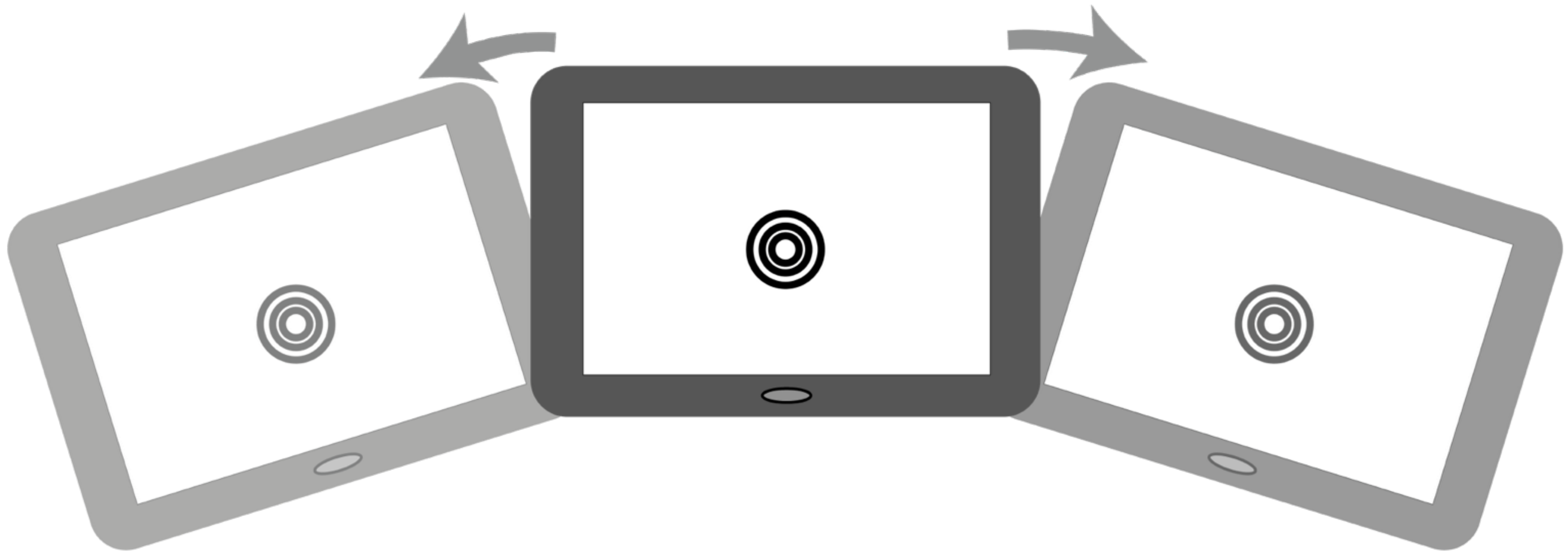


# Design Space Exploration: Hybrid interaction



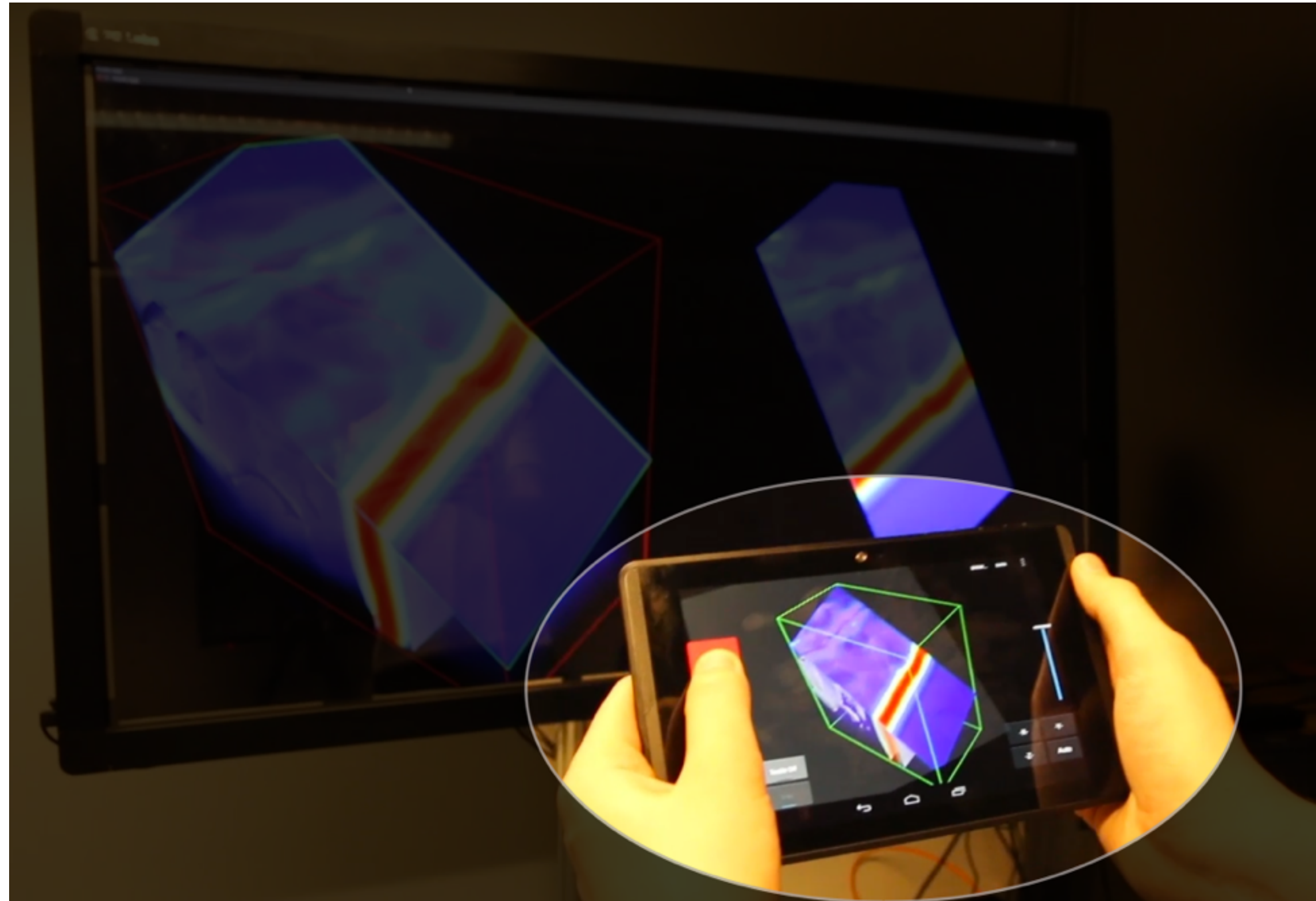
**Contribution #3:**  
**Hybrid interaction prototype and user study**

# Prototype

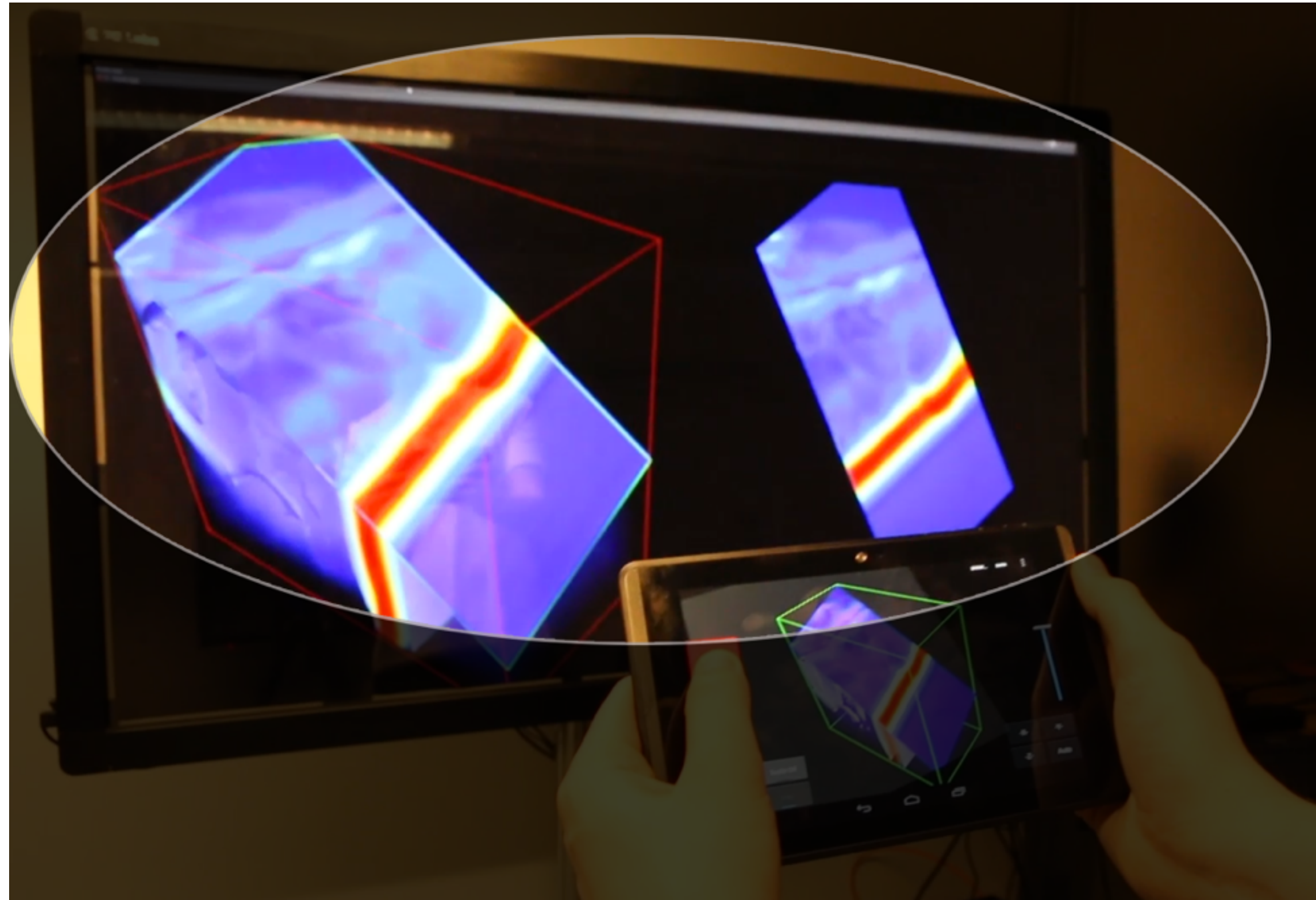




# Prototype

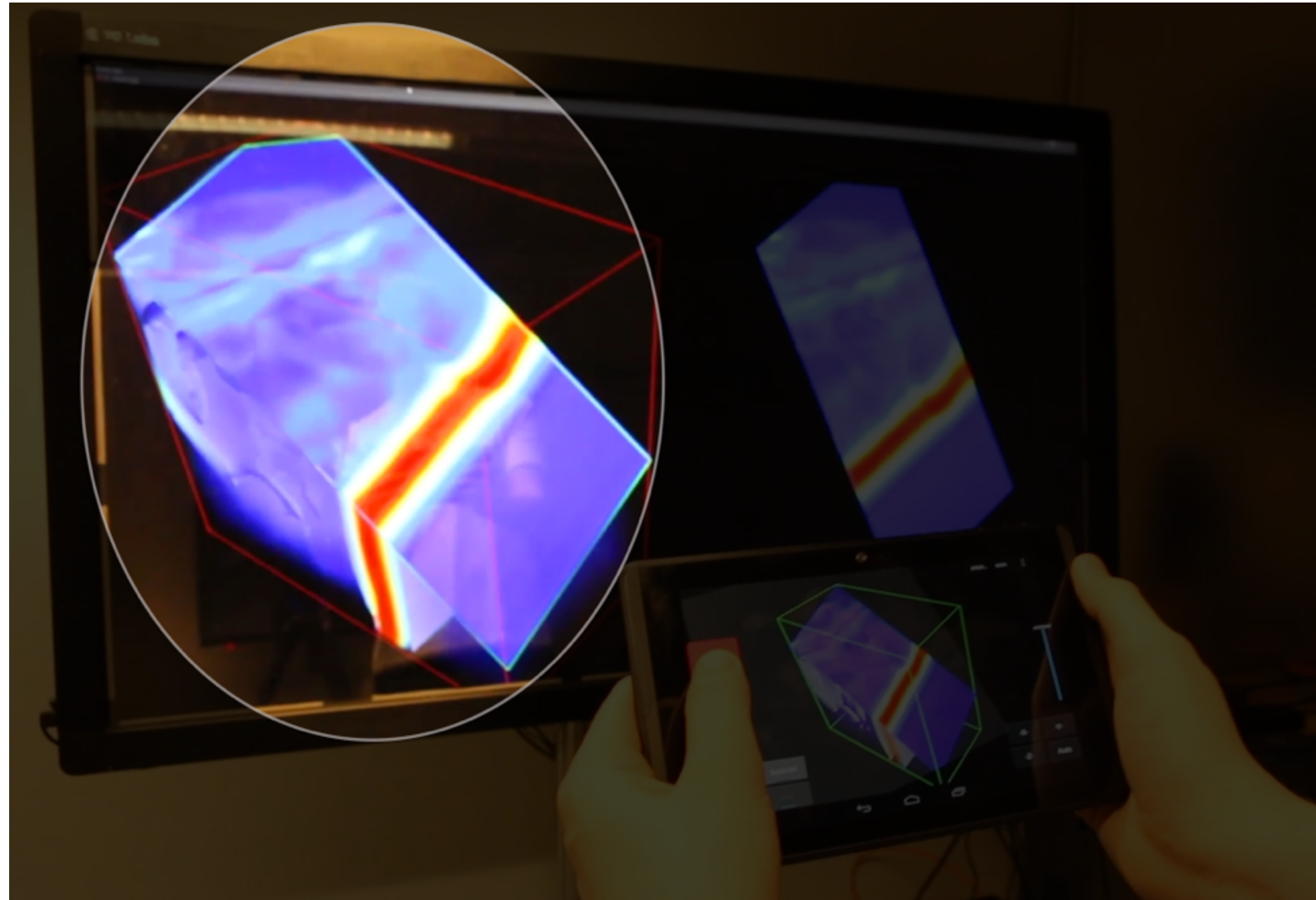


# Prototype



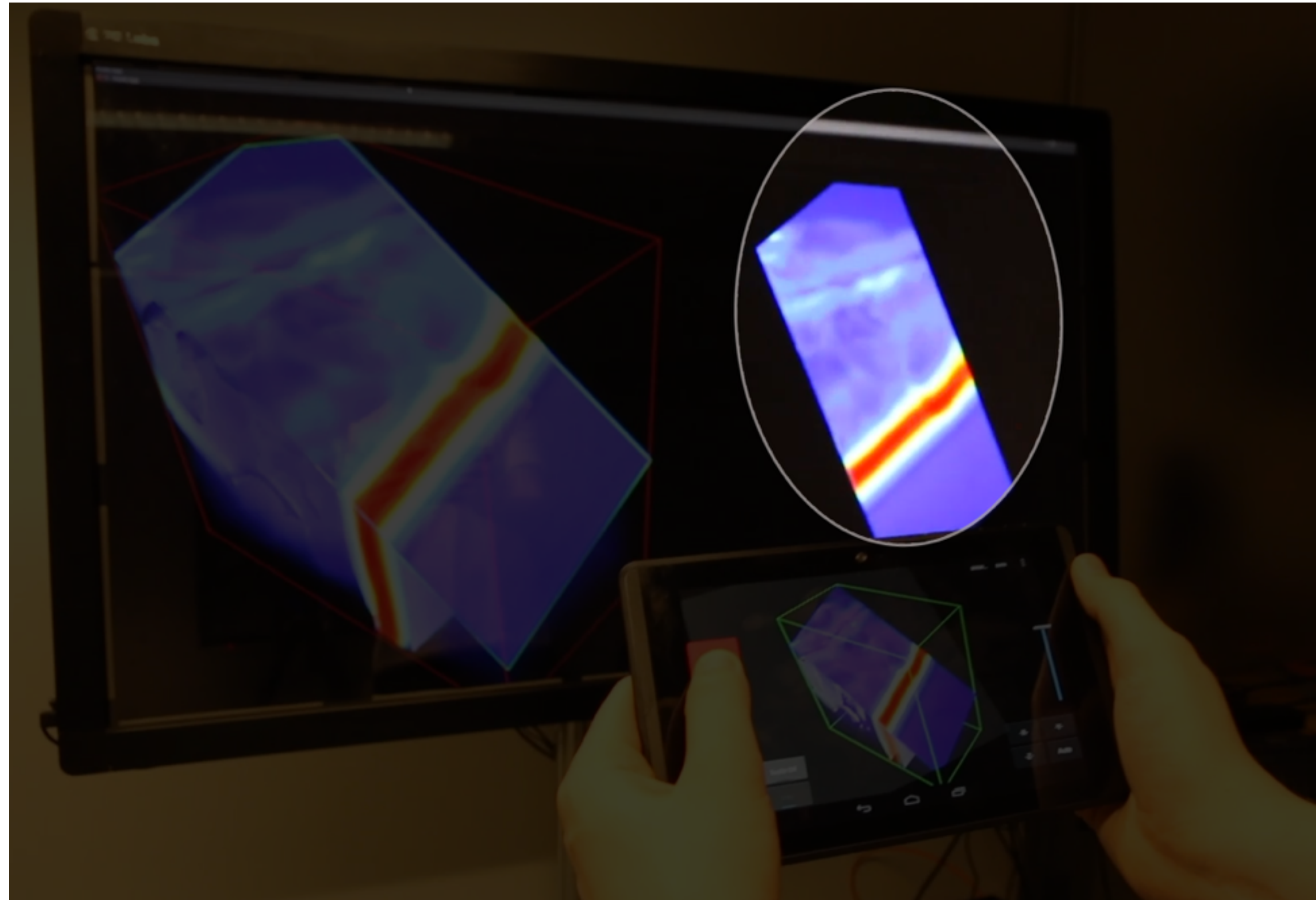


# Prototype

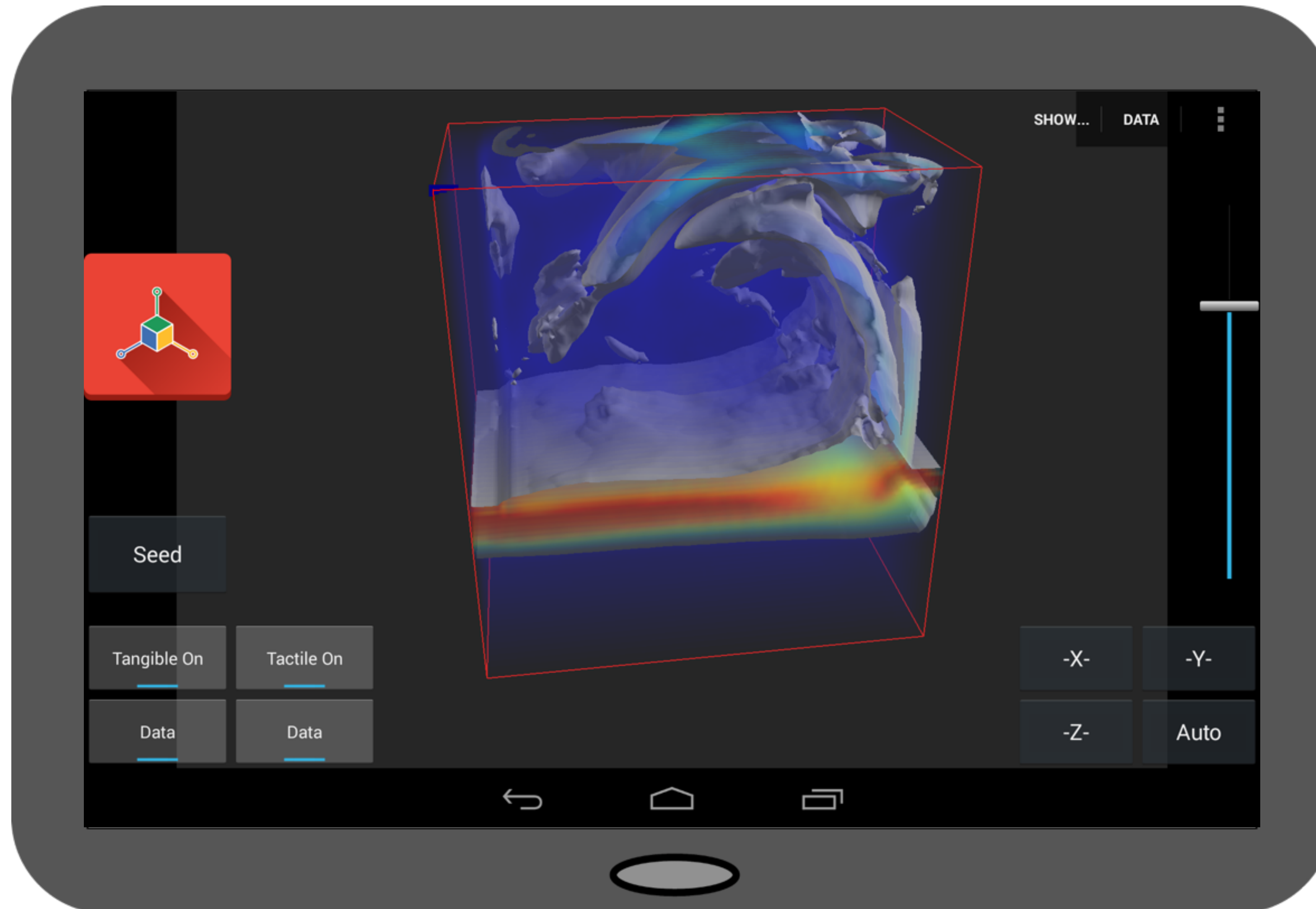




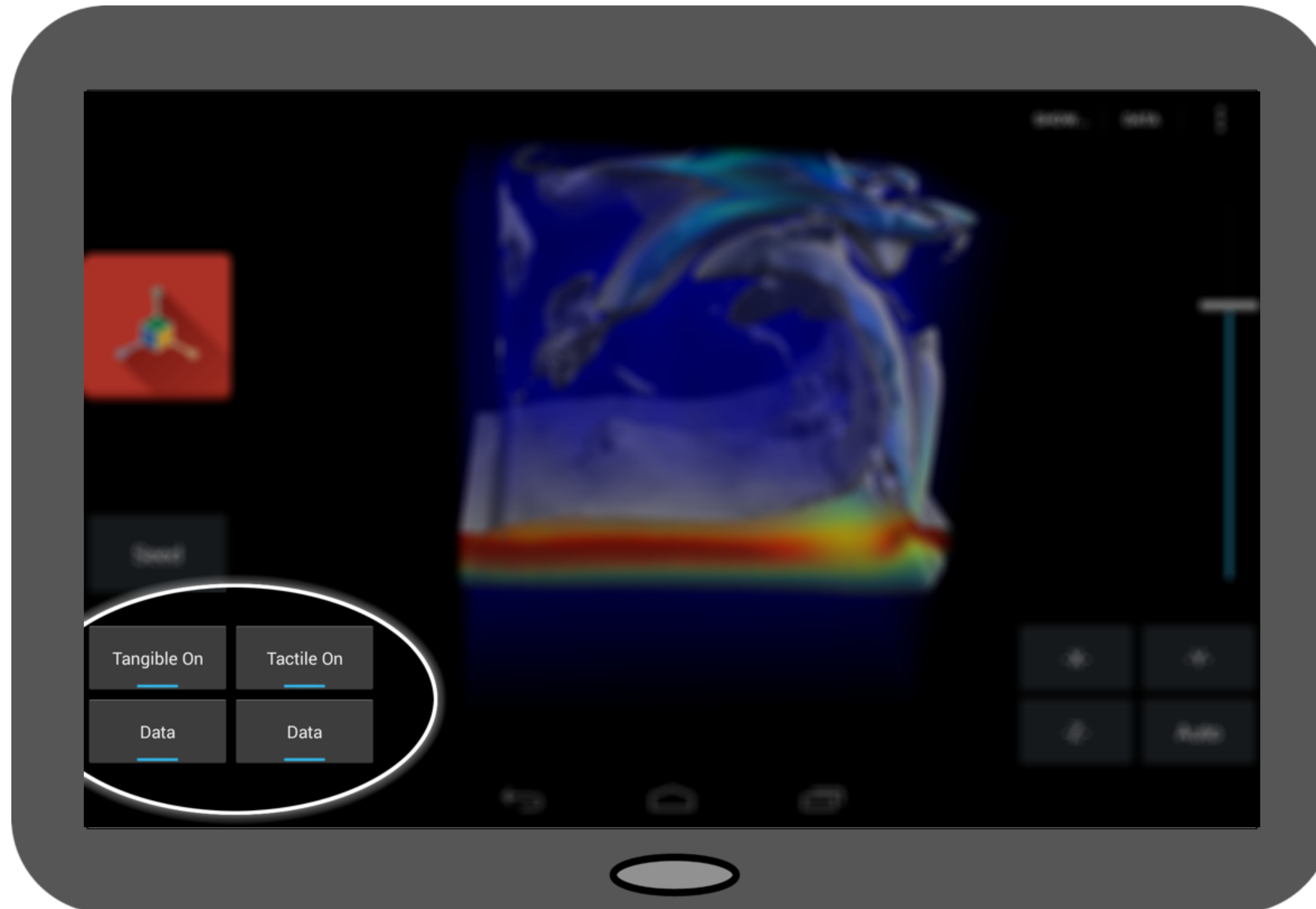
# Prototype



# User Interface

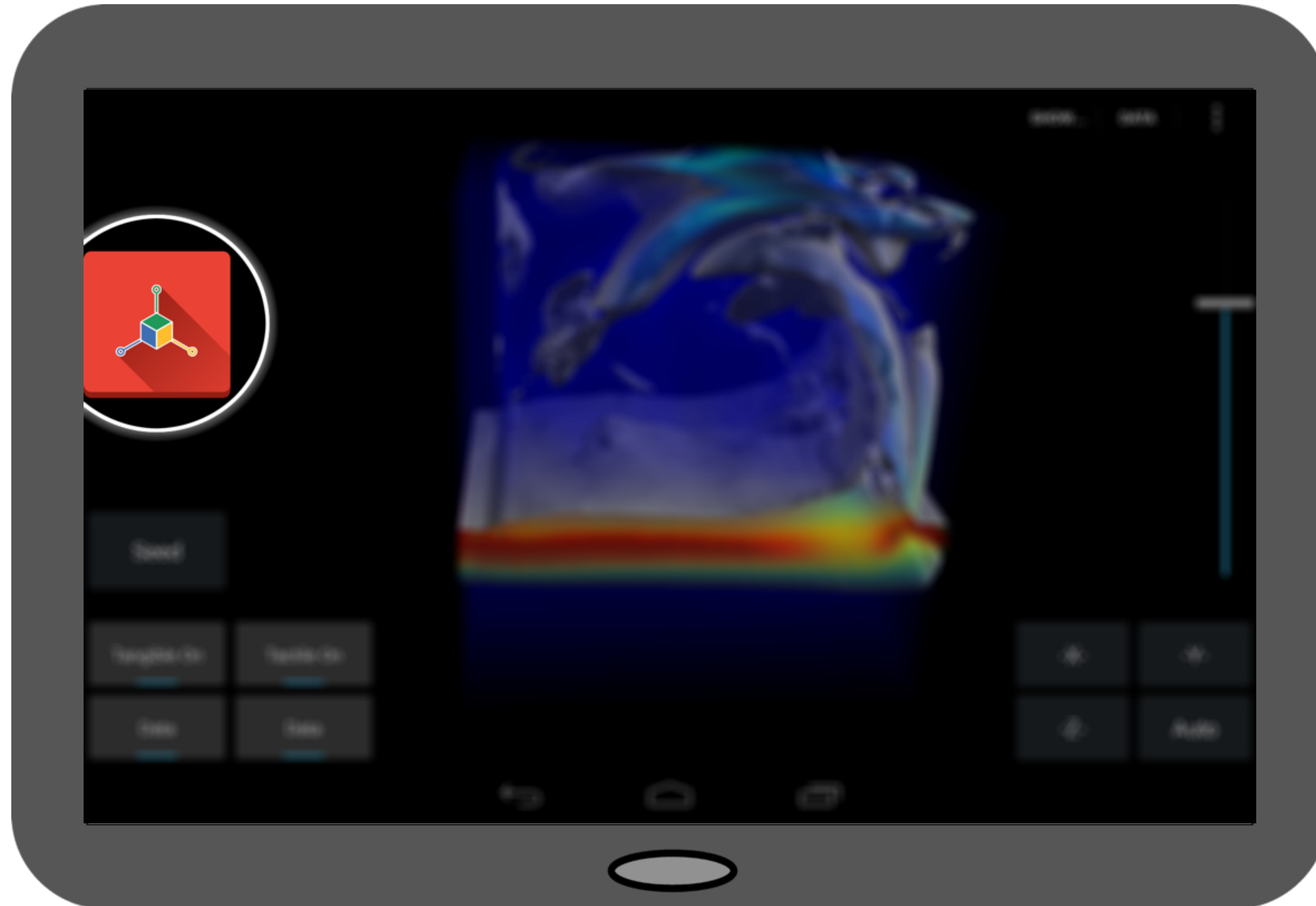


# User Interface

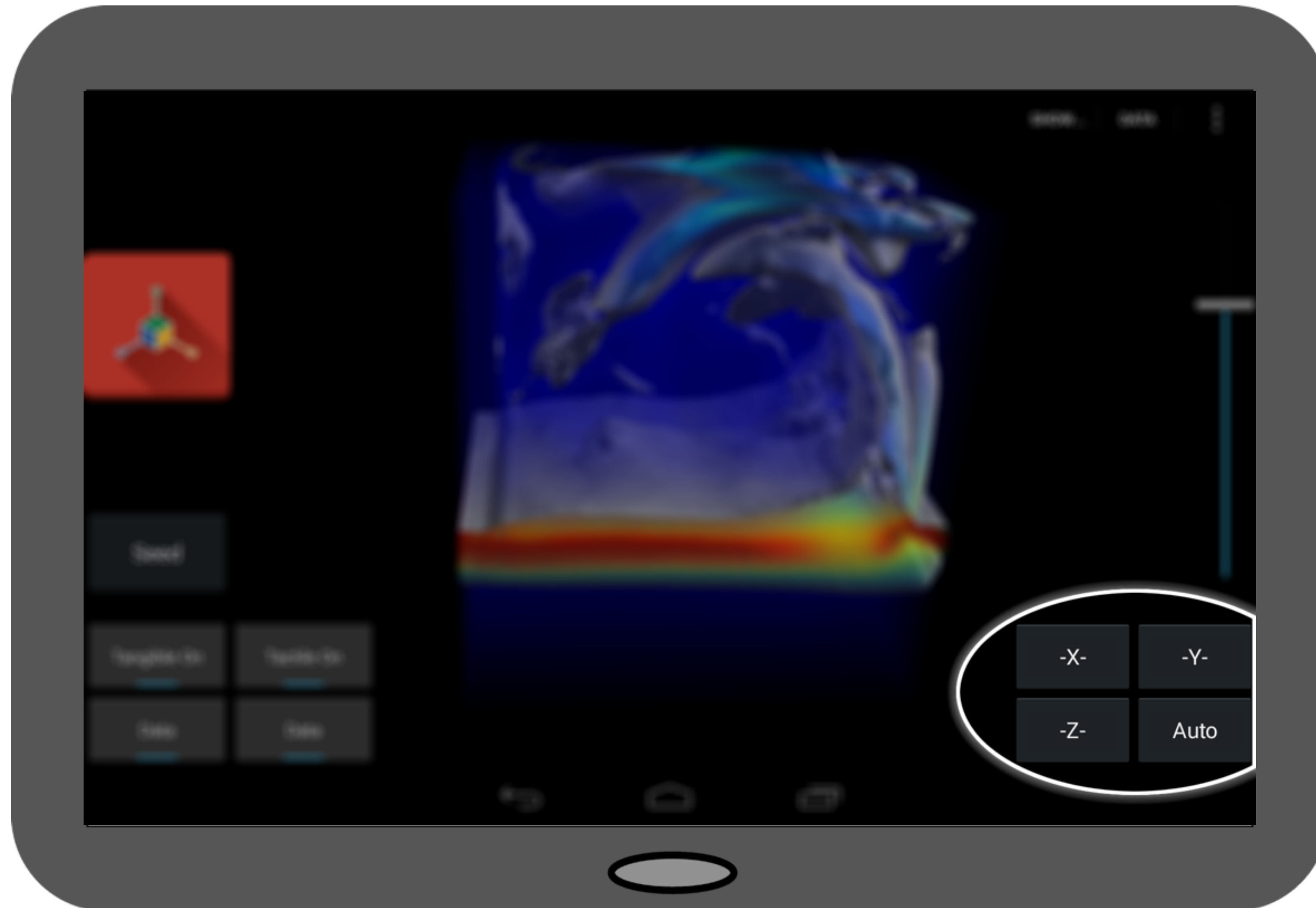




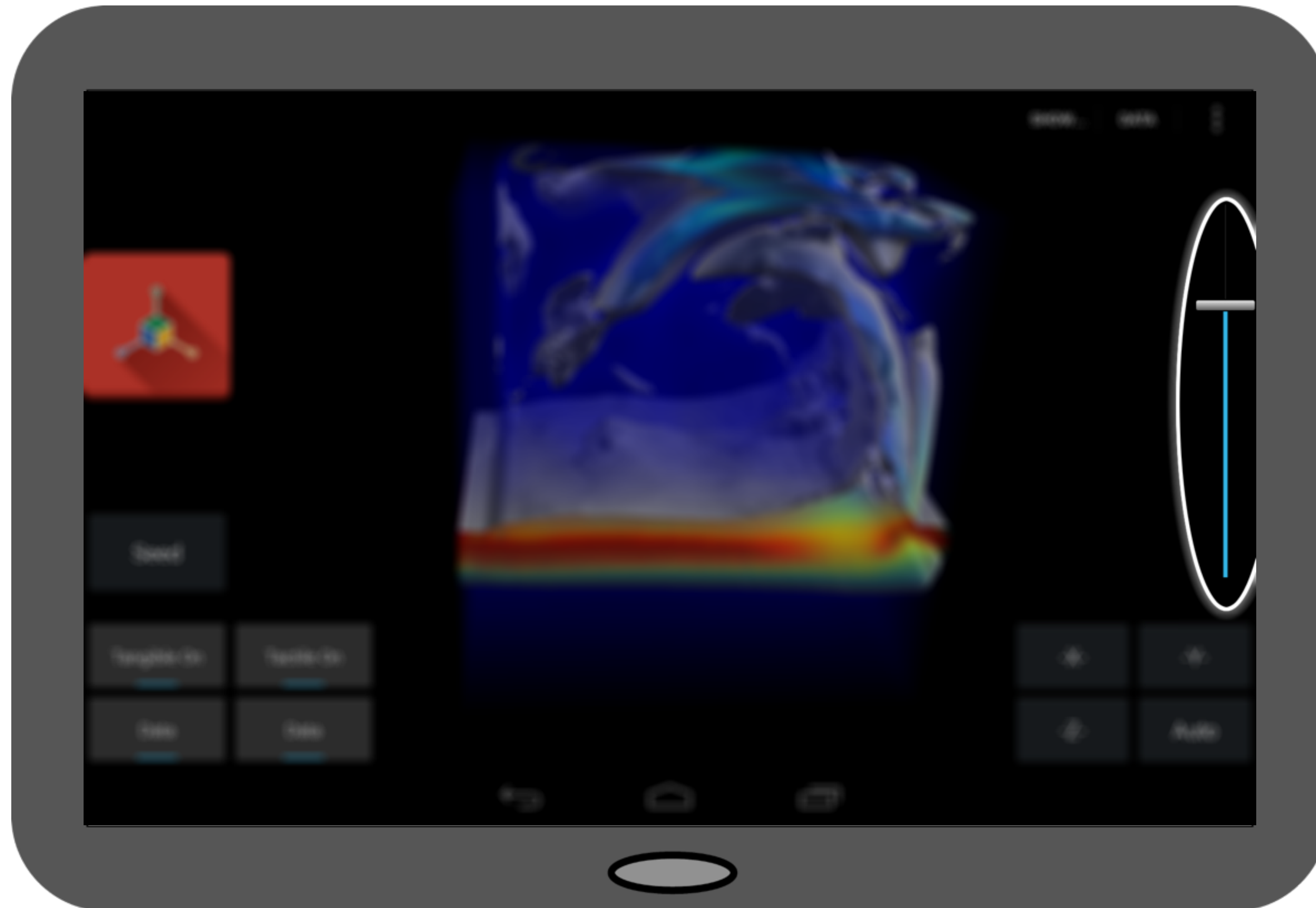
# User Interface



# User Interface



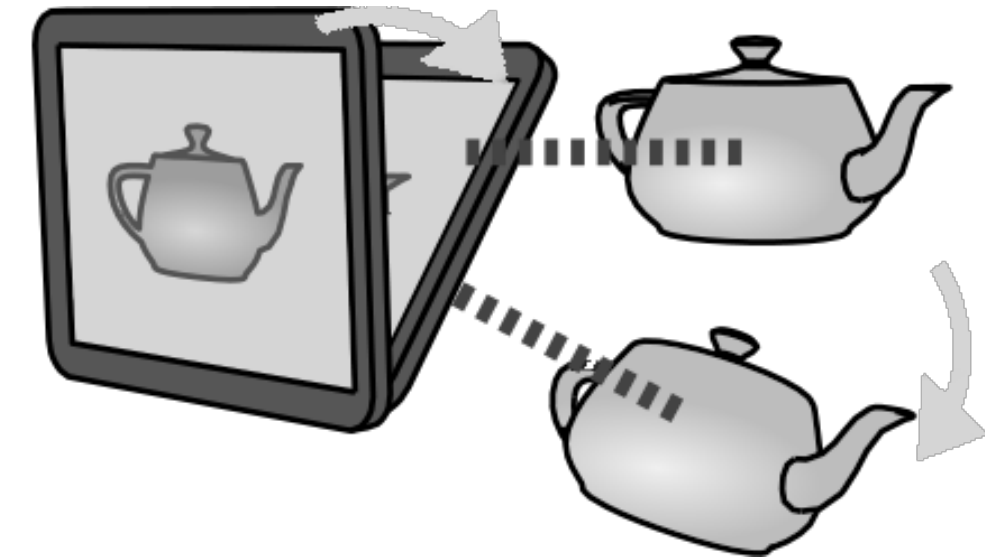
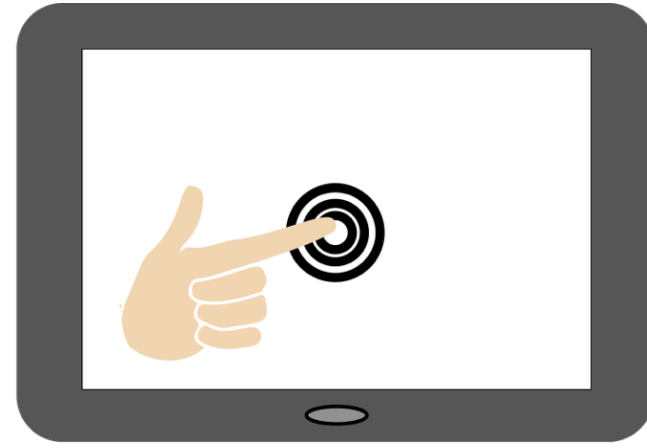
# User Interface



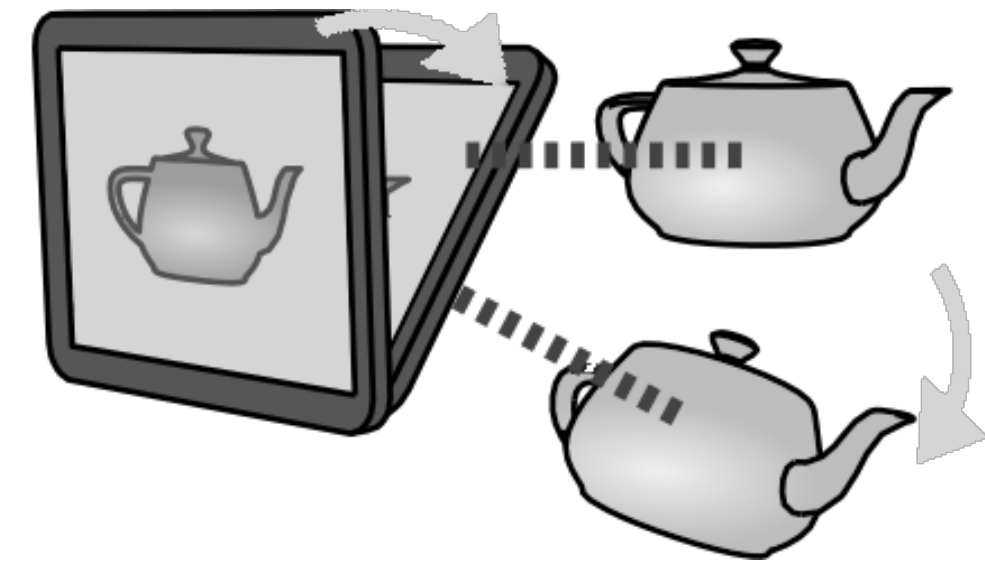
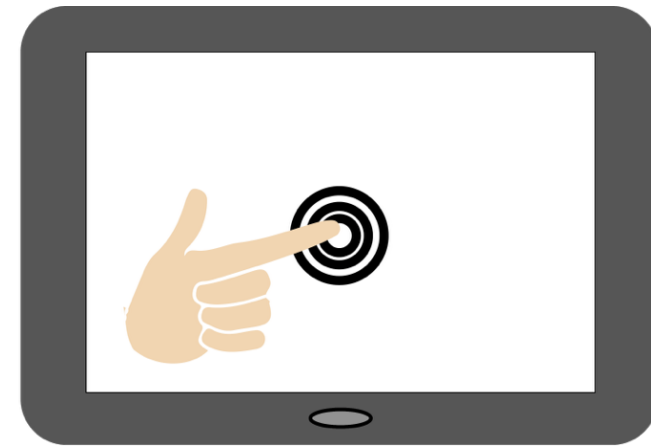


# 3D data space navigation

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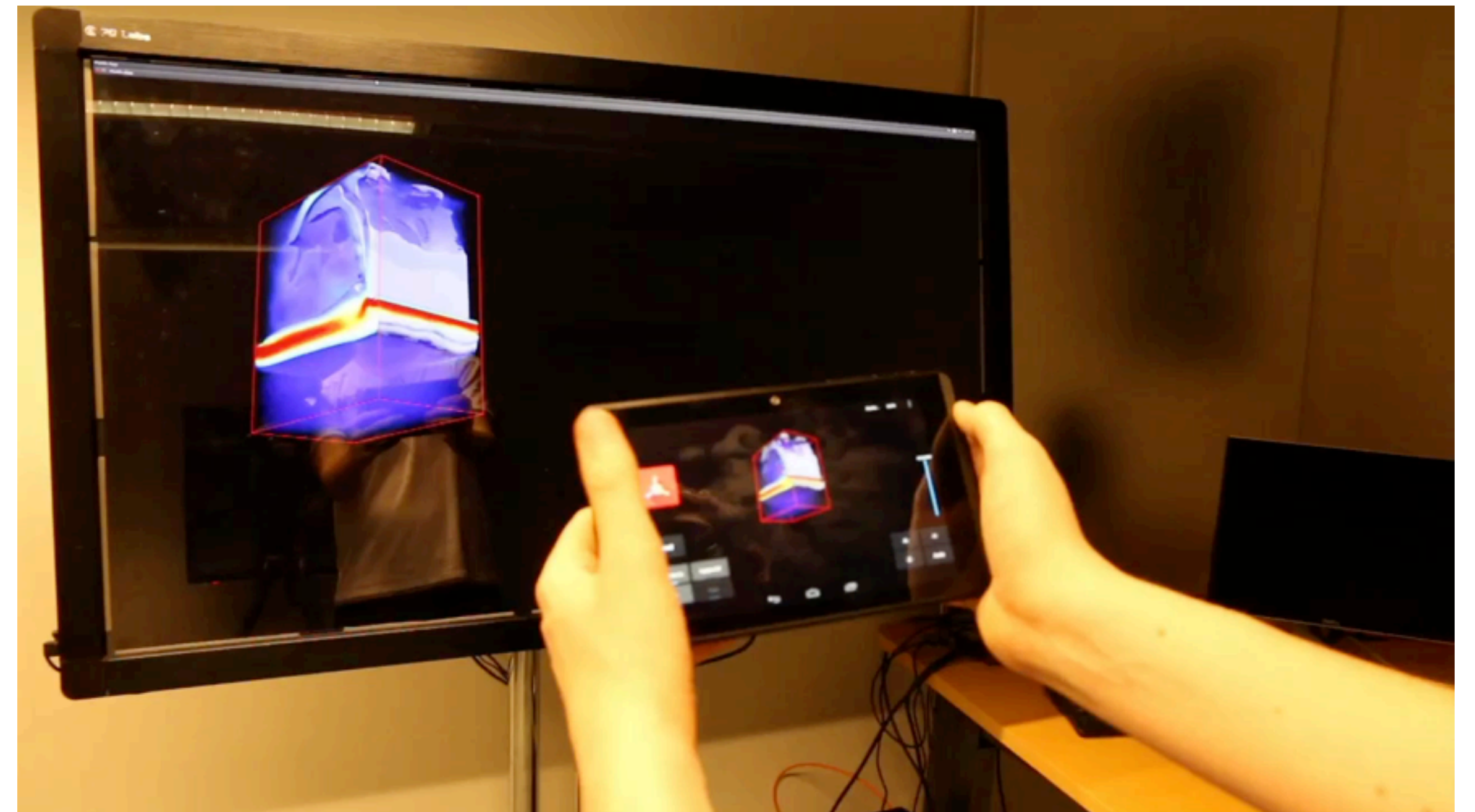
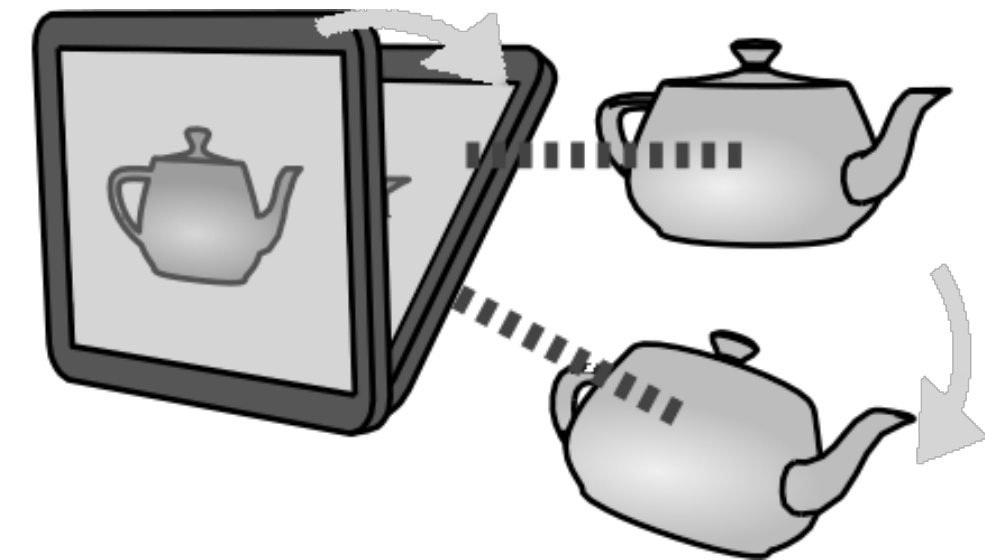
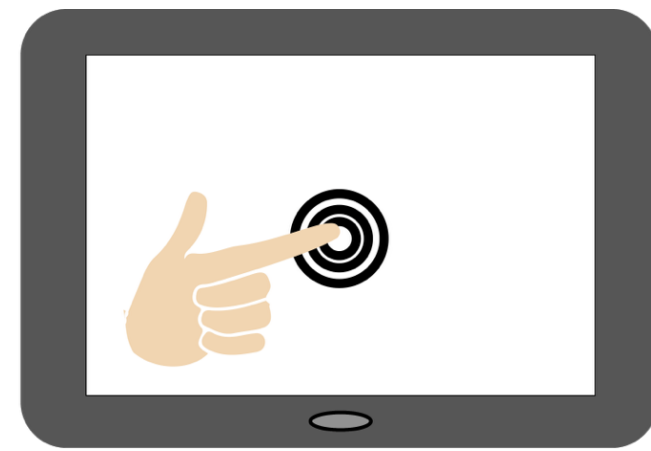


# 3D data space navigation

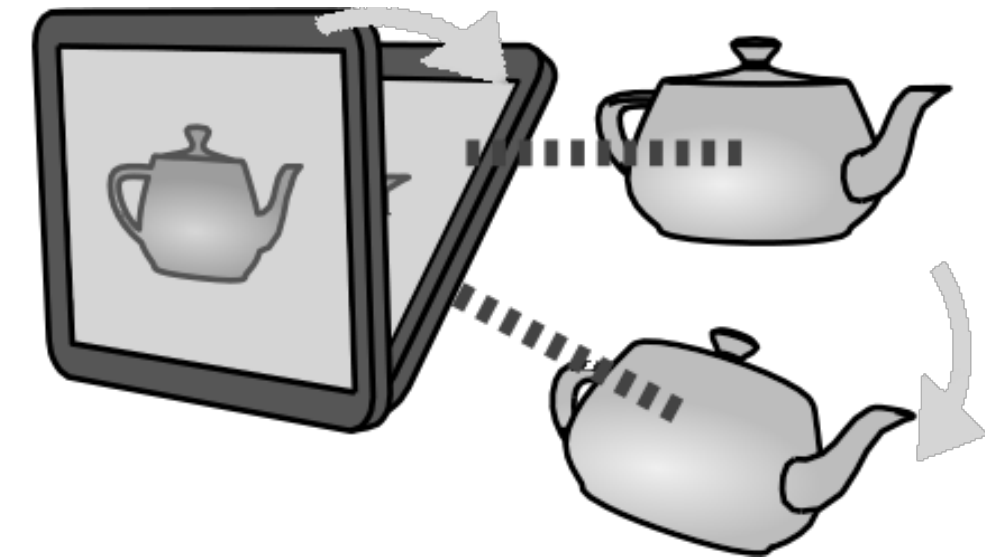
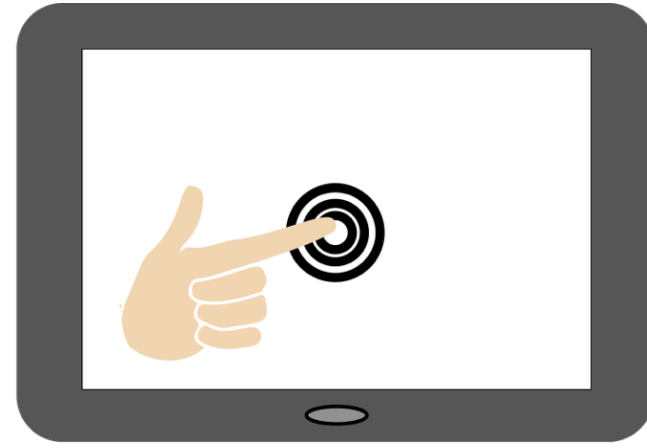




# 3D data space navigation

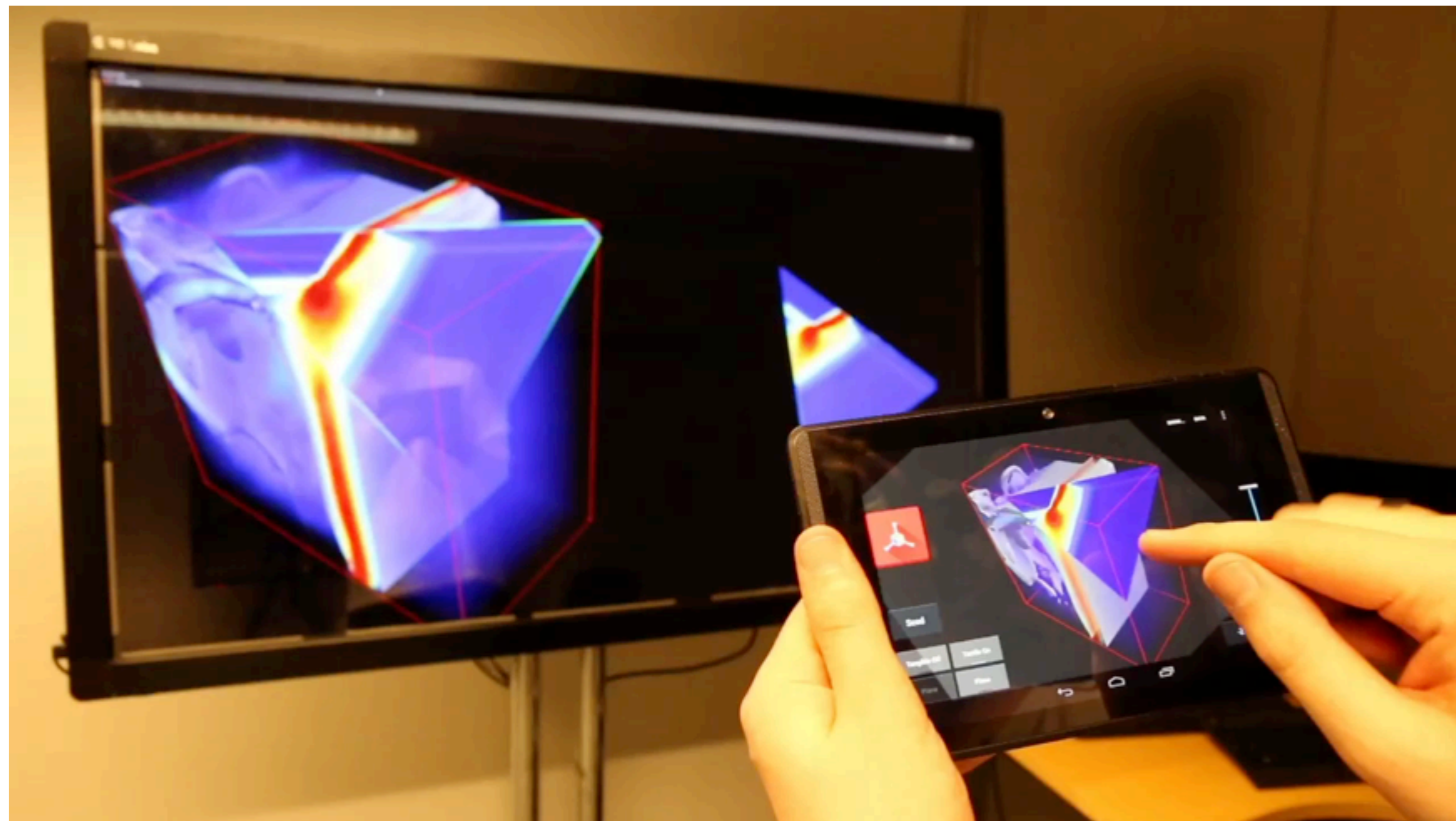
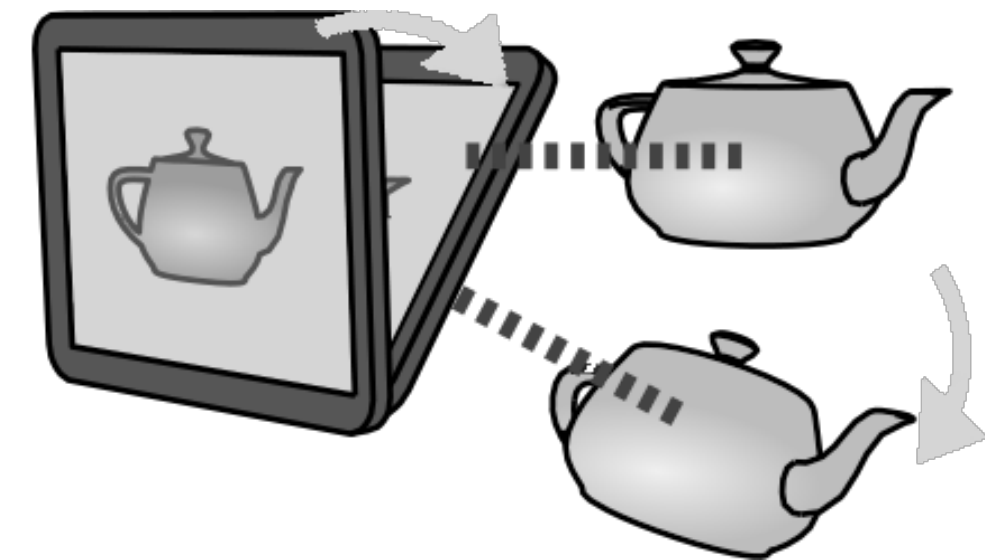
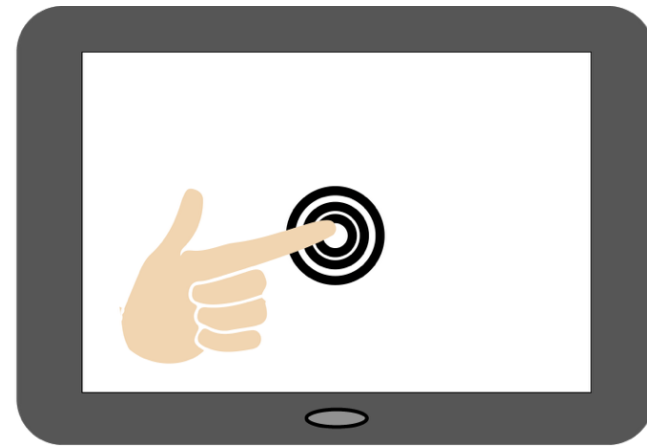


# 3D cutting plane manipulations



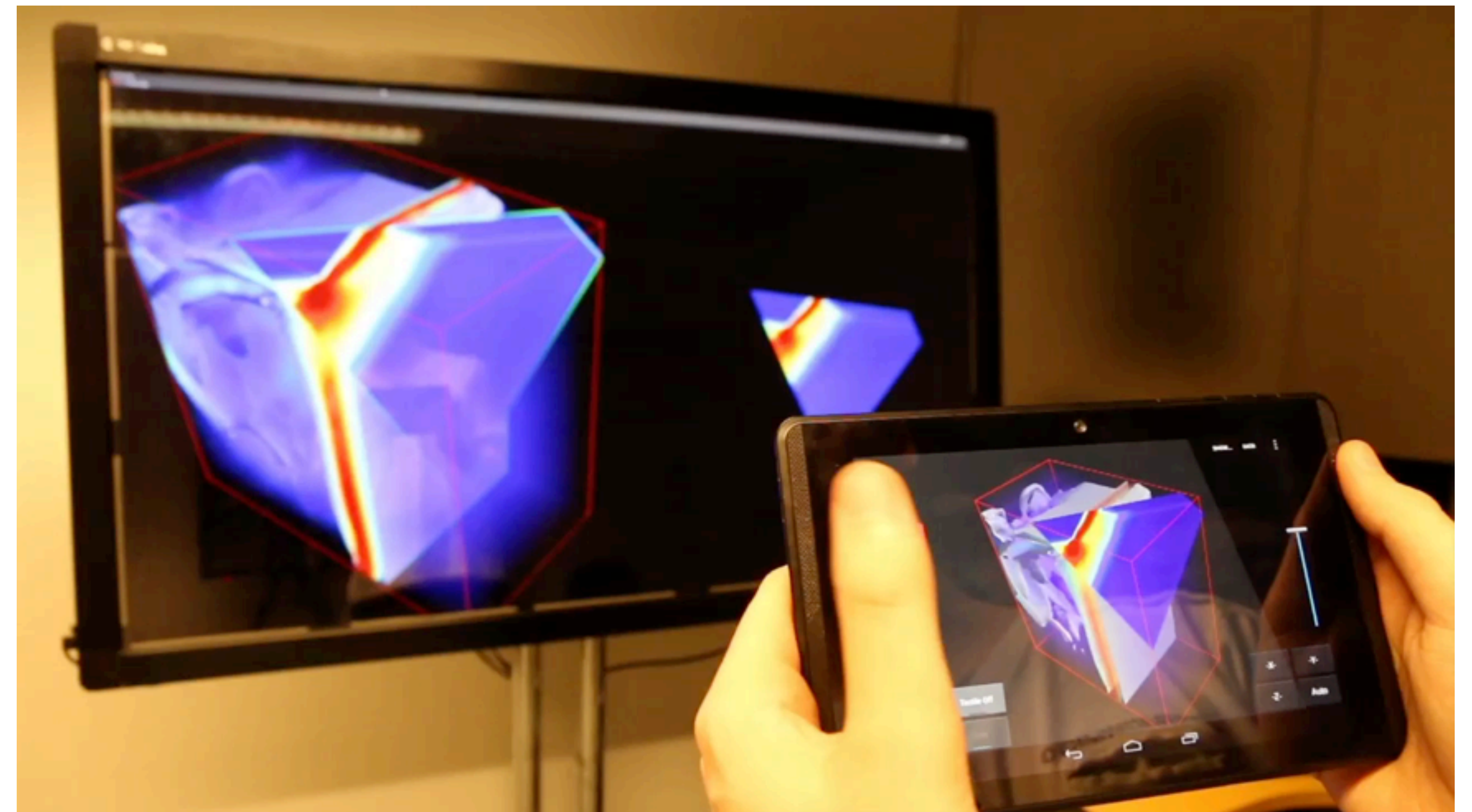
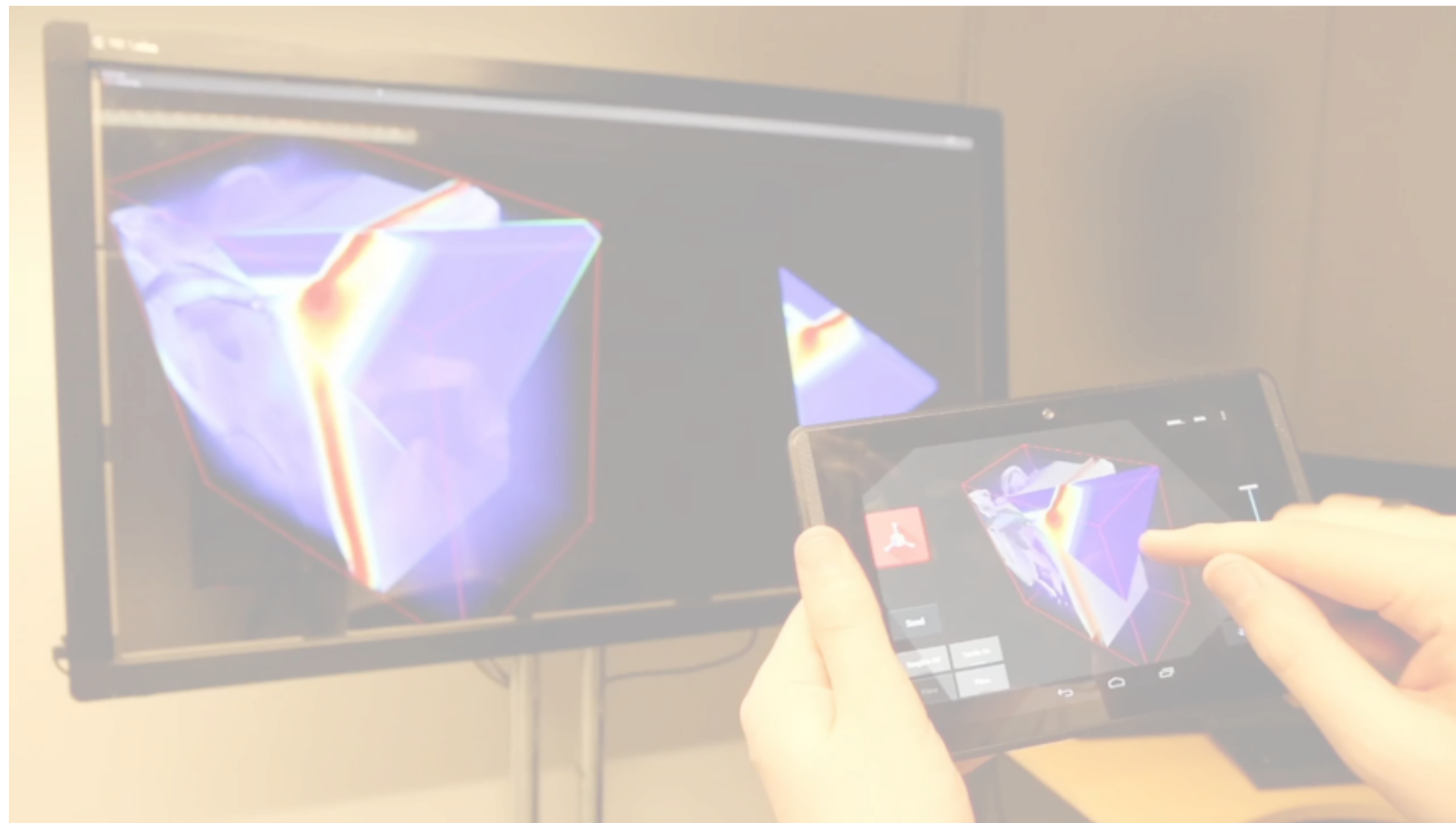
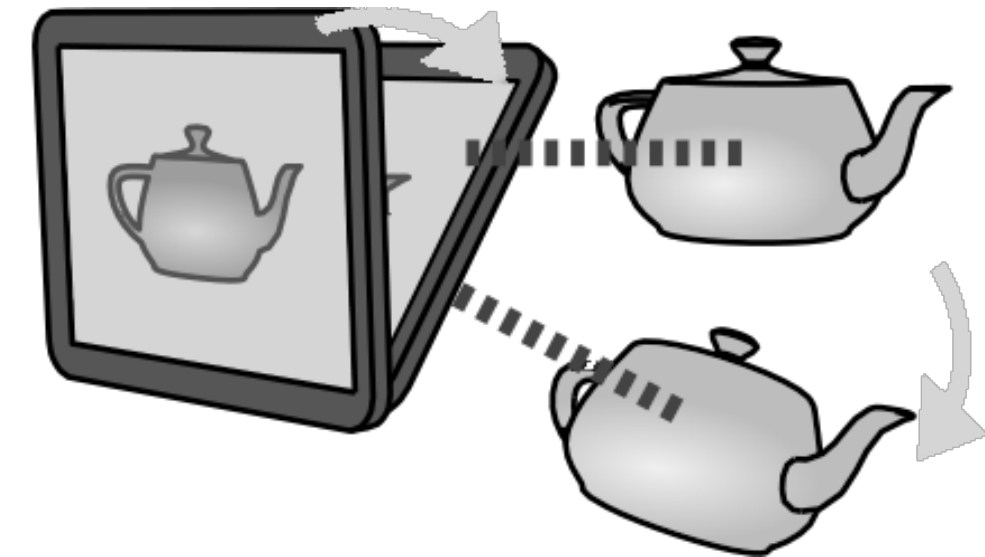
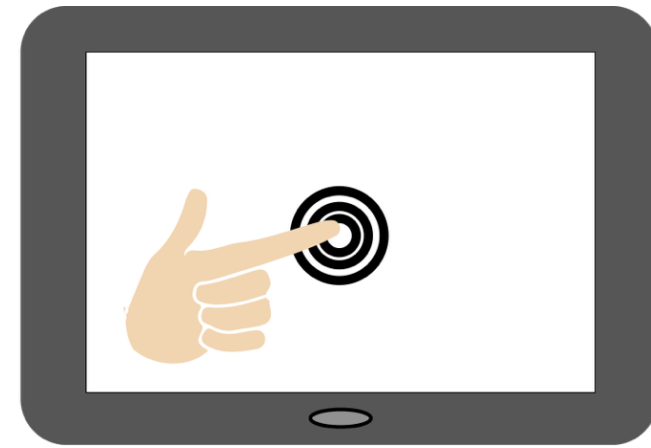


# 3D cutting plane manipulations

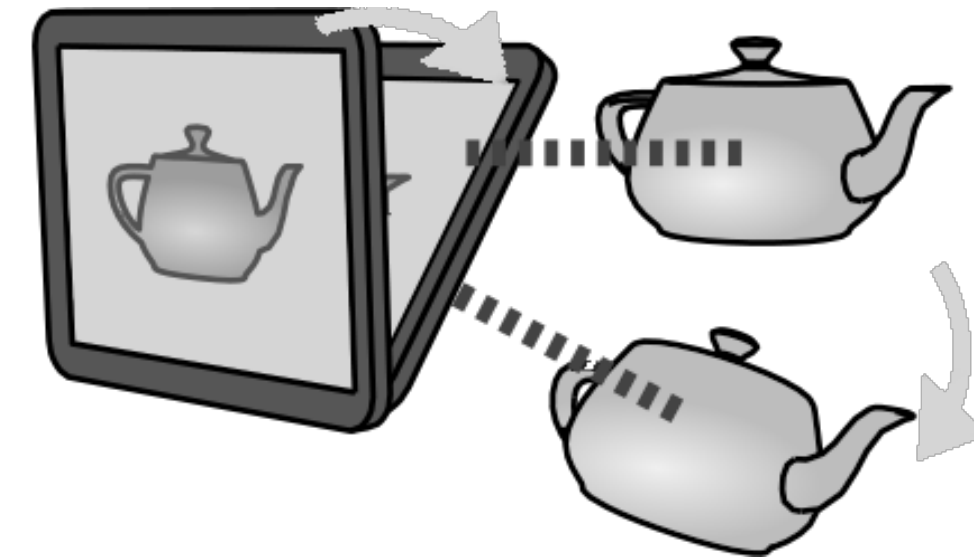
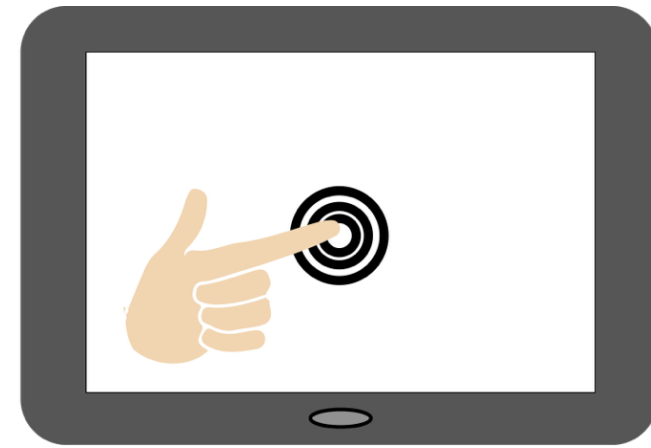




# 3D cutting plane manipulations

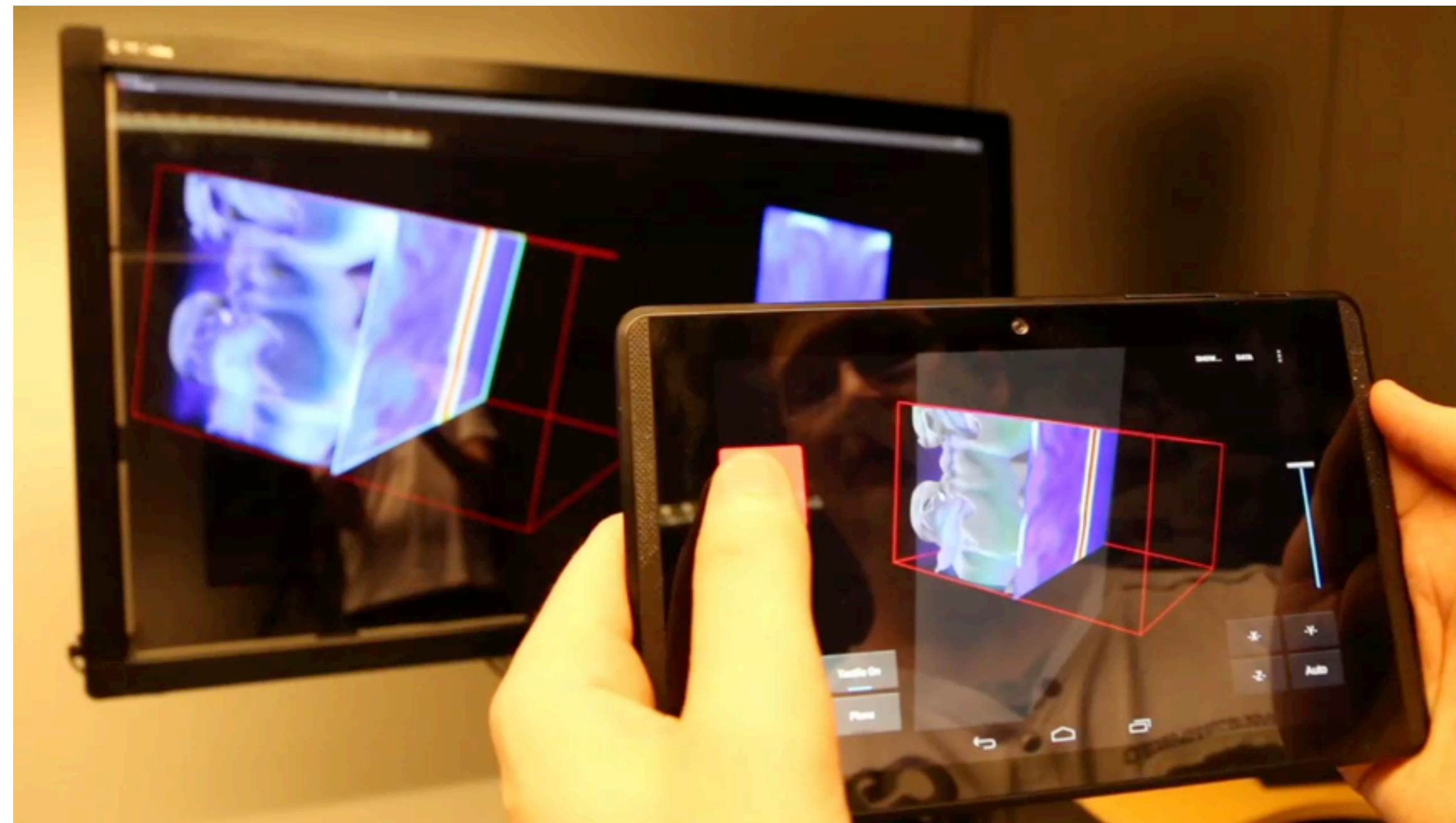
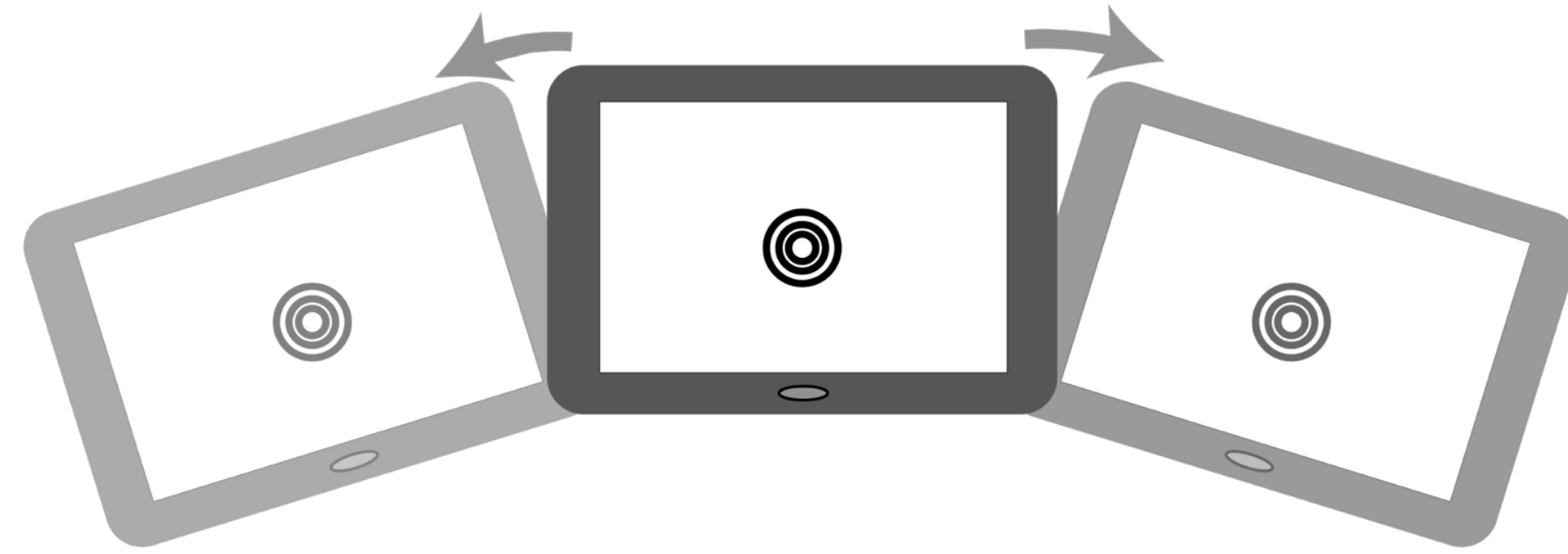


# Hybrid Tactile/Tangible manipulations



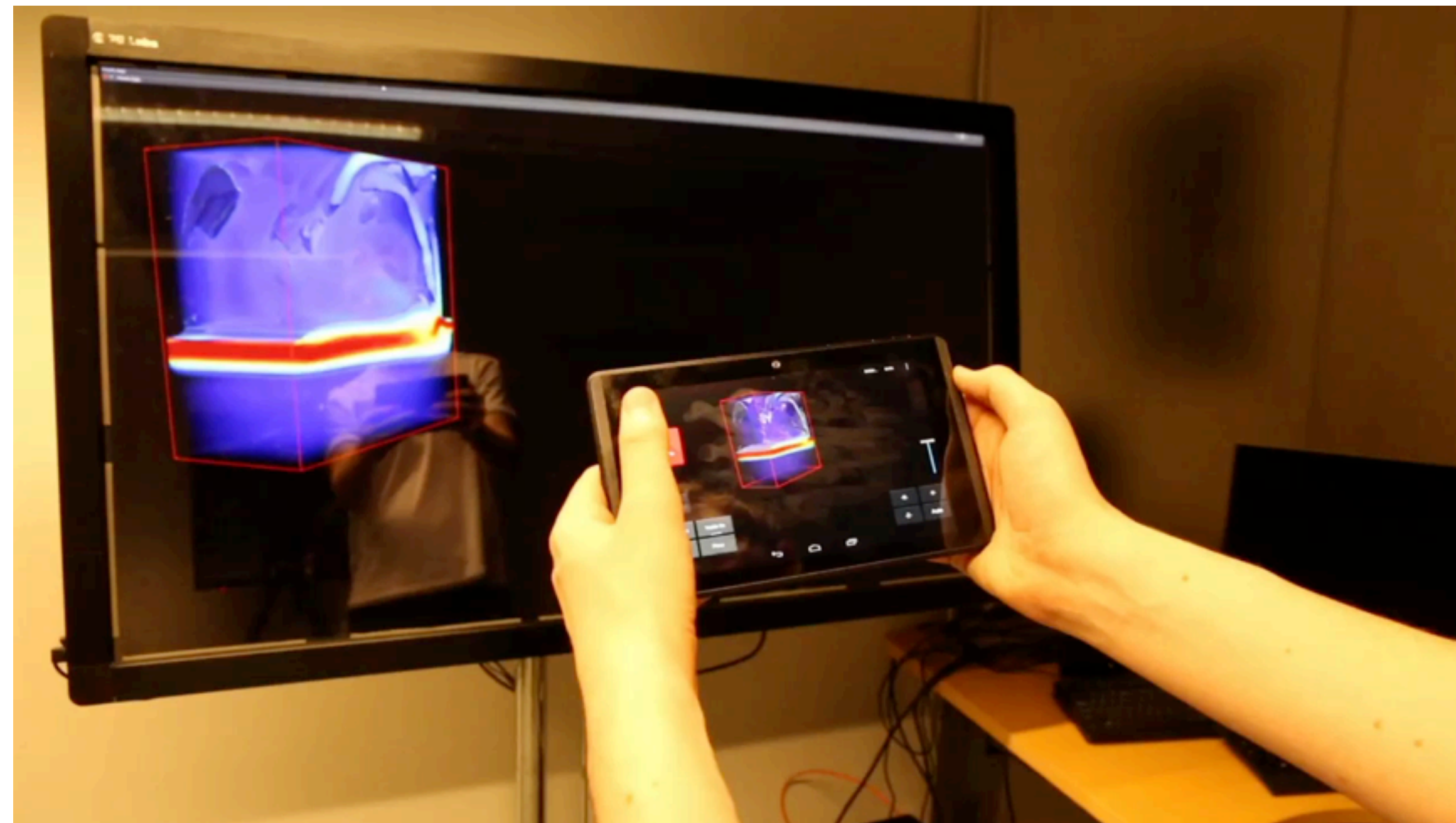
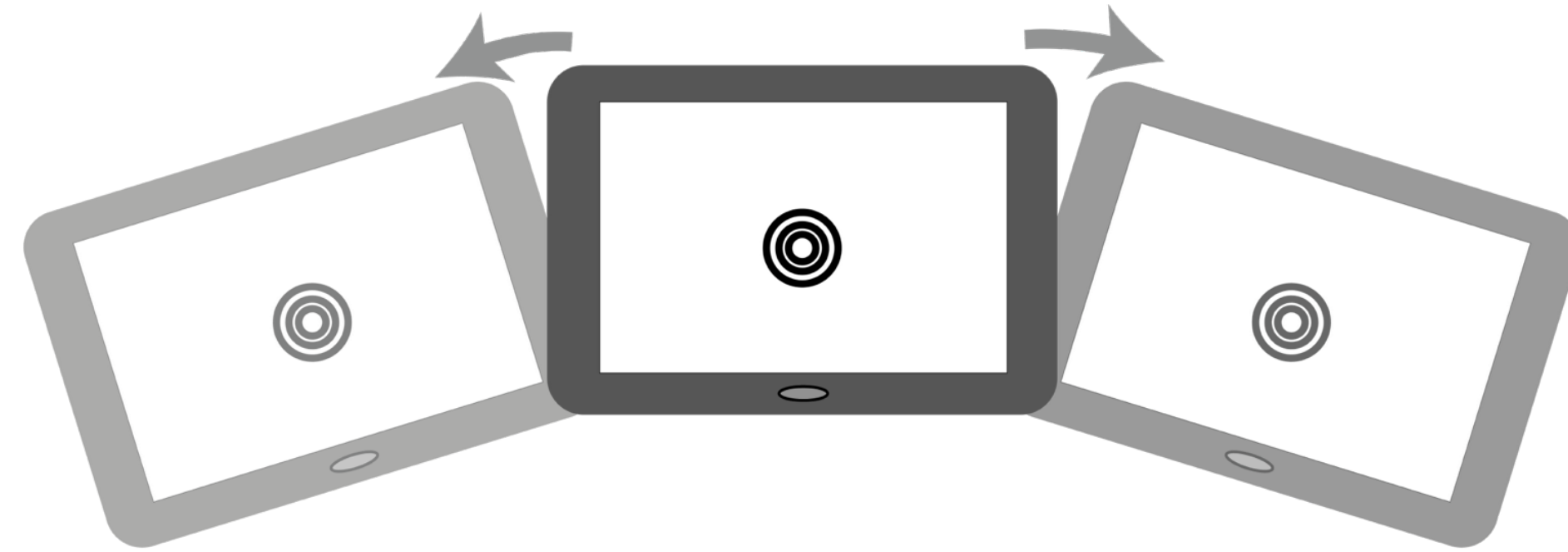


# Hybrid Tactile/Tangible manipulations

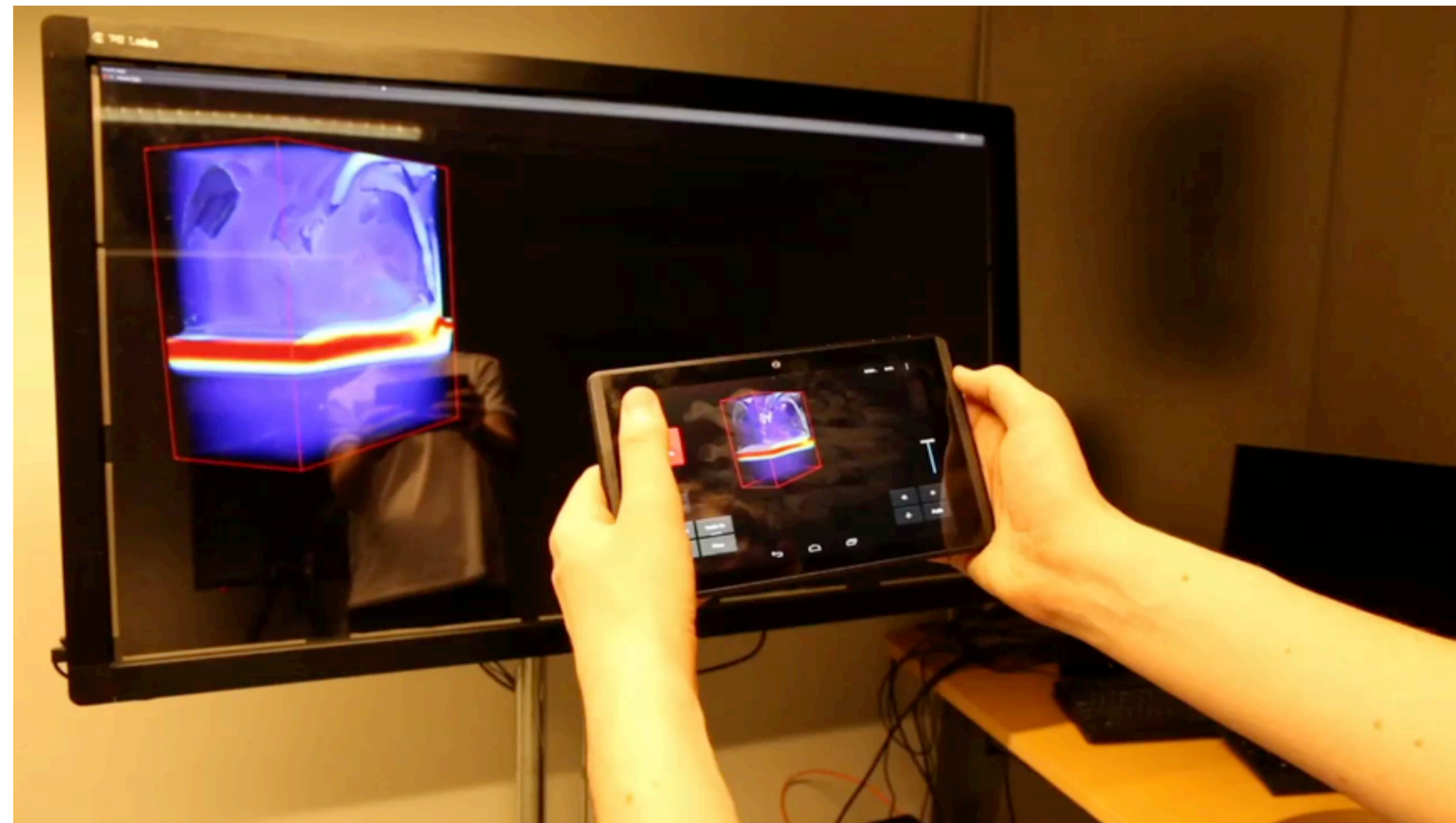
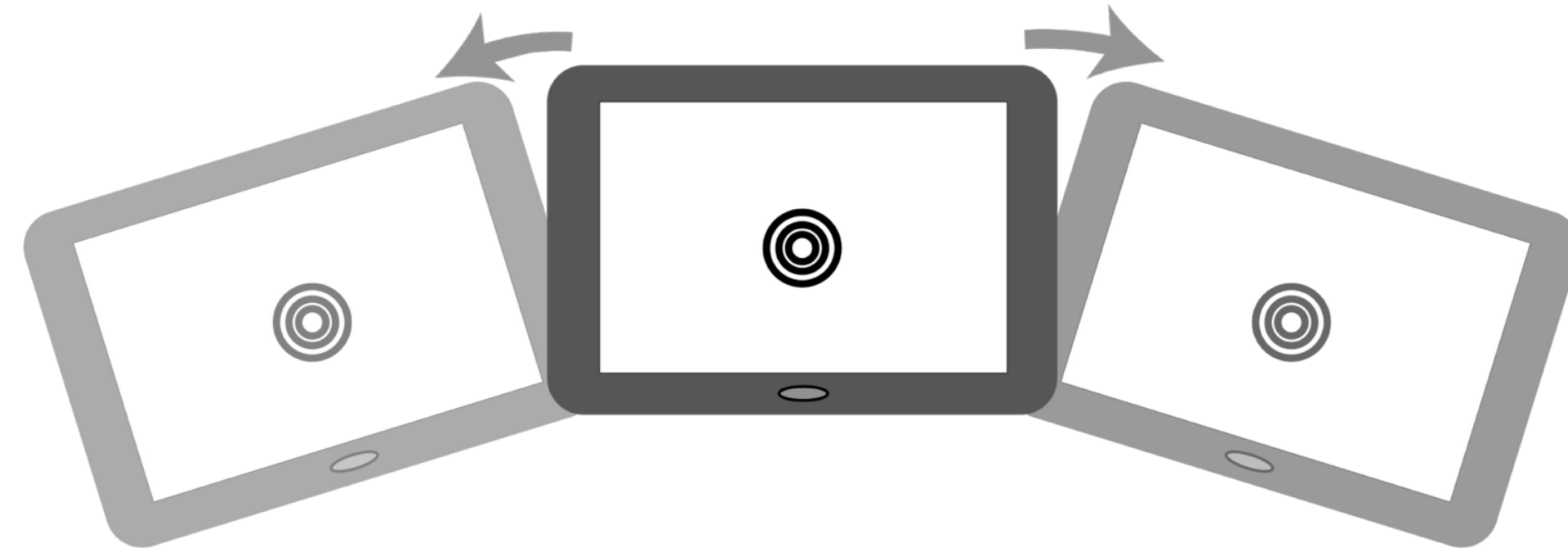




# Gain-factor manipulations

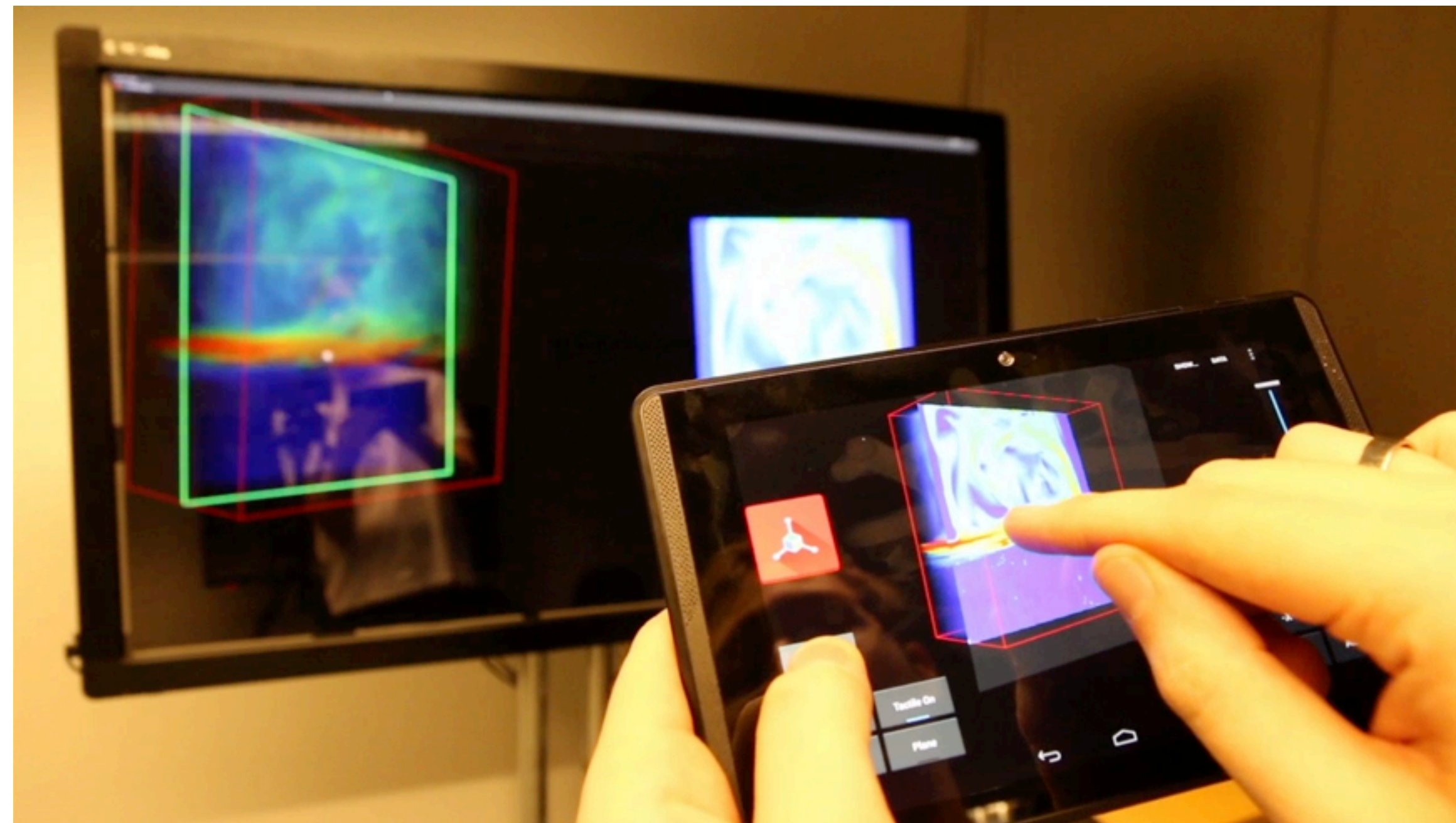
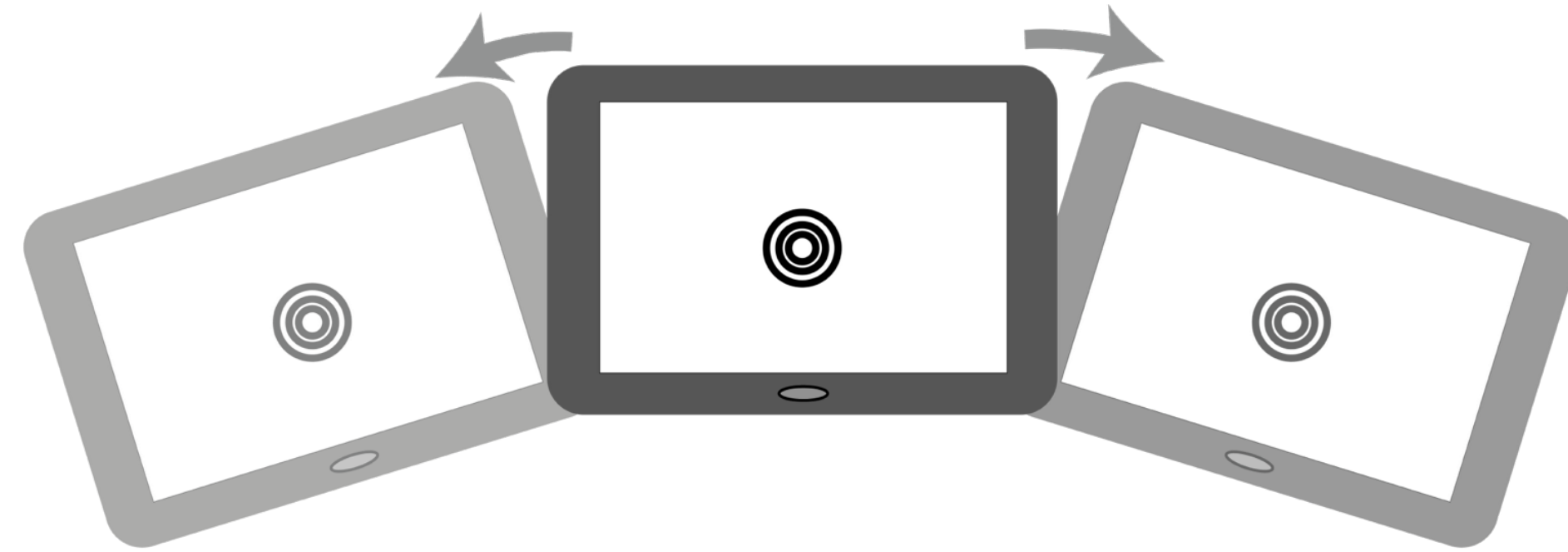


# Gain-factor manipulations



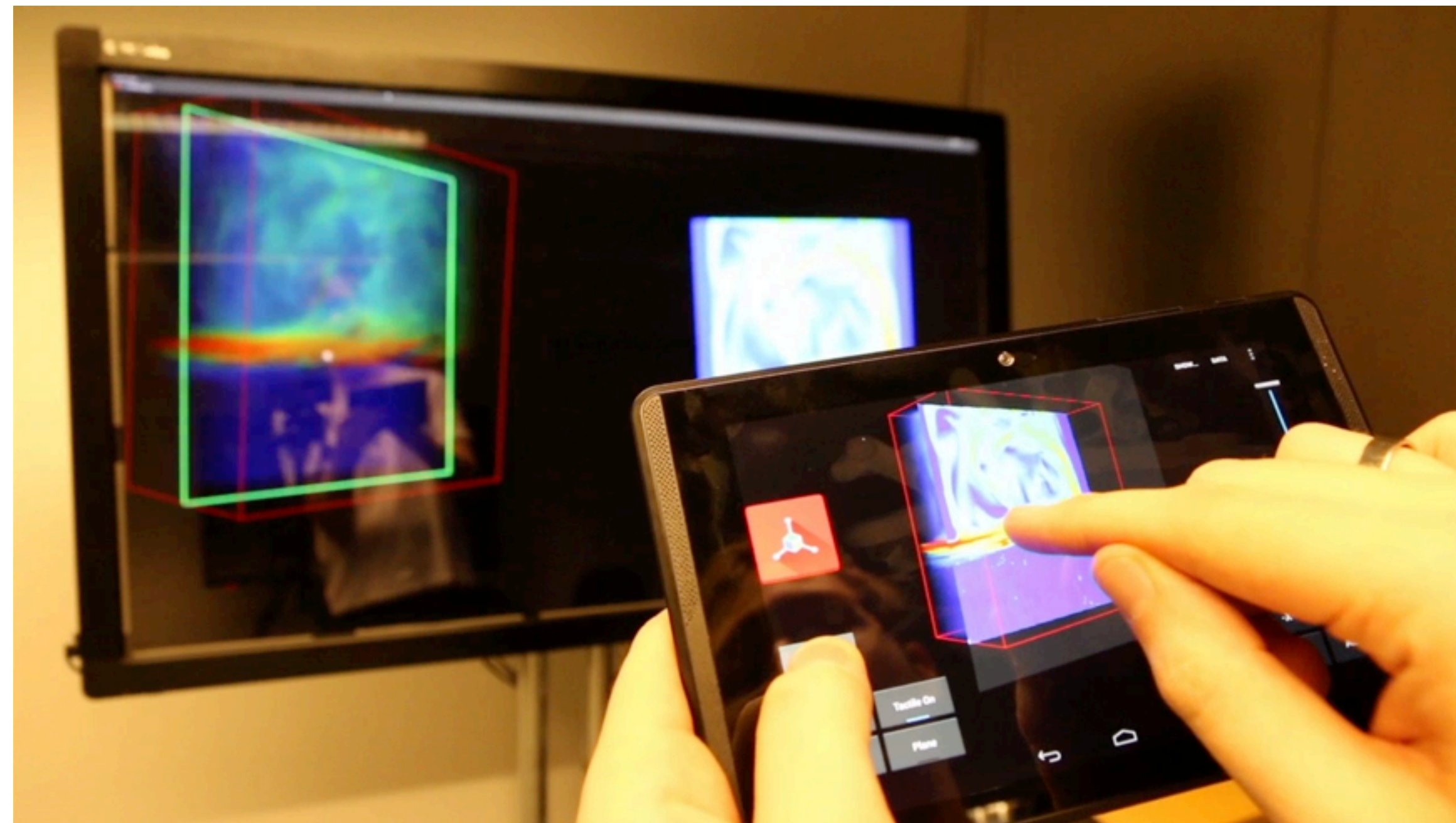
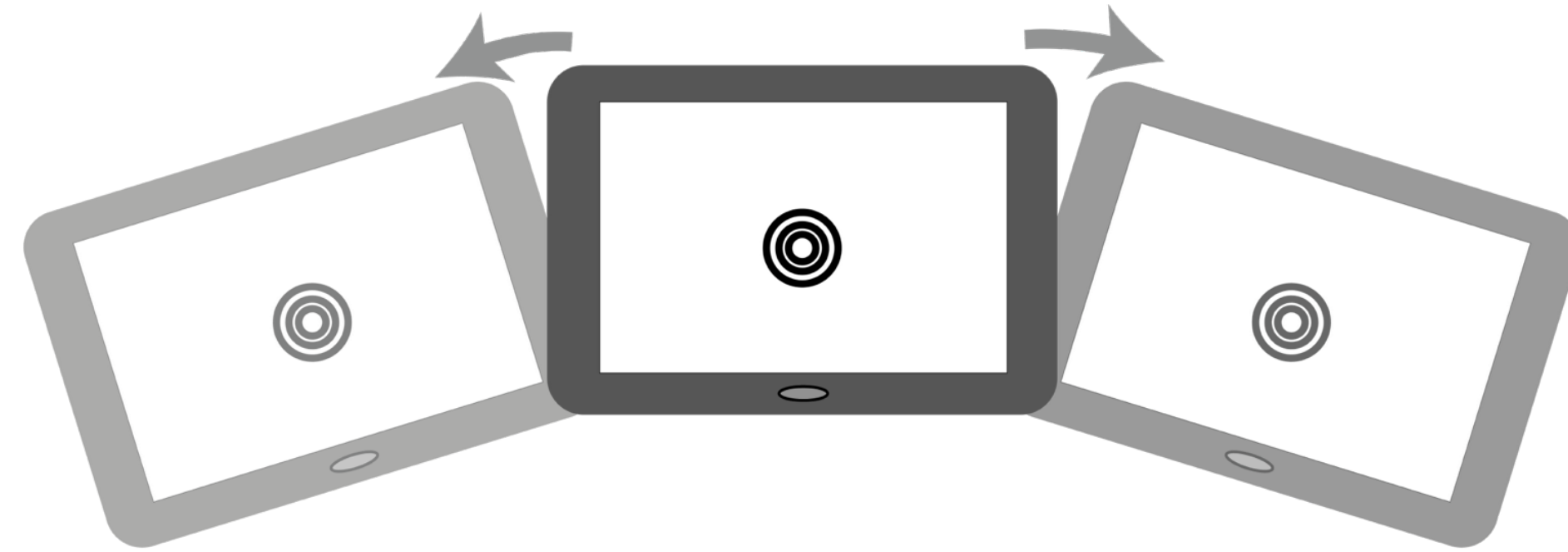


# Seeding point Placement



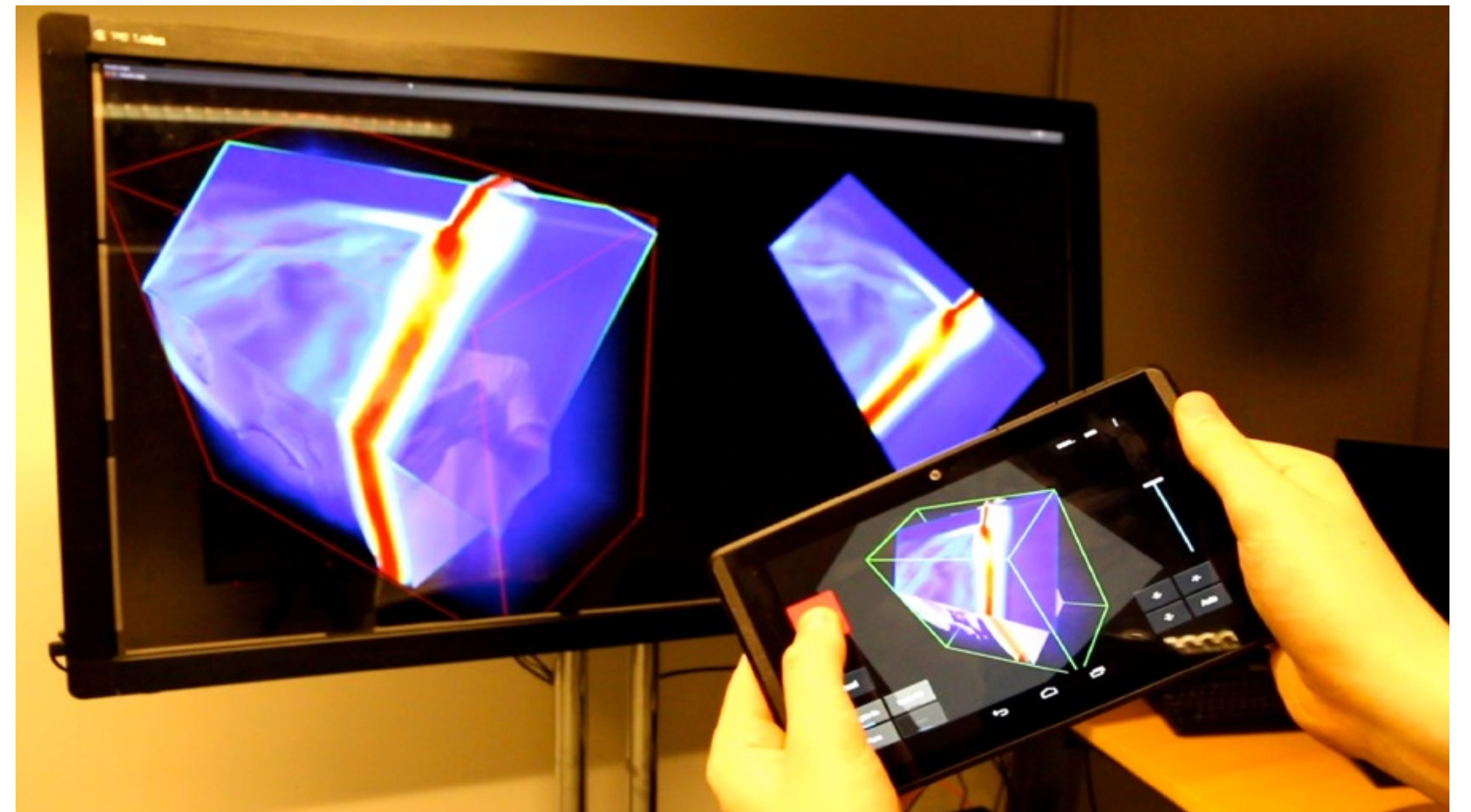


# Seeding point Placement

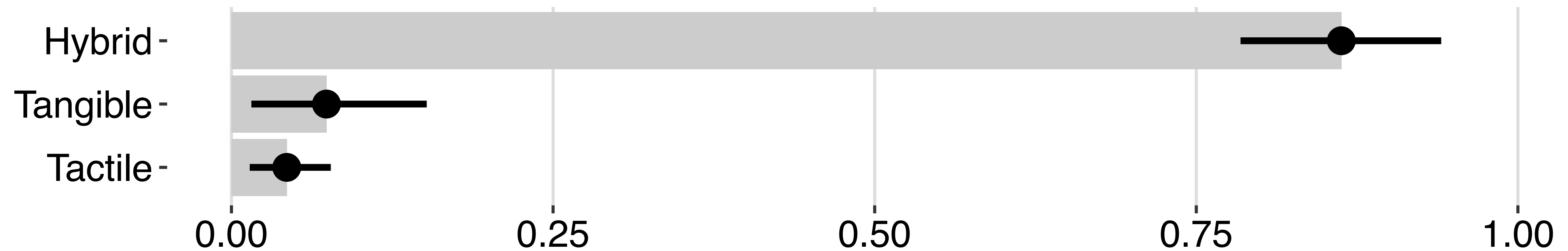


# Hybrid Interaction Study

- 7 fluid dynamic researchers (mean 12.8 years of experience)
- Free exploration task with a FTLE dataset
- Questionnaires



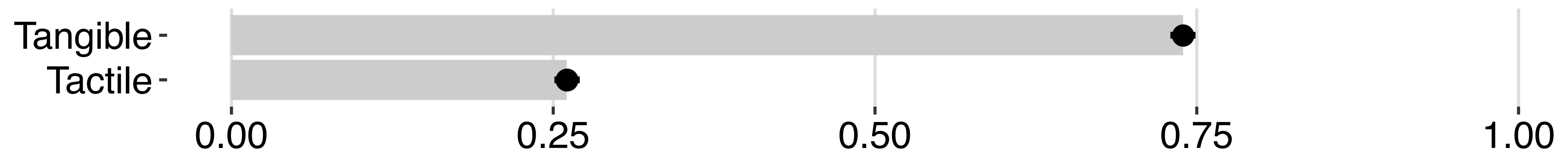
# Quantitative Results



ratio of time spent interacting in the different conditions, error bars 95% CI

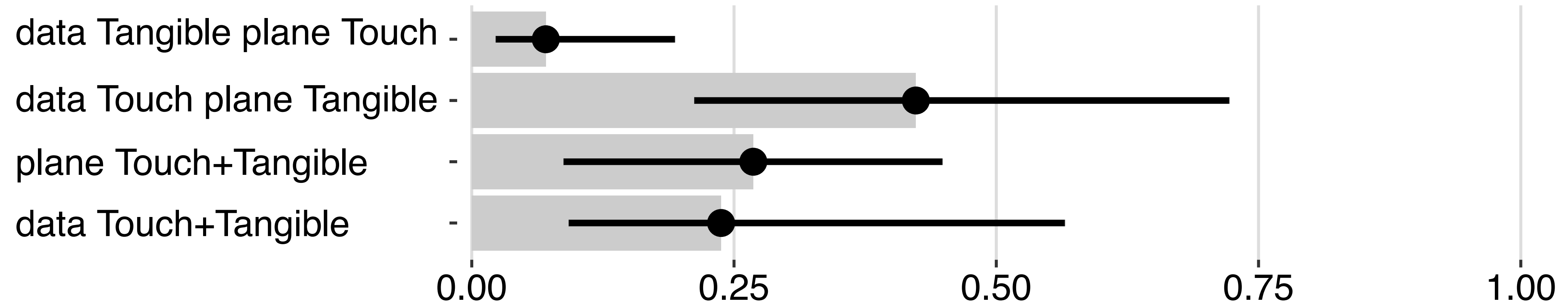


# Quantitative Results



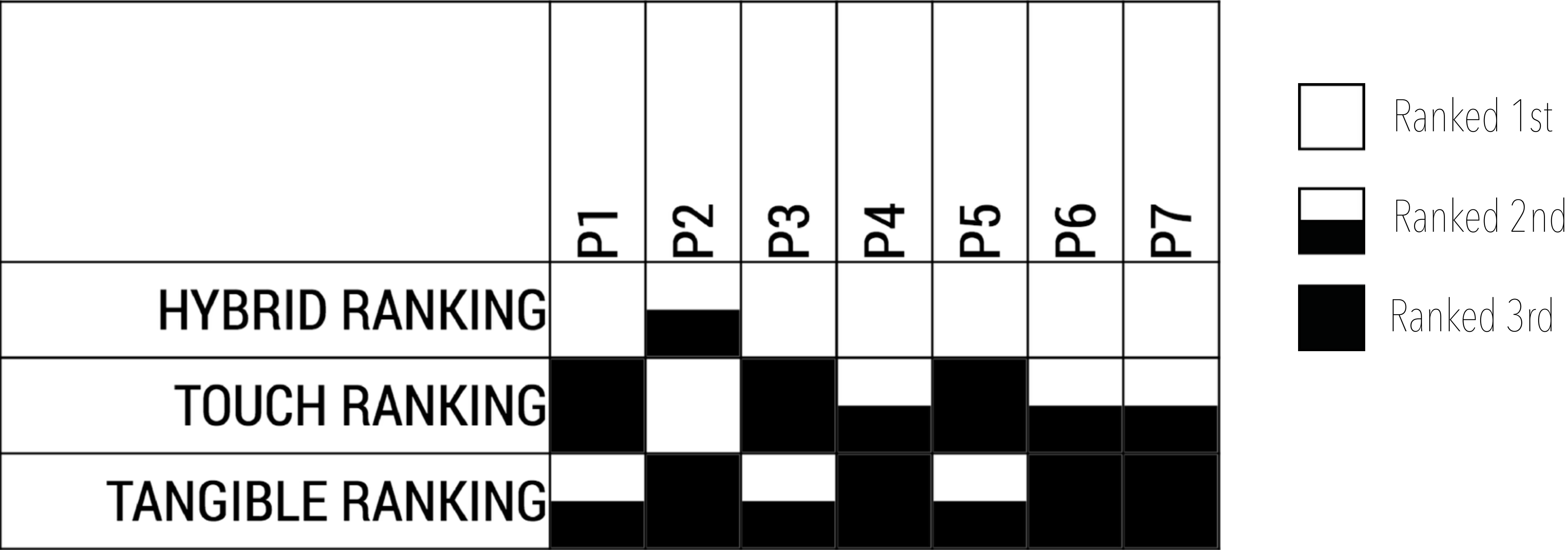
ratio of time spent using the tactile and tangible conditions in hybrid, error bars 95% CI

# Quantitative Results



ratio of time spent interacting with the different plane/data associations in Hybrid Interaction, error bars 95% CI

# Qualitative Results: Preferences





# Qualitative Results

- "The system is a reproduction of what I can do with a PC but with better interaction techniques"
- "Seed point placement is more engaging and flexible"
- "I could achieve rotations or translation difficult to perform with a mouse-only approach"
- "Could be used as an extra visualization tool for primary analysis before getting back to a PC for more in depth analysis that requires scripts"

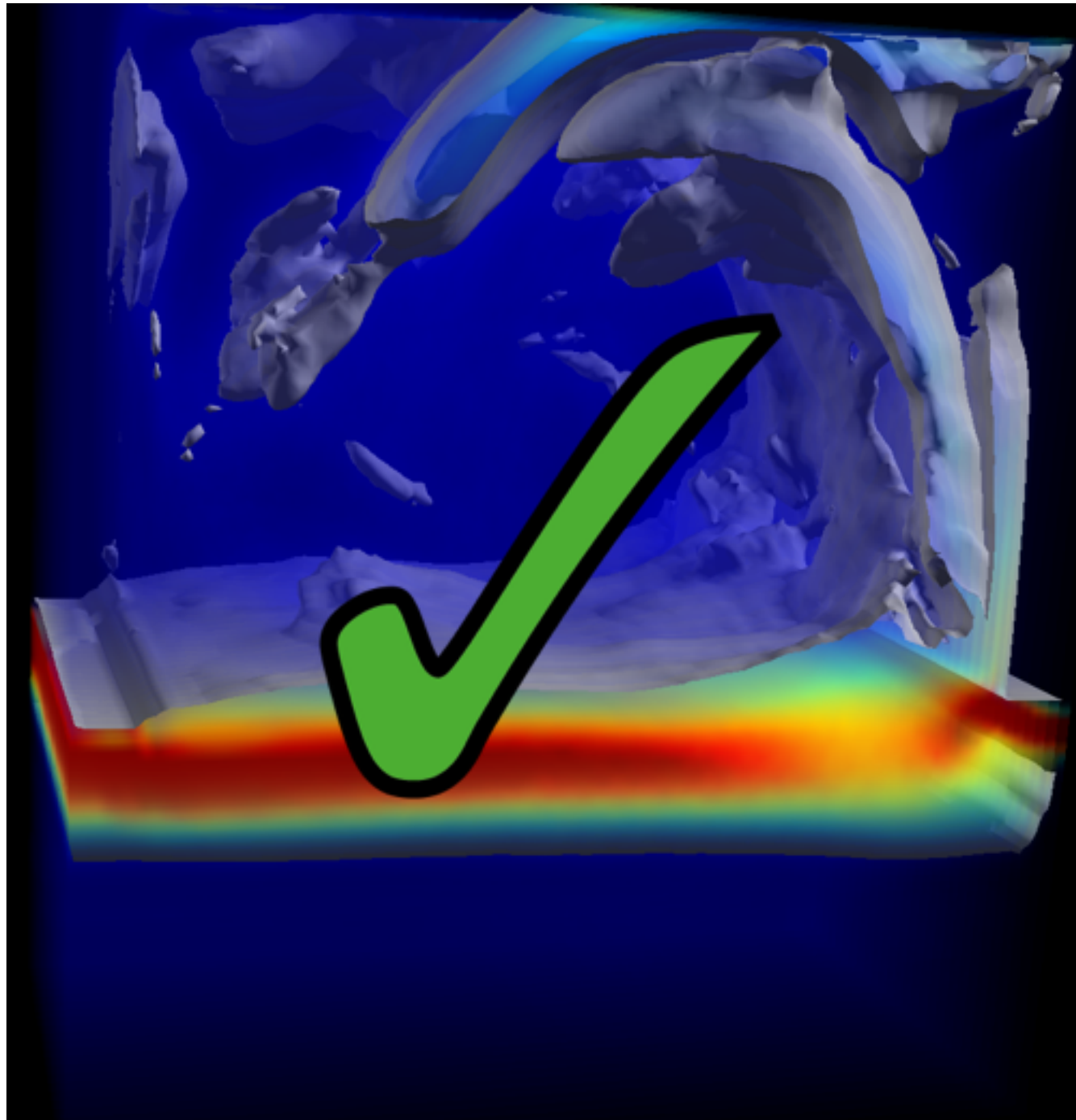
# Qualitative Results

- Only 1 participant did not consider the tool as being fit for practical work yet
- 5 participants would gladly use it if synchronises with their desktop stations

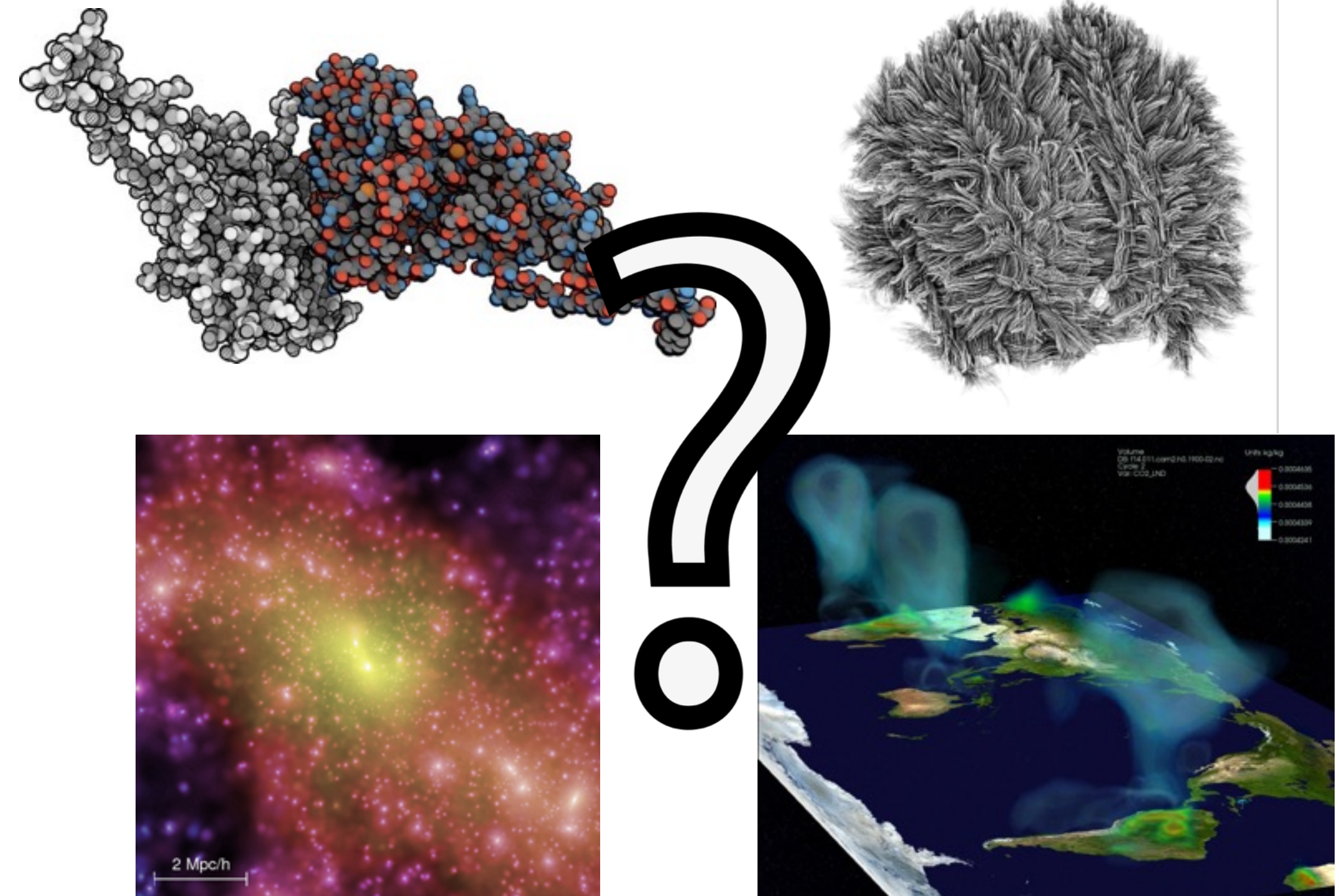
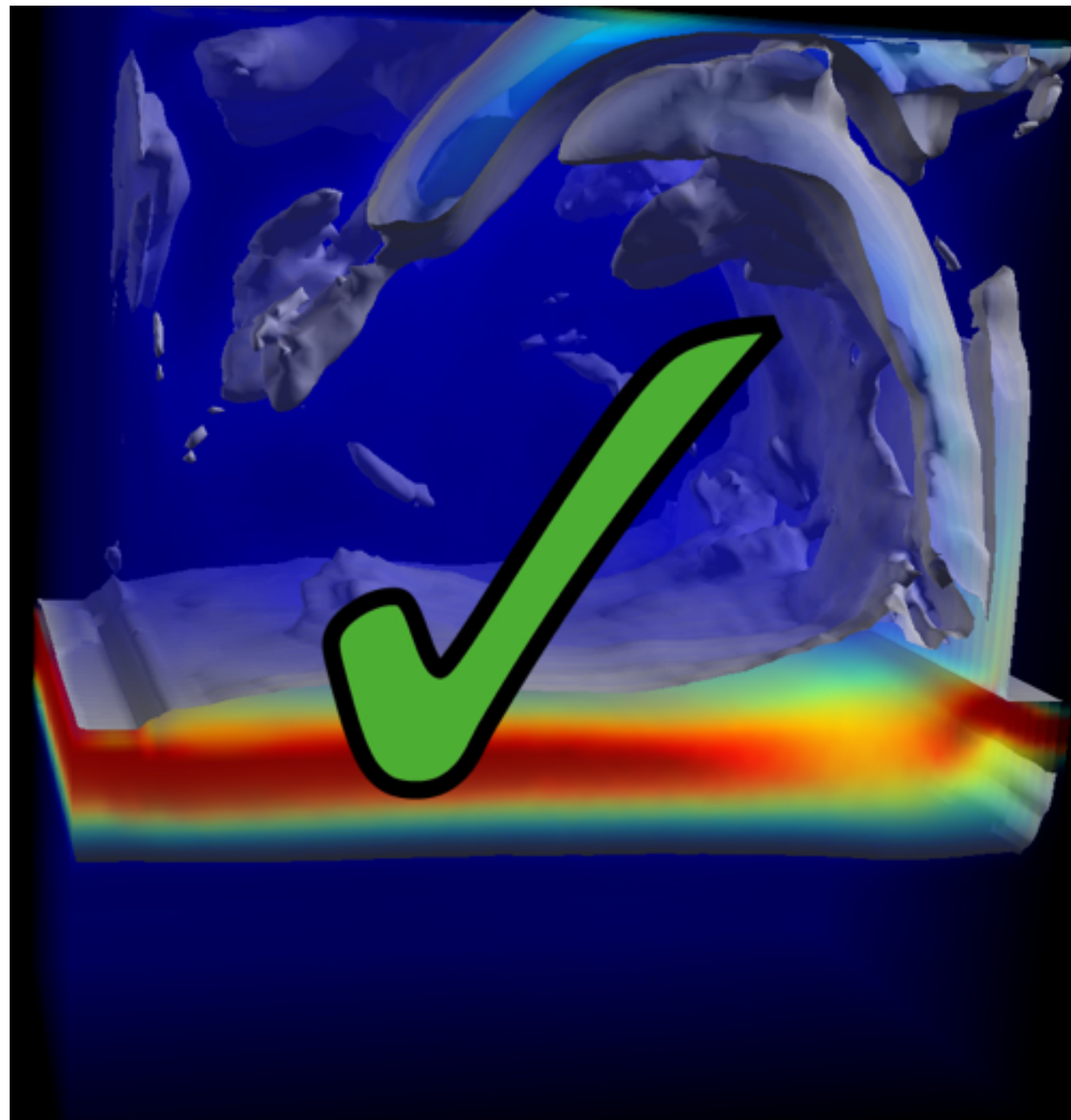
# Limitations



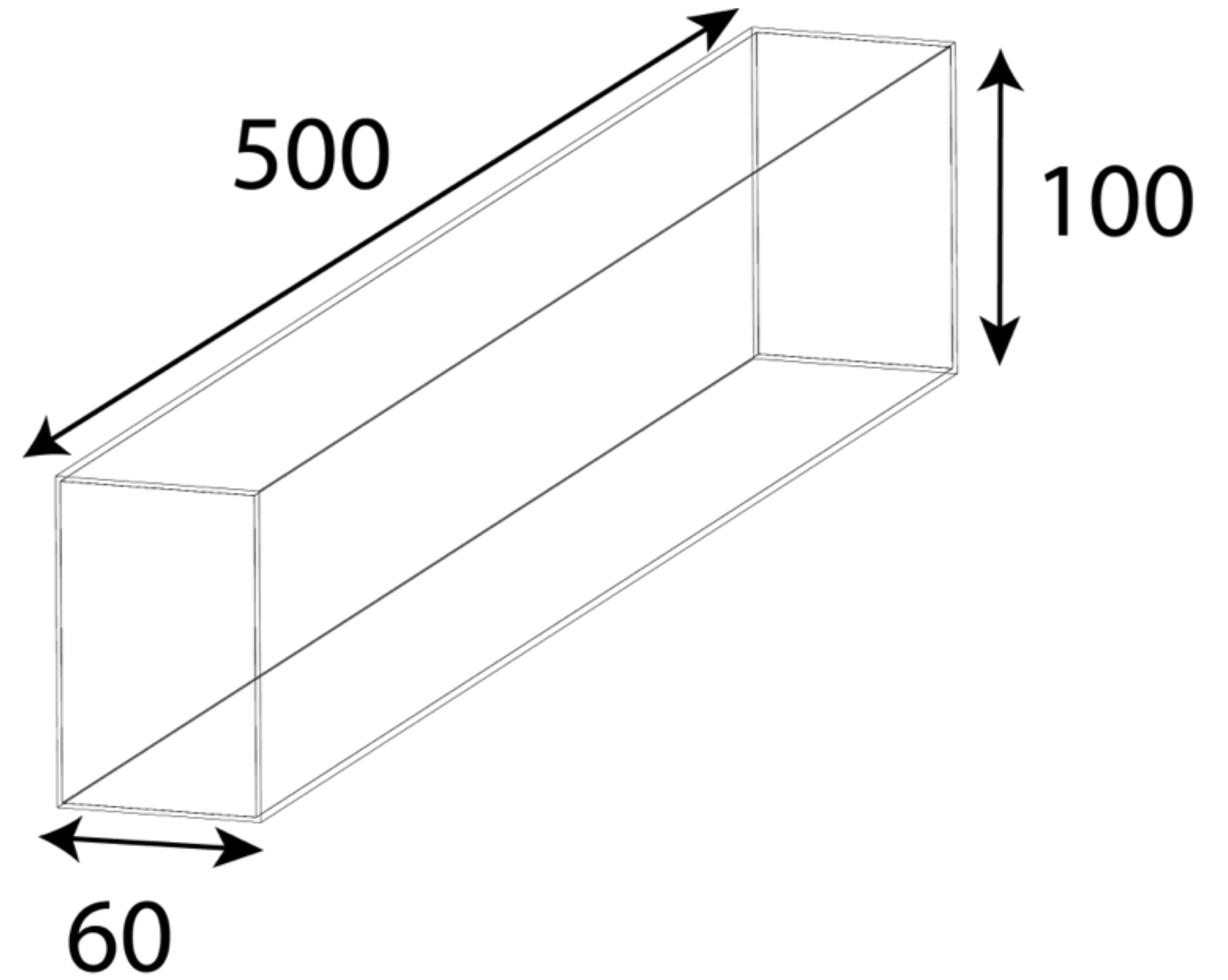
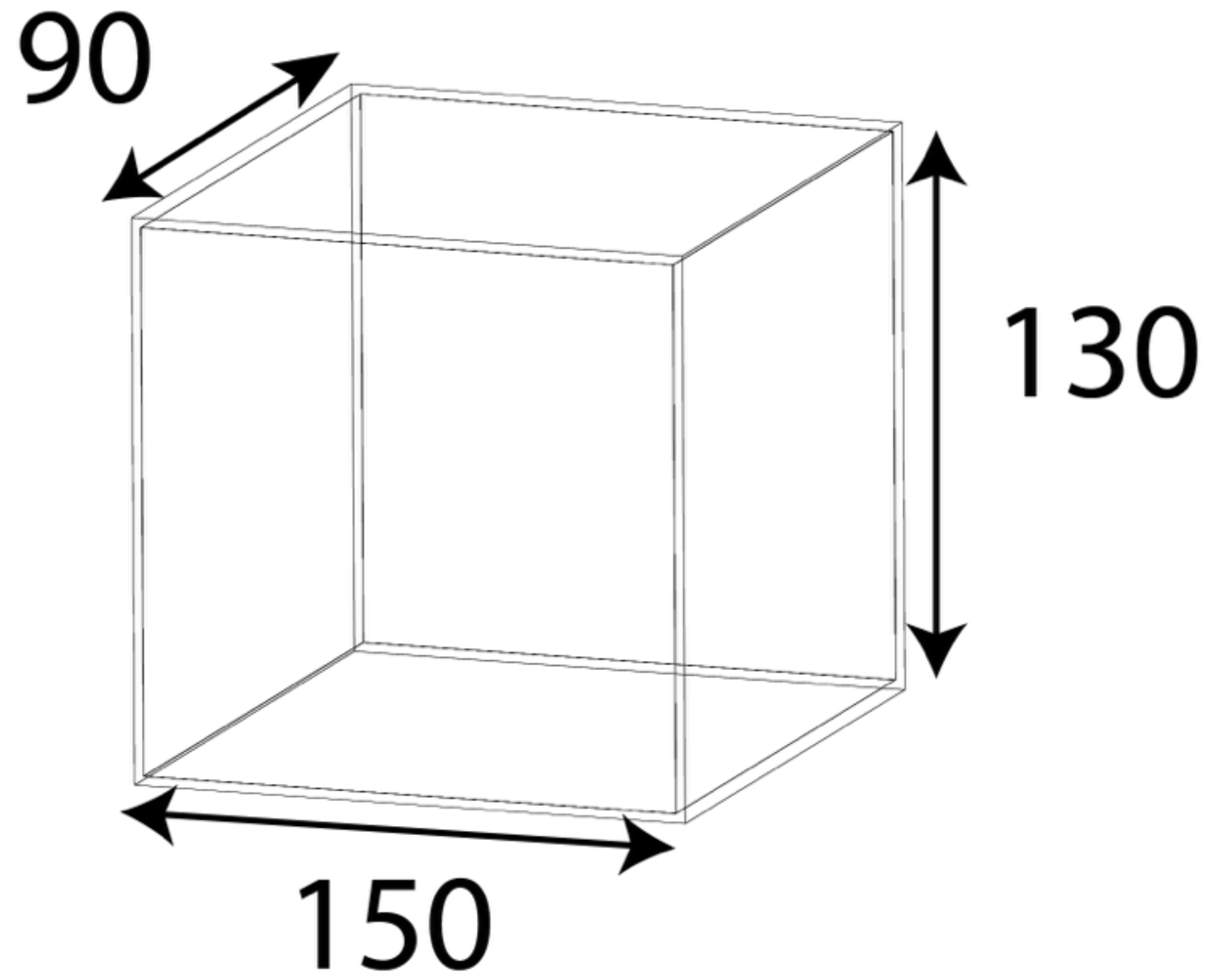
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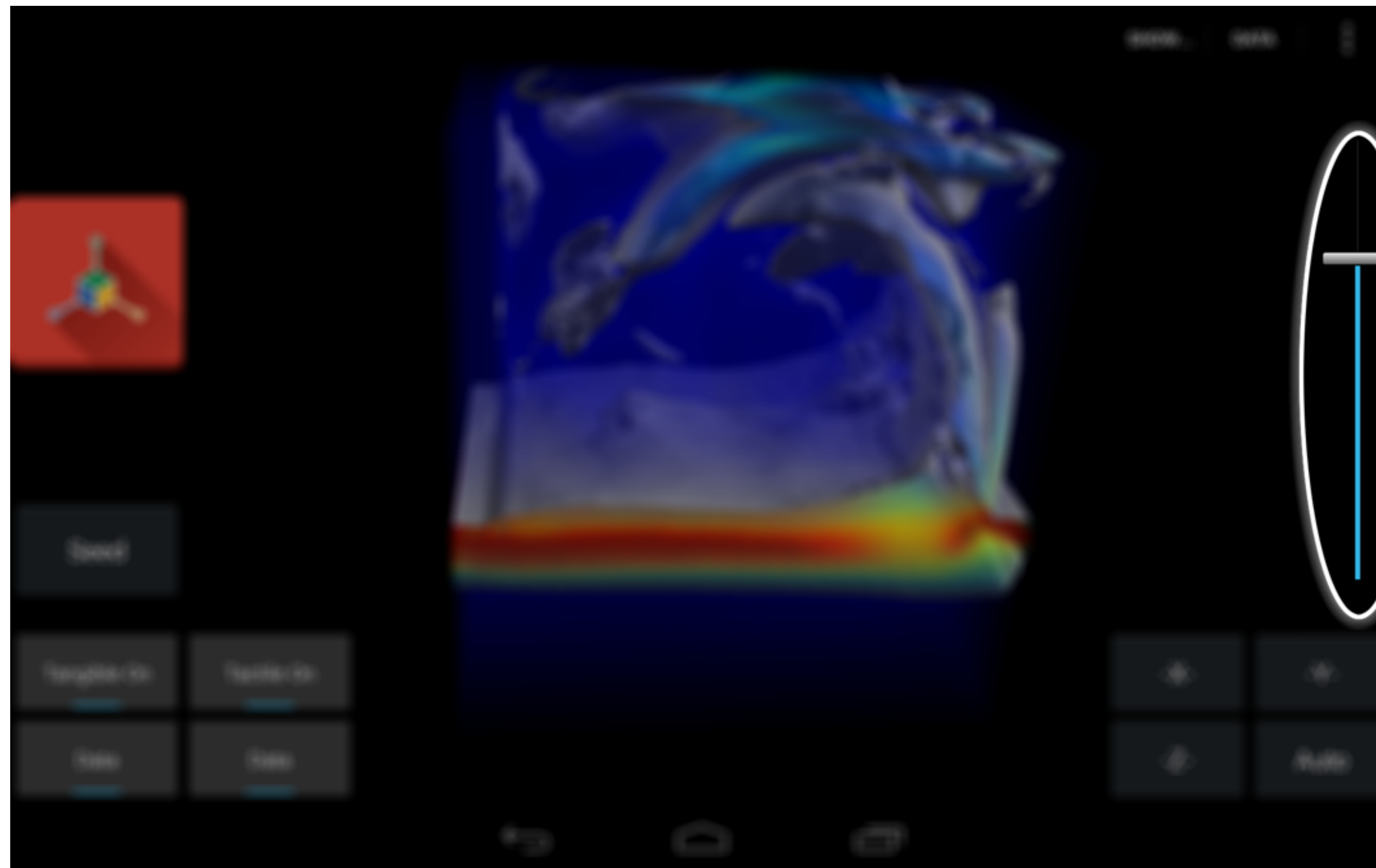


# Limitations





# Limitations



# Conclusion

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- Hybrid interaction possible with off-the-shelves hardware



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- Complex tasks easily achieved with a hybrid tactile/tangible input
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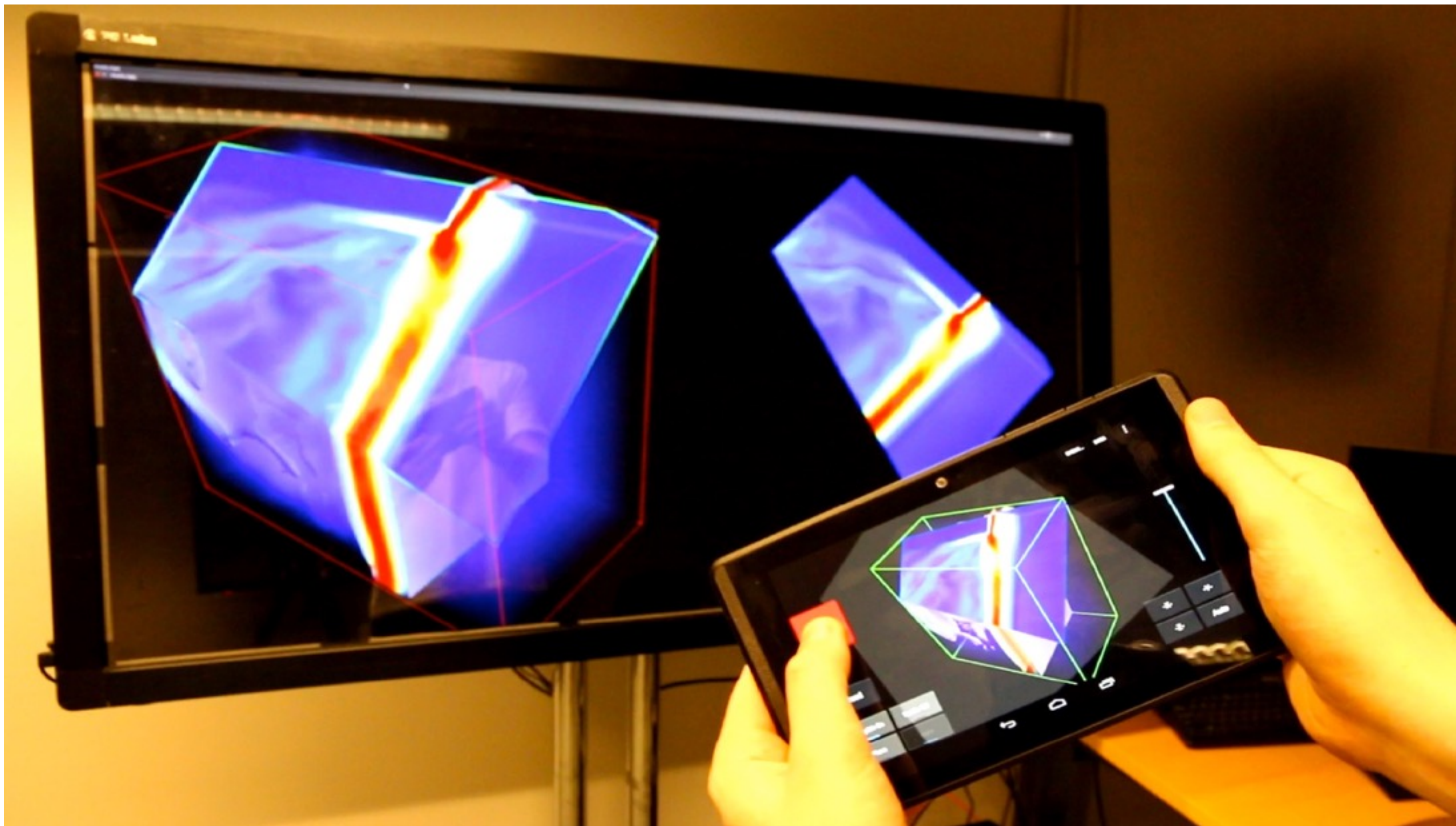
# Conclusion

- Hybrid interaction possible with off-the-shelves hardware
- Complex tasks easily achieved with a hybrid tactile/tangible input
- Hybrid seed point placement is more flexible
- Hybrid interaction is largely preferred



# Hybrid Tactile/Tangible Interaction for 3D Data Exploration

Lonni Besançon, Paul Issartel, Mehdi Ammi, Tobias Isenberg



<http://tiny.cc/hybridinteraction>